HARRIS
HI-574A, HI-674A HI-774
Complete 12-Bit A/D Converter with Microprocessor Interface

## Features

- Complete 12-Bit A/D Converter with Reference and Clock
- Full 8-, 12- or 16-Bit Microprocessor Bus Interface
- 150ns Bus Access Time
- No Missing Codes Over Temperature
- Minimal Setup Time for Control Signals
- Fast Conversion Times
- $25 \mu \mathrm{~s}$ Max (HI-574A)
- 15 $\mu \mathrm{s}$ Max (HI-674A)
- $9 \mu \mathrm{~s}$ Max (HI-774)
- Digital Error Correction (HI-774)
- Low Noise, via Current-Mode Signal Transmission Between Chips
- Byte Enable/Short Cycle ( $\mathrm{A}_{\mathrm{O}}$ Input)
- Guaranteed Break-Before-Make Action, Eliminating Bus Contention During Read Operation. Latched by Start Convert Input (To Set the Conversion Length)
- $\pm 12 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$ Operation


## Applications

- Military and Industrial Data Acquisition Systems
- Electronic Test and Scientific Instrumentation
- Process Control Systems


## Description

The $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A})$ is a complete 12-bit Analog-to-Digital Converter, including a +10 V reference clock, tri-state outputs and a digital interface for microprocessor control. Successive approximation conversion is performed by two monolithic dice housed in a 28 lead package. The bipolar analog die features the Harris Dielectric Isolation process, which provides enhanced AC performance and freedom from latch-up.

Custom design of each IC (bipolar analog and CMOS digital) has yielded improved performance over existing versions of this converter. The voltage comparator features high PSRR plus a high speed current-mode latch, and provides precise decisions down to 0.1 LSB of input overdrive. More than 2X reduction in noise has been achieved by using current instead of voltage for transmission of all signals between the analog and digital IC's. Also, the clock oscillator is current controlled for excellent stability over temperature.
The HI-X74(A) offers standard unipolar and bipolar input ranges, laser trimmed for specified linearity, gain and offset accuracy. The low noise buried zener reference circuit is trimmed for minimum temperature coefficient.
Power requirements are +5 V and $\pm 12 \mathrm{~V}$ to $\pm 15 \mathrm{~V}$, with typical dissipation of 385 mW (HI-574A/674A) and 390mW (HI-774) at 12 V . All models are available in sidebrazed DIP, PDIP, and LCC. For additional HI-Rel screening including 160 hour burnin, specify "-8" suffix. For MIL-STD-883 compliant parts, request $\mathrm{HI}-574 \mathrm{~A} / 883, \mathrm{HI}-674 \mathrm{~A} / 883$, and $\mathrm{HI}-774 / 883$ data

## Pinouts



## Ordering Information

| PART NUMBER | INL | TEMPERATURE RANGE | PACKAGE |
| :---: | :---: | :---: | :---: |
| HI3-574AJN-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI3-574AKN-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI3-574ALN-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI1-574AJD-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574AKD-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574ALD-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574ASD-2 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574ATD-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574AUD-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574ASD/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574ATD/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-574AUD/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI4-574ASE/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-574ATE/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-574AUE/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI3-674AJN-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI3-674AKN-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI3-674ALN-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI1-674AJD-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674AKD-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674ALD-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674ASD-2 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674ATD-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674AUD-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674ASD/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674ATD/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-674AUD/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI4-674ASE/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-674ATE/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-674AUE/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI3-774J-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| HI3-774K-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Plastic DIP |
| H11-774J-5 | $\pm 1.0$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774K-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774L-5 | $\pm 0.5$ LSB | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774S-2 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774T-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774U-2 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774S/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774T/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI1-774U/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 28 Lead Ceramic DIP |
| HI4-774S/883 | $\pm 1.0$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-774T/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |
| HI4-774U/883 | $\pm 0.5$ LSB | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 44 Lead Ceramic LCC |

Functional Block Diagram


* "Nibble" is a 4 bit digital word


## Absolute Maximum Ratings

| Supply Voltage |  |
| :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ to Digital Common | OV to +16.5 V |
| $\mathrm{V}_{\text {EE }}$ to Digital Common | OV to -16.5V |
| $V_{\text {LOGIC }}$ to Digital Common | V to +7 V |
| Analog Common to Digital Common | $\pm 1 \mathrm{~V}$ |
| Control Inputs <br> (CE, $\overline{C S}, A_{0}, 12 / \overline{8}, R / \bar{C}$ ) to Digital Common . | $.-0.5 \mathrm{~V} \text { to } \mathrm{V}_{\text {LOGIC }}+0.5 \mathrm{~V}$ |
| Analog Inputs |  |
| (REFIN, BIPOFF, 10VIN) to | $\pm 16.5 \mathrm{~V}$ |
| 20 VIN to Analog Common | $\pm 24 \mathrm{~V}$ |
| REFOUT . . . . . . Indefinite short to Common, momentary short to $\mathrm{V}_{\mathrm{CC}}$ |  |
| Operating Temperature Range |  |
| HI3-574AxN-5, HI1-574AxD-5 | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |
| HI3-674AxN-5, HI1-674AxD-5 | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |
| HI3-774xN-5, HI1-774xD-5. | $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |
| HI1-574AxD-2, HI1-674AxD-2, HI1-774xD-2 | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Storage Temperature Range |  |
| HI3-574AxN-5 | $40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ |
| HI3-674AxN-5 | $40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ |
| HI3-774xN-5 | $.-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ |
| HI1-574AxD-2, HI1-574AxD-5 | $-65^{\circ} \mathrm{C}<\mathrm{T}_{A}<+150^{\circ} \mathrm{C}$ |
| HI1-674AxD-2, HI1-674AxD-5 | $-65^{\circ} \mathrm{C}<\mathrm{T}_{A}<+150^{\circ} \mathrm{C}$ |
| HI1-774xD-2, HI1-774xD-5. | $-65^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+150^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering, 10s) | $300^{\circ} \mathrm{C}$ |

## Thermal Information

| Thermal Resistance | $\theta_{\text {JA }}$ |
| :---: | :---: |
| HI3-574AxN-5 | $65^{\circ} \mathrm{C} / \mathrm{W}$ |
| HI3-674AxN-5 | $65^{\circ} \mathrm{C} / \mathrm{W}$ |
| HI3-774xN-5 | $65^{\circ} \mathrm{C} / \mathrm{W}$ |
| Power Dissipation at $+75^{\circ} \mathrm{C}$ (Note 1) |  |
| HI3-574AxN-5 | 1000 mW |
| HI3-674AxN-5 | 1000 mW |
| HI3-774xN-5 | 1000 mW |
| HI1-574AxD-x | 2080mW |
| HI1-674AxD-2, HI1-674AxD-5 | 2083mW |
| HI1-774xD-2, HI1-774xD-5 | 2083mW |
| HI4-574AxE-x | 2270mW |
| Transistor Count |  |
| HI-574A, HI-674A | 1117 |
| HI-774 | 2117 |
| Junction Temperature |  |
| HI3-574AxN-5, HI3-674AxN-5, HI3-774xN-5. | . $+150^{\circ} \mathrm{C}$ |
| HI1-574AxD-2, HI1-574AxD-5. | . $+175^{\circ} \mathrm{C}$ |
| HI1-674AxD-2, HI1-674AxD-5. | . $+175^{\circ} \mathrm{C}$ |
| HI1-774xD-2, HI1-774xD-5 | + $175^{\circ} \mathrm{C}$ |

DC and Transfer Accuracy Specifications Typical at $+25^{\circ} \mathrm{C}$ with $\mathrm{V}_{\mathrm{CC}}=+15 \mathrm{~V}$ or +12 V , $\mathrm{V}_{\text {LOGIC }}=+5 \mathrm{~V}, \mathrm{~V}_{\mathrm{EE}}=-15 \mathrm{~V}$ or -12 V , Unless Otherwise Specified

| PARAMETERS | TEMPERATURE RANGE $-5\left(0^{\circ} \mathrm{C}\right.$ to $\left.+75^{\circ} \mathrm{C}\right)$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | J SUFFIX | K SUFFIX | L SUFFIX |  |
| DYNAMIC CHARACTERISTICS |  |  |  |  |
| Resolution (Max) | 12 | 12 | 12 | Bits |
| Linearity Error $+25^{\circ} \mathrm{C} \text { (Max) }$ | $\pm 1$ | $\pm 1 / 2$ | $\pm 1 / 2$ | LSB |
| $0^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ (Max) | $\pm 1$ | $\pm 1 / 2$ | $\pm 1 / 2$ | LSB |
| Max resolution for which no missing codes is guaranteed $+25^{\circ} \mathrm{C}$ <br> HI-574A, HI-674A | 12 | 12 | 12 | Bits |
| HI-774 | 11 | 12 | 12 | Bits |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }} \quad \mathrm{HI} 574 \mathrm{~A}, \mathrm{HI}-674 \mathrm{~A}$ | 11 | 12 | 12 | Bits |
| HI-774 | 11 | 12 | 12 | Bits |
| Unipolar Offset (Max) <br> Adjustable to Zero | $\pm 2$ | $\pm 1.5$ | $\pm 1$ | LSB |
| Bipolar Offset (Max) $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V} \text { (Adjustable to Zero) }$ | $\pm 4$ | $\pm 4$ | $\pm 3$ | LSB |
| $\mathrm{V}_{\text {IN }}=-10 \mathrm{~V}$ | $\pm 0.15$ | $\pm 0.1$ | $\pm 0.1$ | \% of F.S. |
| Full Scale Calibration Error <br> $+25^{\circ} \mathrm{C}$ (Max), with fixed $50 \Omega$ resistor from REF OUT to REF IN (Adjustable to Zero) | $\pm 0.25$ | $\pm 0.25$ | $\pm 0.15$ | \% of F.S. |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (No adjustment at $+25^{\circ} \mathrm{C}$ ) | $\pm 0.475$ | $\pm 0.375$ | $\pm 0.20$ | \% of F.S. |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (With adjustment to zero $+25^{\circ} \mathrm{C}$ ) | $\pm 0.22$ | $\pm 0.12$ | $\pm 0.05$ | \% of F.S. |

Specifications HI-574A, HI-674A, HI-774

DC and Transfer Accuracy Specifications Typical at $+25^{\circ} \mathrm{C}$ with $\mathrm{V}_{\mathrm{CC}}=+15 \mathrm{~V}$ or $+12 \mathrm{~V}, \mathrm{~V}_{\mathrm{LOGIC}}=+5 \mathrm{~V}, \mathrm{~V}_{\mathrm{EE}}=-15 \mathrm{~V}$ or -12 V , Unless Otherwise Specified (Continued)

| PARAMETERS | TEMPERATURE RANGE $-5\left(0^{\circ} \mathrm{C}\right.$ to $\left.+75^{\circ} \mathrm{C}\right)$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | J SUFFIX | K SUFFIX | L SUFFIX |  |
| Temperature Coefficients Guaranteed Max change, $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (Using internal reference) | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| Hi-774 | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| Bipolar Offset HI-574A, HI-674A | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| HI-774 | $\pm 2$ | $\pm 2$ | $\pm 1$ | LSB |
| Full Scale Calibration HI-574A, HI-674A | $\pm 9$ | $\pm 2$ | $\pm 2$ | LSB |
| HI-774 | $\pm 9$ | $\pm 5$ | $\pm 2$ | LSB |
| Power Supply Rejection Max change in Full Scale Calibration $+13.5 \mathrm{~V}<\mathrm{V}_{\mathrm{CC}}<+16.5 \mathrm{~V} \text { or }+11.4 \mathrm{~V}<\mathrm{V}_{\mathrm{CC}}<+12.6 \mathrm{~V}$ | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| $+4.5 \mathrm{~V}<\mathrm{V}_{\text {LOGIC }}<+5.5 \mathrm{~V}$ | $\pm 1 / 2$ | $\pm 1 / 2$ | $\pm 1 / 2$ | LSB |
| $-16.5 \mathrm{~V}<\mathrm{V}_{\text {EE }}<-13.5 \mathrm{~V}$ or $-12.6 \mathrm{~V}<\mathrm{V}_{\mathrm{EE}}<-11.4 \mathrm{~V}$ | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |

ANALOG INPUTS

| Input Ranges |  |  |
| :---: | :---: | :---: |
| Bipolar | -5 to +5 | V |
|  | -10 to +10 | V |
| Unipolar | 0 to +10 | V |
|  | 0 to +20 | V |
| Input Impedance |  |  |
| 10 V Span | $5 \mathrm{~K}, \pm 25 \%$ | $\Omega$ |
| 20 V Span | 10K, $\pm 25 \%$ | $\Omega$ |
| POWER SUPPLIES |  |  |
| Operating Voltage Range |  |  |
| $V_{\text {LOGIC }}$ | +4.5 to +5.5 | V |
| $\mathrm{V}_{\mathrm{CC}}$ | +11.4 to +16.5 | V |
| $\mathrm{V}_{\mathrm{EE}}$ | -11.4 to -16.5 | V |
| Operating Current |  |  |
| logic | 7 Typ, 15 Max | mA |
| $\mathrm{I}_{\text {CC }}+15 \mathrm{~V}$ Supply | 11 Typ, 15 Max | mA |
| $\mathrm{I}_{\text {EE }}$-15V Supply | 21 Typ, 28 Max | mA |
| Power Dissipation $\pm 15 \mathrm{~V},+15 \mathrm{~V}$ | 515 Typ, 720 Max | mW |
| $\pm 12 \mathrm{~V},+5 \mathrm{~V}$ | 385 Typ | mW |
| Internal Reference Voltage |  |  |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ | $+10.00 \pm 0.05 \mathrm{Max}$ | V |
| Output current, available for external loads (External load should not change during conversion). | 2.0 Max | mA |

Specifications HI-574A, HI-674A, HI-774

DC and Transfer Accuracy Specifications Typical at $+25^{\circ} \mathrm{C}$ with $\mathrm{V}_{\mathrm{CC}}=+15 \mathrm{~V}$ or $+12 \mathrm{~V}, \mathrm{~V}_{\mathrm{LOGIC}}=+5 \mathrm{~V}, \mathrm{~V}_{\mathrm{EE}}=-15 \mathrm{~V}$ or -12 V , Unless Otherwise Specified

| PARAMETERS | TEMPERATURE RANGE$-2\left(-55^{\circ} \mathrm{C} \text { to }+125^{\circ} \mathrm{C}\right)$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | S SUFFIX | T SUFFIX | U SUFFIX |  |
| DYNAMIC CHARACTERISTICS |  |  |  |  |
| Resolution (Max) | 12 | 12 | 12 | Bits |
| Linearity Error $+25^{\circ} \mathrm{C}$ | $\pm 1$ | $\pm 1 / 2$ | $\pm 1 / 2$ | LSB |
| $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ (Max) | $\pm 1$ | $\pm 1$ | $\pm 1$ | LSB |
| Max resolution for which no missing codes is guaranteed $+25^{\circ} \mathrm{C}$ <br> HI-574A, HI-674A | 12 | 12 | 12 | Bits |
| HI-774 | 11 | 12 | 12 | Bits |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }} \quad \frac{\mathrm{HI}-574 \mathrm{~A}, \mathrm{HI}-674 \mathrm{~A}}{}$ | 11 | 12 | 12 | Bits |
|  | 11 | 12 | 12 | Bits |
| Unipolar Offset (Max) <br> Adjustable to Zero  <br>  HI-574A, HI-674A <br>   | $\pm 2$ | $\pm 1.5$ | $\pm 1$ | LSB |
|  | $\pm 2$ | $\pm 2$ | $\pm 1$ | LSB |
| Bipolar Offset (Max) $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V} \text { (Adjustable to Zero) }$ | $\pm 4$ | $\pm 4$ | $\pm 3$ | LSB |
| $\mathrm{V}_{\text {IN }}=-10 \mathrm{~V}$ | $\pm 0.15$ | $\pm 0.1$ | $\pm 0.1$ | \% of F.S. |
| Full Scale Calibration Error <br> $+25^{\circ} \mathrm{C}$ (Max), with fixed $50 \Omega$ resistor from REF OUT to REF IN (Adjustable to Zero) | $\pm 0.25$ | $\pm 0.25$ | $\pm 0.15$ | \% of F.S. |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (No adjustment at $+25^{\circ} \mathrm{C}$ ) | $\pm 0.75$ | $\pm 0.50$ | $\pm 0.275$ | \% of F.S. |
| $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (With adjustment to zero $+25^{\circ} \mathrm{C}$ ) | $\pm 0.50$ | $\pm 0.25$ | $\pm 0.125$ | \% of F.S. |
| Temperature Coefficients Guaranteed Max change, $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (Using internal reference) <br> Unipolar Offset | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| Bipolar Offset | $\pm 2$ | $\pm 2$ | $\pm 1$ | LSB |
| Full Scale Calibration | $\pm 20$ | $\pm 10$ | $\pm 5$ | LSB |
| Power Supply Rejection Max change in Full Scale Calibration $+13.5 \mathrm{~V}<\mathrm{V}_{\mathrm{CC}}<+16.5 \mathrm{~V} \text { or }+11.4 \mathrm{~V}<\mathrm{V}_{\mathrm{CC}}<+12.6 \mathrm{~V}$ | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| $+4.5 \mathrm{~V}<\mathrm{V}_{\text {LOGIC }}<+5.5 \mathrm{~V}$ | $\pm 1 / 2$ | $\pm 1 / 2$ | $\pm 1 / 2$ | LSB |
| $-16.5 \mathrm{~V}<\mathrm{V}_{\mathrm{EE}}<-13.5 \mathrm{~V} \text { or }-12.6 \mathrm{~V}<\mathrm{V}_{\mathrm{EE}}<-11.4 \mathrm{~V}$ | $\pm 2$ | $\pm 1$ | $\pm 1$ | LSB |
| ANALOG INPUTS |  |  |  |  |
| Input Ranges <br> Bipolar | $-5 \text { to }+5$ |  |  | V |
|  | $-10 \text { to }+10$ |  |  | V |
| Unipolar | $0 \text { to }+10$ |  |  | V |
|  | $0 \text { to +20 }$ |  |  | V |

Specifications HI-574A, HI-674A, HI-774
DC and Transfer Accuracy Specifications Typical at $+25^{\circ} \mathrm{C}$ with $\mathrm{V}_{\mathrm{CC}}=+15 \mathrm{~V}$ or $+12 \mathrm{~V}, \mathrm{~V}_{\mathrm{LOGIC}}=+5 \mathrm{~V}, \mathrm{~V}_{\mathrm{EE}}=-15 \mathrm{~V}$ or -12 V , Unless Otherwise Specified (Continued)

| PARAMETERS | TEMPERATURE RANGE $-2\left(-55^{\circ} \mathrm{C}\right.$ to $\left.+125^{\circ} \mathrm{C}\right)$ |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | S SUFFIX | T SUFFIX | U SUFFIX |  |
| Input Impedance |  |  |  |  |
| 10 V Span | $5 \mathrm{~K}, \pm 25 \%$ |  |  | $\Omega$ |
| 20 V Span | 10K, $\pm 25 \%$ |  |  | $\Omega$ |
| POWER SUPPLIES |  |  |  |  |
| Operating Voltage Range |  |  |  |  |
| $\mathrm{V}_{\text {LOGIC }}$ | +4.5 to +5.5 |  |  | V |
| $\mathrm{V}_{\mathrm{CC}}$ | +11.4 to +16.5 |  |  | V |
| $\mathrm{V}_{\mathrm{EE}}$ | -11.4 to -16.5 |  |  | V |
| Operating Current | 7 Typ, 15 Max |  |  |  |
|  |  |  |  | mA |
| $\mathrm{I}_{\text {CC }}+15 \mathrm{~V}$ Supply | 11 Typ, 15 Max |  |  | mA |
| $\mathrm{I}_{\text {EE }}-15 \mathrm{~V}$ Supply | 21 Typ, 28 Max |  |  | mA |
| Power Dissipation <br> $\pm 15 \mathrm{~V},+15 \mathrm{~V}$ |  |  |  |  |
|  |  |  |  | mW |
| $\pm 12 \mathrm{~V},+5 \mathrm{~V}$ | 385 Typ |  |  | mW |
| Internal Reference Voltage  <br> $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ $+10.00 \pm 0.05 \mathrm{Max}$ |  |  |  |  |
|  |  |  |  | V |
| Output current, available for external loads (External load should not change during conversion). | 2.0 Max |  |  | mA |

Digital Specifications All Models, Over Full Temperature Range

| PARAMETERS | MIN | TYP | MAX |
| :---: | :---: | :---: | :---: |
| Logic Inputs (CE, $\overline{C S}, \mathrm{R} / \overline{\mathrm{C}}, \mathrm{A}_{\mathrm{O}}, 412 / \overline{8}$ ) |  |  |  |
| Logic "1" | +2.4V | - | +5.5V |
| Logic "0" | -0.5V | - | $+0.8 \mathrm{~V}$ |
| Current | - | $\pm 0.1 \mu \mathrm{~A}$ | $\pm 5 \mu \mathrm{~A}$ |
| Capacitance | - | 5 pF | - |
| Logic Outputs (DB11-DB0, STS) |  |  |  |
| Logic "0" ( $\mathrm{I}_{\text {SINK }}-1.6 \mathrm{~mA}$ ) | - | - | +0.4V |
| Logic "1" ( $\mathrm{ISOURCE}^{-500 \mu \mathrm{~A}}$ ) | +2.4V | - | - |
| Logic "1" ( Source $^{-10 \mu \mathrm{~A}}$ ) | $+4.5 \mathrm{~V}$ | - | - |
| Leakage (High Z State, DB11-DB0 Only) | - | $\pm 0.1 \mu \mathrm{~A}$ | $\pm 5 \mu \mathrm{~A}$ |
| Capacitance | - | 5 pF | - |

Timing Specifications (HI-574A) $+25^{\circ} \mathrm{C}$, Note 2, Unless Otherwise Specified

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CONVERT MODE |  |  |  |  |  |
| $\mathrm{t}_{\text {DSC }}$ | STS Delay from CE | - | - | 200 | ns |
| $t_{\text {HEC }}$ | CE Pulse Width | 50 | - | - | ns |
| $\mathrm{t}_{\text {SSC }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{HSC}}$ | $\overline{\mathrm{CS}}$ Low During CE High | 50 | - | - | ns |
| $t_{\text {SRC }}$ | R/C to CE Setup | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{HRC}}$ | R/C Low During CE High | 50 | - | - | ns |
| $t_{\text {SAC }}$ | $A_{O}$ to CE Setup | 0 | - | - | ns |
| $t_{\text {HAC }}$ | $\mathrm{A}_{\mathrm{O}}$ Valid During CE High | 50 | - | - | ns |
| $t_{C}$ | Conversion Time 12 -Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ | 15 | 20 | 25 | $\mu \mathrm{s}$ |
|  | 8-Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ | 10 | 13 | 17 | $\mu \mathrm{s}$ |

READ MODE

| $t_{\text {DD }}$ | Access Time from CE | - | 75 | 150 | ns |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $t_{H D}$ | Data Valid After CE Low | 25 | - | - | ns |
| $\mathrm{t}_{\mathrm{HL}}$ | Output Float Delay | - | 100 | 150 | ns |
| $t_{\text {SSR }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | - | - | ns |
| $t_{\text {SRR }}$ | R/C to CE Setup | 0 | - | - | ns |
| $t_{\text {SAR }}$ | $A_{O}$ to CE Setup | 50 | - | - | ns |
| $t_{\text {HSR }}$ | $\overline{\mathrm{CS}}$ Valid After CE Low | 0 | - | - | ns |
| $t_{\text {HRR }}$ | R/C High After CE Low | 0 | - | - | ns |
| $t_{\text {HAR }}$ | $\mathrm{A}_{\text {O }}$ Valid After CE Low | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{HS}}$ | STS Delay After Data Valid | 300 | - | 1200 | ns |

Timing Specifications (HI-674A) $+25^{\circ} \mathrm{C}$, Note 2, Unless Otherwise Specified

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CONVERT MODE |  |  |  |  |  |
| $t_{\text {DSC }}$ | STS Delay from CE | - | - | 200 | ns |
| $t_{\text {HEC }}$ | CE Pulse Width | 50 | - | - | ns |
| ${ }^{\text {SSSC }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{HSC}}$ | $\overline{\mathrm{CS}}$ Low During CE High | 50 | - | - | ns |
| $t_{\text {SRC }}$ | R/E to CE Setup | 50 | - | - | ns |
| $t_{\text {HRC }}$ | R/C Low During CE High | 50 | - | - | ns |
| $t_{\text {SAC }}$ | $A_{O}$ to CE Setup | 0 | - | - | ns |
| $\mathrm{t}_{\mathrm{HAC}}$ | $\mathrm{A}_{\mathrm{O}}$ Valid During CE High | 50 | - | - | ns |
| $\mathrm{t}_{C}$ | Conversion Time 12 -Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ | 9 | 12 | 15 | $\mu \mathrm{s}$ |
|  | 8-Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ | 6 | 8 | 10 | $\mu \mathrm{s}$ |

READ MODE

| $t_{\text {DD }}$ | Access Time from CE | - | 75 | 150 | ns |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{HD}}$ | Data Valid After CE Low | 25 | - | - | ns |
| $\mathrm{t}_{\mathrm{HL}}$ | Output Float Delay | - | 100 | 150 | ns |
| $\mathrm{t}_{\text {SSR }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | - | - | ns |
| $t_{\text {SRR }}$ | R/C to CE Setup | 0 | - | - | ns |
| $t_{\text {SAR }}$ | $A_{0}$ to CE Setup | 50 | - | - | ns |
| $t_{\text {HSR }}$ | $\overline{\mathrm{CS}}$ Valid After CE Low | 0 | - | - | ns |
| $t_{\text {HRR }}$ | R/C High After CE Low | 0 | - | - | ns |
| $t_{\text {HAR }}$ | $\mathrm{A}_{\mathrm{O}}$ Valid After CE Low | 50 | - | - | ns |
| $t_{\text {HS }}$ | STS Delay After Data Valid | 25 | - | 850 | ns |

Specifications HI-574A, HI-674A, HI-774

Timing Specifications (HI-774) $+25^{\circ} \mathrm{C}$, Into a load with $\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega$ and $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, Note 2, Unless Otherwise Specified

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CONVERT MODE |  |  |  |  |  |
| $t_{\text {DSC }}$ | STS Delay from CE | - | 100 | 200 | ns |
| $t_{\text {HEC }}$ | CE Pulse Width | 50 | 30 | - | ns |
| $\mathrm{t}_{\text {SSC }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | 20 | - | ns |
| $\mathrm{t}_{\mathrm{HSC}}$ | $\overline{\mathrm{CS}}$ Low During CE High | 50 | 20 | - | ns |
| $\mathrm{t}_{\text {SRC }}$ | R/ $\bar{C}$ to CE Setup | 50 | 0 | - | ns |
| $\mathrm{t}_{\mathrm{HRC}}$ | R/C Low During CE High | 50 | 20 | - | ns |
| $t_{\text {SAC }}$ | $A_{O}$ to CE Setup | 0 | 0 | - | ns |
| $t_{\text {HAC }}$ | $\mathrm{A}_{\mathrm{O}}$ Valid During CE High | 50 | 30 | - | ns |
| $t_{C}$ | Conversion Time 12 -Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}(-5)$ | - | 8.0 | 9 | $\mu \mathrm{s}$ |
|  | 8-Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}(-5)$ | - | 6.4 | 6.8 | $\mu \mathrm{s}$ |
|  | 12-Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}(-2)$ | - | 9 | 11 | $\mu \mathrm{s}$ |
|  | 8-Bit Cycle $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}(-2)$ | - | 6.8 | 8.3 | $\mu \mathrm{s}$ |

READ MODE

| $t_{D D}$ | Access Time from CE | - | 75 | 150 | ns |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{HD}}$ | Data Valid After CE Low | 25 | 35 | - | ns |
| $\mathrm{t}_{\mathrm{HL}}$ | Output Float Delay | - | 70 | 150 | ns |
| $\mathrm{t}_{\text {SSR }}$ | $\overline{\mathrm{CS}}$ to CE Setup | 50 | 0 | - | ns |
| $\mathrm{t}_{\text {SRR }}$ | R/ $\bar{C}$ to CE Setup | 0 | 0 | - | ns |
| $\mathrm{t}_{\text {SAR }}$ | $A_{0}$ to CE Setup | 50 | 25 | - | ns |
| $t_{\text {HSR }}$ | CS Valid After CE Low | 0 | 0 | - | ns |
| $\mathrm{t}_{\text {HRR }}$ | R/C High After CE Low | 0 | 0 | - | ns |
| $\mathrm{t}_{\text {HAR }}$ | AO Valid After CE Low | 50 | 25 | - | ns |
| $\mathrm{t}_{\text {HS }}$ | STS Delay After Data Valid | - | 90 | 300 | ns |

NOTE:

1. Dissipation rating assumes device is mounted with all leads soldered to printed circuit board.
2. Time is measured from $50 \%$ level of digital transitions. Tested with a 50 pF and $3 \mathrm{k} \Omega$ load.

## Pin Description

| PIN | SYMBOL | DESCRIPTION |
| :---: | :---: | :---: |
| 1 | $V_{\text {Logic }}$ | Logic supply pin (+5V) |
| 2 | 12/8 | Data Mode Select - Selects between 12-bit and 8-bit output modes. |
| 3 | $\overline{\mathrm{CS}}$ | Chip Select - Chip Select high disables the device. |
| 4 | $\mathrm{A}_{\circ}$ | Byte Address/Short Cycle - See Table 1 for operation. |
| 5 | R/C | Read/Convert - See Table 1 for operation. |
| 6 | CE | Chip Enable - Chip Enable low disables the device. |
| 7 | $\mathrm{V}_{\mathrm{CC}}$ | Positive Supply (+12V/+15V) |
| 8 | REF OUT | +10V Reference |
| 9 | AC | Analog Common |
| 10 | REF IN | Reference Input |
| 11 | $\mathrm{V}_{\mathrm{EE}}$ | Negative Supply (-12V/-15V). |
| 12 | BIP OFF | Bipolar Offset |
| 13 | 10V Input | 10V Input - Used for 0 V to 10 V and -5V to +5 V input ranges. |
| 14 | 20V Input | 20 V Input - Used for 0 V to 20 V and -10V to +10 V input ranges. |
| 15 | DC | Digital Common |
| 16 | DB0 | Data Bit 0 (LSB) |
| 17 | DB1 | Data Bit 1 |
| 18 | DB2 | Data Bit 2 |
| 19 | DB3 | Data Bit 3 |
| 20 | DB4 | Data Bit 4 |
| 21 | DB5 | Data Bit 5 |
| 22 | DB6 | Data Bit 6 |
| 23 | DB7 | Data Bit 7 |
| 24 | DB8 | Data Bit 8 |
| 25 | DB9 | Data Bit 9 |
| 26 | DB10 | Data Bit 10 |
| 27 | DB11 | Data Bit 11 (MSB) |
| 28 | STS | Status Bit - Status high implies a conversion is in progress. |

## Definitions of Specifications

## Linearity Error

Linearity error refers to the deviation of each individual code from a line drawn from "zero" through "full scale". The point used as "zero" occurs $1 / 2$ LSB ( 1.22 mV for 10 V span) before the first code transition (all zeros to only the LSB "on"). "Full scale" is defined as a level $1 \frac{1}{2}$ LSB beyond the last code transition (to all ones). The deviation of a code from the true straight line is measured from the middle of each particular code.

The $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A}) \mathrm{K}$ and L grades are guaranteed for maximum nonlinearity of $\pm 1 / 2$ LSB. For these grades, this means that an analog value which falls exactly in the center of a given code width will result in the correct digital output code. Values nearer the upper or lower transition of the code width may produce the next upper or lower digital output code. The HI-X74(A)J is guaranteed to $\pm 1$ LSB max error. For this grade, an analog value which falls within a given code width will result in either the correct code for that region or either adjacent one.
Note that the linearity error is not user-adjustable.
Differential Linearity Error (No Missing Codes)
A specification which guarantees no missing codes requires that every code combination appear in a monotonic increasing sequence as the analog input level is increased. Thus every code must have a finite width. For the HI-X74(A)K and L grades, which guarantee no missing codes to 12-bit resolution, all 4096 codes must be present over the entire operating temperature ranges. The $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A}) \mathrm{J}$ grade guarantees no missing codes to 11-bit resolution over temperature; this means that all code combinations of the upper 11 bits must be present; in practice very few of the 12-bit codes are missing.

## Unipolar Offset

The first transition should occur at a level $1 / 2$ LSB above analog common. Unipolar offset is defined as the deviation of the actual transition from that point. This offset can be adjusted as discussed on the following pages. The unipolar offset temperature coefficient specifies the maximum change of the transition point over temperature, with or without external adjustment.

## Bipolar Offset

Similarly, in the bipolar mode, the major carry transition (0111 11111111 to 100000000000 ) should occur for an analog value $\frac{1}{2}$ LSB below analog common. The bipolar offset error and temperature coefficient specify the initial deviation and maximum change in the error over temperature.

## Full Scale Calibration Error

The last transition (from 111111111110 to 11111111 1111) should occur for an analog value $1 \frac{1}{2}$ LSB below the nominal full scale ( 9.9963 V for 10.000 V full scale). The full scale calibration error is the deviation of the actual level at the last transition from the ideal level. This error, which is typically 0.05 to $0.1 \%$ of full scale, can be trimmed out as shown in Figures 2 and 3 . The full scale calibration error over temperature is given with and without the initial error trimmed out. The temperature coefficients for each grade indicate the maximum change in the full scale gain from the initial value using the internal 10 V reference.

## Temperature Coefficients

The temperature coefficients for full-scale calibration, unipolar offset, and bipolar offset specify the maximum change from the initial $\left(+25^{\circ} \mathrm{C}\right)$ value to the value at $\mathrm{T}_{\text {MIN }}$ or $\mathrm{T}_{\text {MAX }}$.

## Power Supply Rejection

The standard specifications for the HI-X74A assume use of +5.00 and $\pm 15.00$ or $\pm 12.00$ volt supplies. The only effect of power supply error on the performance of the device will be a small change in the full scale calibration. This will result in a linear change in all lower order codes. The specifications show the maximum change in calibration from the initial value with the supplies at the various limits.

## Code Width

A fundamental quantity for $A / D$ converter specifications is the code width. This is defined as the range of analog input values for which a given digital output code will occur. The nominal value of a code width is equivalent to 1 least significant bit (LSB) of the full scale range or 2.44 mV out of 10 V for a 12-bit ADC.

## Quantization Uncertainty

Analog-to-digital converters exhibit an inherent quantization uncertainty of $\pm^{1} / 2$ LSB. This uncertainty is a fundamental characteristic of the quantization process and cannot be reduced for a converter of given resolution.

## Left-justified Data

The data format used in the $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A})$ is left-justified. This means that the data represents the analog input as a fraction of full-scale, ranging from 0 to $\frac{4095}{4096}$. This implies a binary point to the left of the MSB.

## Applying the H-X74(A)

For each application of this converter, the ground connections, power supply bypassing, analog signal source, digital timing and signal routing on the circuit board must be optimized to assure maximum performance. These areas are reviewed in the following sections, along with basic operating modes and calibration requirements.

## Physical Mounting and Layout Considerations

## Layout

Unwanted, parasitic circuit components, (L, R, and C) can make 12 bit accuracy impossible, even with a perfect $A / D$ converter. The best policy is to eliminate or minimize these parasitics through proper circuit layout, rather than try to quantify their effects.
The recommended construction is a double-sided printed circuit board with a ground plane on the component side. Other techniques, such as wire-wrapping or point-to-point wiring on vector board, will have an unpredictable effect on accuracy.

In general, sensitive analog signals should be routed between ground traces and kept well away from digital lines. If analog and digital lines must cross, they should do so at right angles.

## Power Supplies

Supply voltages to the $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A})(+15 \mathrm{~V},-15 \mathrm{~V}$ and $+5 \mathrm{~V})$ must be "quiet" and well regulated. Voltage spikes on these lines can affect the converter's accuracy, causing several LSBs to flicker when a constant input is applied. Digital noise and spikes from a switching power supply are especially troublesome. If switching supplies must be used, outputs should be carefully filtered to assure "quiet" DC voltage at the converter terminals.

Further, a bypass capacitor pair on each supply voltage terminal is necessary to counter the effect of variations in supply current. Connect one pair from pin 1 to 15 ( $V_{\text {LOGIC }}$ supply), one from pin 7 to 9 ( $\mathrm{V}_{\mathrm{CC}}$ to Analog Common) and one from pin 11 to 9 ( $\mathrm{V}_{\mathrm{EE}}$ to Analog Common). For each capacitor pair, a $10 \mu \mathrm{~F}$ tantalum type in parallel with a $0.1 \mu \mathrm{~F}$ ceramic type is recommended.

## Ground Connections

Pins 9 and 15 should be tied together at the package to guarantee specified performance for the converter. In addition, a wide PC trace should run directly from pin 9 to (usually) +15 V common, and from pin 15 to (usually) the +5 V Logic Common. If the converter is located some distance from the system's "single point" ground, make only these connections to pins 9 and 15: Tie them together at the package, and back to the system ground with a single path. This path should have low resistance. (Code dependent currents flow in the $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{EE}}$ and $\mathrm{V}_{\text {LOGIC }}$ terminals, but not through the HI-X74(A)'s Analog Common or Digital Common).

## Analog Signal Source

## HI-574A and HI-674A

The device chosen to drive the $\mathrm{HI}-\mathrm{X} 74 \mathrm{~A}$ analog input will see a nominal load of $5 \mathrm{k} \Omega$ ( 10 V range) or $10 \mathrm{k} \Omega$ ( 20 V range). However, the other end of these input resistors may change $\pm 400 \mathrm{mV}$ with each bit decision, creating abrupt changes in current at the analog input. Thus, the signal source must maintain its output voltage while furnishing these step changes in load current, which occur at $1.6 \mu \mathrm{~s}$ and 950 ns intervals for the HI574 A and $\mathrm{HI}-674 \mathrm{~A}$ respectively. This requires low output impedance and fast settling by the signal source.
The output impedance of an op amp, for example, has an open loop value which, in a closed loop, is divided by the loop gain available at a frequency of interest. The amplifier should have acceptable loop gain at 600 KHz for use with the $\mathrm{HI}-\mathrm{X} 74 \mathrm{~A}$. To check whether the output properties of a signal source are suitable, monitor the HI-X74A's input (pin 13 or 14) with an oscilloscope while a conversion is in progress. Each of the twelve disturbances should subside in $1 \mu$ s or less for the $\mathrm{HI}-574 \mathrm{~A}$ and 500 ns or less for the HI-674A. (The comparator decision is made about $1.5 \mu \mathrm{~s}$ and 850 ns after each code change from the SAR for the HI-574A and HI-674A, respectively.)

If the application calls for a Sample/Hold to precede the converter, it should be noted that not all Sample/Holds are compatible with the HI-574A in the manner described above. These will require an additional wideband buffer amplifier to lower their output impedance. A simpler solution is to use the Harris HA-5320 Sample/Hold, which was designed for use with the HI-574A.

## HI-774

The device driving the HI-774 analog input will see a nominal load of $5 \mathrm{k} \Omega$ ( 10 V range) or $10 \mathrm{k} \Omega$ ( 20 V range). However, the other end of these input resistors may change as much as $\pm 400 \mathrm{mV}$ with each bit decision. These input disturbances are caused by the internal DAC changing codes which causes a glitch on the summing junction. This creates abrupt changes in current at the analog input causing a "kick back" glitch from the input. Because the algorithm starts with the MSB, the first glitches will be the largest and get smaller as the conversion proceeds. These glitches can occur at 350ns intervals so an op amp with a low output impedance and fast settling is desirable. Ultimately the input must settle to within the window of Figure 1 at the bit decision points in order to achieve 12 bit accuracy.

The HI-774 differs from the most high-speed successive approximation type ADC's in that it does not require a high performance buffer or sample and hold. With error correction the input can settle while the conversion is underway, but only during the first $4.8 \mu \mathrm{~s}$. The input must be within $10.76 \%$ of the final value when the MSB decision is made. This occurs approximately 650 ns after the conversion has been initiated. Digital error correction also loosens the bandwidth requirements of the buffer or sample and hold. As long as the input "kick back" disturbances settle within the window of Figure 1 the device will remain accurate. The combined effect of settling and the "kick back" disturbances must remain in the Figure 1 window.

If the design is being optimized for speed, the input device should have closed loop bandwidth to 3 MHz , and a low output impedance (calculated by dividing the open loop output resistance by the open loop gain). If the application requires a high speed sample and hold the Harris HA-5330 or HA-5320 are recommended.

In any design the input (pin 13 or 14) should be checked during a conversion to make sure that the input stays within the correctable window of Figure 1.

## Digital Error Correction

## HI-774

The HI-774 features the smart successive approximation register (SSAR ${ }^{\text {TM }}$ ) which includes digital error correction. This has the advantage of allowing the initial input to vary within a +31 to -32 LSB window about the final value. The input can move during the first $4.8 \mu \mathrm{~s}$, after which it must remain stable within $\pm 1 / 2$ LSB. With this feature a conversion can start before the input has settled completely; however, it must be within the window as described in Figure 1.

The conversion cycle starts by making the first 8 -bit decisions very quickly, allowing the internal DAC to settle only to 8 -bit accuracy. Then the converter goes through two error correction cycles. At this point the input must be stable within $\pm 1 / 2$ LSB. These cycles correct the 8 -bit word to 12 -bit accuracy for any errors made (up to +16 or -32 LSBs). This is up one count or down two counts at 8 -bit resolution. The converter then continues to make the 4 LSB decisions, settling out to 12-bit accuracy. The last four bits can adjust the code in the positive direction by up to 15 LSBs. This results
in a total correction range of +31 to -32 LSBs. When an 8-bit conversion is performed, the input must settle to within $\pm \frac{1}{2}$ LSB at 8 bit resolution (which equals $\pm 8$ LSBs at 12 -bit resolution).

With the HI-774 a conversion can be initiated before the input has completely settled, as long as it meets the constraints of the Figure 1 window. This allows the user to start conversion up to $4.8 \mu \mathrm{~s}$ earlier than with a typical analog to digital converter. A typical successive approximation type ADC must have a constant input during a conversion because once a bit decision is made it is locked in and cannot change.


FIGURE 1. HI-774 ERROR CORRECTION WINDOW vs TIME

†When driving the 20 V (pin 14) input, minimize capacitance on pin 13.
FIGURE 2. UNIPOLAR CONNECTIONS

$\dagger$ When driving the 20V (pin 14) input, minimize capacitance on pin 13.

## FIGURE 3. BIPOLAR CONNECTIONS

## Range Connections and Calibration Procedures

The $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A})$ is a "complete" $\mathrm{A} / \mathrm{D}$ converter, meaning it is fully operational with addition of the power supply voltages, a Start Convert signal, and a few external components as shown in Figure 2 and Figure 3. Nothing more is required for most applications.

Whether controlled by a processor or operating in the standalone mode, the $\mathrm{HI}-\mathrm{X74}(\mathrm{~A})$ offers four standard input ranges: 0 V to $+10 \mathrm{~V}, 0 \mathrm{~V}$ to $+20 \mathrm{~V}, \pm 5 \mathrm{~V}$ and $\pm 10 \mathrm{~V}$. The maximum errors for gain and offset are listed under Specifications. If required, however, these errors may be adjusted to zero as explained below. Power supply and ground connections have been discussed in an earlier section.

## Unipolar Connections and Calibration

Refer to Figure 2. The resistors shown* are for calibration of offset and gain. If this is not required, replace R2 with a $50 \Omega$, $1 \%$ metal film resistor and remove the network on pin 12. Connect pin 12 to pin 9 . Then, connect the analog signal to pin 13 for the 0 V to 10 V range, or to pin 14 for the 0 V to 20 V range. Inputs to +20 V ( 5 V over the power supply) are no problem - the converter operates normally.

Calibration consists of adjusting the converter's most negative output to its ideal value (offset adjustment), then, adjusting the most positive output to its ideal value (gain adjustment). To understand the procedure, note that in principle, one is setting the output with respect to the midpoint of an increment of analog input, as denoted by two adjacent code changes. Nominal value of an increment is one LSB. However, this approach is impractical because nothing "hap-
pens" at a midpoint to indicate that an adjustment is complete. Therefore, calibration is performed in terms of the observable code changes instead of the midpoint between code changes.

For example, midpoint of the first LSB increment should be positioned at the origin, with an output code of all 0's. To do this, apply an input of $+1 / 2$ LSB $(+1.22 \mathrm{mV}$ for the 10 V range; +2.44 mV for the 20 V range). Adjust the Offset potentiometer R1 until the first code transition flickers between 00000000 0000 and 000000000001.

Next, perform a Gain Adjust at positive full scale. Again, the ideal input corresponding to the last code change is applied. This is $1 \frac{1}{2}$ LSB's below the nominal full scale ( +9.9963 V for 10 V range; +19.9927 V for 20 V range). Adjust the Gain potentiometer R2 for flicker between codes 111111111110 and 111111111111.

## Bipolar Connections and Calibration

Refer to Figure 3. The gain and offset errors listed under Specifications may be adjusted to zero using potentiometers R1 and R2*. If this isn't required, either or both pots may be replaced by a $50 \Omega, 1 \%$ metal film resistor.

Connect the Analog signal to pin 13 for a $\pm 5 \mathrm{~V}$ range, or to pin 14 for a $\pm 10 \mathrm{~V}$ range. Calibration of offset and gain is similar to that for the unipolar ranges as discussed above. First apply a DC input voltage $\frac{1}{2}$ LSB above negative full scale (i.e., -4.9988 V for the $\pm 5 \mathrm{~V}$ range, or -9.9976 V for the $\pm 10 \mathrm{~V}$ range). Adjust the offset potentiometer R1 for flicker between output codes 000000000000 and 00000000 0001. Next, apply a DC input voltage $1 \frac{1}{2}$ LSB's below positive full scale $(+4.9963 \mathrm{~V}$ for $\pm 5 \mathrm{~V}$ range; +9.9927 V for $\pm 10 \mathrm{~V}$ range). Adjust the Gain potentiometer R2 for flicker between codes 111111111110 and 111111111111.
*The $100 \Omega$ potentiometer R2 provides Gain Adjust for the 10 V and 20 V ranges. In some applications, a full scale of 10.24 V (LSB equals 2.5 mV ) or 20.48 V (LSB equals 5.0 mV ) is more convenient. For these, replace R2 by a $50 \Omega, 1 \%$ metal film resistor. Then, to provide Gain Adjust for the 10.24 V range, add a $200 \Omega$ potentiometer in series with pin 13 . For the 20.48 V range, add a $500 \Omega$ potentiometer in series with pin 14.

## Controlling the HI-X74(A)

The HI-X74(A) includes logic for direct interface to most microprocessor systems. The processor may take full control of each conversion, or the converter may operate in the "stand-alone" mode, controlled only by the R/C input. Full control consists of selecting an 8 or 12 bit conversion cycle, initiating the conversion, and reading the output data when ready-choosing either 12 bits at once or 8 followed by 4 , in a left-justified format. The five control inputs are all TTL/ CMOS-compatible: $\left(12 / \overline{8}, \overline{\mathrm{CS}}, \mathrm{A}_{\mathrm{O}}, \mathrm{R} / \overline{\mathrm{C}}\right.$ and CE$)$. Table 1 illustrates the use of these inputs in controlling the converter's operations. Also, a simplified schematic of the internal control logic is shown in Figure 7.

## "Stand-Alone Operation"

The simplest control interface calls for a singe control line connected to R/C. Also, CE and 12/8 are wired high, $\overline{\mathrm{CS}}$ and $A_{O}$ are wired low, and the output data appears in words of 12 bits each.

The $R / \bar{C}$ signal may have any duty cycle within (and including) the extremes shown in Figures 8 and 9. In general, data may be read when R/C is high unless STS is also high, indicating a conversion is in progress. Timing parameters particular to this mode of operation are listed below under "StandAlone Mode Timing".

## HI-574A STAND-ALONE MODE TIMING

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $t_{\text {HRL }}$ | Low R/C Pulse Width | 50 | - | - | ns |
| $t_{\text {DS }}$ | STS Delay from R/C | - | - | 200 | ns |
| $t_{\text {HDR }}$ | Data Valid after R/C Low | 25 | - | - | ns |
| $\mathrm{t}_{\mathrm{HS}}$ | STS Delay after Data Valid | 300 | - | 1200 | ns |
| $\mathrm{t}_{\text {HRH }}$ | High R/C Pulse Width | 150 | - | - | ns |
| $\mathrm{t}_{\text {DDR }}$ | Data Access Time | - | - | 150 | ns |

Time is measured from $50 \%$ level of digital transitions. Tested with a 50 pF and $3 \mathrm{k} \Omega$ load.

HI-674A STAND-ALONE MODE TIMING

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {HRL }}$ | Low R/C Pulse Width | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{DS}}$ | STS Delay from R/C | - | - | 200 | ns |
| $t_{\text {HDR }}$ | Data Valid after R/C Low | 25 | - | - | ns |
| $\mathrm{t}_{\mathrm{HS}}$ | STS Delay after Data Valid | 25 | - | 850 | ns |
| $t_{\text {HRH }}$ | High R/C Pulse Width | 150 | - | - | ns |
| $t_{\text {DDR }}$ | Data Access Time | - | - | 150 | ns |

Time is measured from $50 \%$ level of digital transitions. Tested with a 50 pF and $3 \mathrm{k} \Omega$ load.

HI-774 STAND-ALONE MODE TIMING

| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $t_{\text {HRL }}$ | Low R/C Pulse Width | 50 | - | - | ns |
| $\mathrm{t}_{\mathrm{DS}}$ | STS Delay from R/C | - | - | 200 | ns |
| $\mathrm{t}_{\text {HDR }}$ | Data Valid after R/C Low | 20 | - | - | ns |
| $\mathrm{t}_{\text {HS }}$ | STS Delay after Data Valid | - | - | 850 | ns |
| $\mathrm{t}_{\text {HRH }}$ | High R/ट्ट Pulse Width | 150 | - | - | ns |
| $\mathrm{t}_{\text {DDR }}$ | Data Access Time | - | - | 150 | ns |

## Conversion Length

A Convert Start transition (see Table 1) latches the state of $A_{O}$, which determines whether the conversion continues for 12 bits ( $A_{O}$ low) or stops with 8 -bits ( $A_{O}$ high). If all 12-bits are read following an 8 -bit conversion, the last three LSB's will read ZERO and DB3 will read ONE. $A_{O}$ is latched because it is also involved in enabling the output buffers (see "Reading the Output Data"). No other control inputs are latched.

TABLE 1. TRUTH TABLE FOR HI-X74(A) CONTROL INPUTS

| $\mathbf{C E}$ | $\overline{\mathbf{C S}}$ | $\mathbf{R} / \overline{\mathbf{C}}$ | $\mathbf{1 2 / \mathbf { 8 }}$ | $\mathbf{A}_{\mathbf{O}}$ | OPERATION |
| :---: | :---: | :---: | :---: | :---: | :--- |
| 0 | X | X | X | X | None |
| X | 1 | X | X | X | None |
| $\uparrow$ | 0 | 0 | X | 0 | Initiate 12 bit conversion |
| $\uparrow$ | 0 | 0 | X | 1 | Initiate 8 bit conversion |
| 1 | $\downarrow$ | 0 | X | 0 | Initiate 12 bit conversion |
| 1 | $\downarrow$ | 0 | X | 1 | Initiate 8 bit conversion |
| 1 | 0 | $\downarrow$ | X | 0 | Initiate 12 bit conversion |
| 1 | 0 | $\downarrow$ | X | 1 | Initiate 8 bit conversion |
| 1 | 0 | 1 | 1 | X | Enable 12 bit Output |
| 1 | 0 | 1 | 0 | 0 | Enable 8 MSB's Only |
| 1 | 0 | 1 | 0 | 1 | Enable 4 LSB's Plus 4 Trailing <br> Zeroes |

## Conversion Start

A conversion may be initiated as shown in Table 1 by a logic transition on any of three inputs: $\mathrm{CE}, \overline{\mathrm{CS}}$ or $\mathrm{R} / \overline{\mathrm{C}}$. The last of the three to reach the correct state starts the conversion, so one, two or all three may be dynamically controlled. The nominal delay from each is the same, and if necessary, all three may change state simultaneously. To assure that a particular input controls the start of conversion, the other two should be set up at least 50 ns earlier, however. See the HI-774 Timing Specifications, Convert mode.
This variety of $\mathrm{HI}-\mathrm{X} 74(\mathrm{~A})$ control modes allows a simple interface in most system applications. The Convert Start timing relationships are illustrated in Figure 4.

The output signal STS indicates status of the converter by going high only while a conversion is in progress. While STS is high, the output buffers remain in a high impedance state and data cannot be read. Also, an additional Start Convert will not reset the converter or reinitiate a conversion while STS is high.

## Reading the Output Data

The output data buffers remain in a high impedance state until four conditions are met: R/C high, STS low, CE high and $\overline{\mathrm{CS}}$ low. At that time, data lines become active according to the state of inputs $12 / \overline{8}$ and $A_{0}$. Timing constraints are illustrated in Figure 5.

The $12 / \overline{8}$ input will be tied high or low in most applications, though it is fully TTL/CMOS-compatible. With $12 / \overline{8}$ high, all 12 output lines become active simultaneously, for interface to a 12-bit or 16-bit data bus. The $\mathrm{A}_{\mathrm{O}}$ input is ignored.
With $12 / \overline{8}$ low, the output is organized in two 8 -bit bytes, selected one at a time by $A_{O}$. This allows an 8-bit data bus to be connected as shown in Figure 6. $\mathrm{A}_{\mathrm{O}}$ is usually tied to the least significant bit of the address bus, for storing the HIX74(A) output in two consecutive memory locations. (With $A_{O}$ low, the 8 MSB 's only are enabled. With $A_{O}$ high, 4 MSB's are disabled, bits 4 through 7 are forced low, and the 4 LSB's are enabled). This two byte format is considered "left justified data", for which a decimal (or binary!) point is assumed to the left of byte 1 :

## BYTE 1

BYTE 2


Further, $A_{O}$ may be toggled at any time without damage to the converter. Break-before-make action is guaranteed between the two data bytes, which assures that the outputs strapped together in Figure 6 will never be enabled at the same time.

A read operation usually begins after the conversion is complete and STS is low. For earliest access to the data however, the read should begin no later than ( $t_{D D}+t_{H S}$ ) before STS goes low. See Figure 5.


See HI-774 Timing Specifications for more information.
FIGURE 4. CONVERT START TIMING


See HI-774 Timing Specifications for more information.
FIGURE 5. READ CYCLE TIMING


FIGURE 6. INTERFACE TO AN 8 BIT DATA BUS


FIGURE 7. HI-774 CONTROL LOGIC


FIGURE 8. LOW PULSE FOR R/C - OUTPUTS ENABLED AFTER CONVERSION


FIGURE 9. HIGH PULSE FOR R/C - OUTPUTS ENABLED WHILE R/C HIGH, OTHERWISE HIGH-Z

## Die Characteristics

DIE DIMENSIONS:
Analog: 3070mm x 4610mm
Digital: $1900 \mathrm{~mm} \times 4510 \mathrm{~mm}$
METALLIZATION:
Digital Type: Nitrox
Thickness: 10k $\AA 2 k \AA$
Metal 1: AL Si Cu
Thickness: $8 \mathrm{k} \AA \pm 1 \mathrm{k} \AA$
Metal 2: AISiCu
Thickness: 16k $\pm 2 k \AA$
AnalogType: AI
Thickness: 16k $\AA \pm 2 k \AA$

## GLASSIVATION:

Type: Nitride Over Silox Nitride Thickness: $3.5 \mathrm{k} \AA \pm 0.5 \mathrm{k} \AA$ Silox Thickness: $12 \mathrm{k} \AA \pm 1.5 \mathrm{k} \AA$

WORST CASE CURRENT DENSITY:
$1.3 \times 10^{5} \mathrm{~A} / \mathrm{cm}^{2}$

Metallization Mask Layout
HI-574A, HI-674A, HI-774


