## Rochester Electronics Manufactured Components

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceed the OCM data sheet.

## Quality Overview

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF35835
- Class Q Military
- Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
- Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.

## SN74LS195A

## Universal 4-Bit Shift Register

The SN74LS195A is a high speed 4-Bit Shift Register offering typical shift frequencies of 39 MHz . It is useful for a wide variety of register and counting applications. It utilizes the Schottky diode clamped process to achieve high speeds and is fully compatible with all ON Semiconductor TTL products.

- Typical Shift Right Frequency of 39 MHz
- Asynchronous Master Reset
- J, $\overline{\mathrm{K}}$ Inputs to First Stage
- Fully Synchronous Serial or Parallel Data Transfers
- Input Clamp Diodes Limit High Speed Termination Effects


## GUARANTEED OPERATING RANGES

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage | 4.75 | 5.0 | 5.25 | V |
| $\mathrm{~T}_{\mathrm{A}}$ | Operating Ambient <br> Temperature Range | 0 | 25 | 70 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{I}_{\mathrm{OH}}$ | Output Current - High |  |  | -0.4 | mA |
| $\mathrm{I}_{\mathrm{OL}}$ | Output Current - Low |  |  | 8.0 | mA |

ON Semiconductor ${ }^{\text {m }}$
http://onsemi.com

| LOW |
| :---: |
| POWER |
| SCHOTTKY |

POWER SCHOTTKY


PLASTIC N SUFFIX CASE 648


SOIC D SUFFIX CASE 751B

CONNECTION DIAGRAM DIP (TOP VIEW)


NOTE:
The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

| PIN NAMES |  | LOADING (Note a) |  |
| :---: | :---: | :---: | :---: |
|  |  | HIGH | LOW |
| PE | Parallel Enable (Active LOW) Input | 0.5 U.L. | 0.25 U.L |
| $\mathrm{P}_{0}-\mathrm{P}_{3}$ | Parallel Data Inputs | 0.5 U.L. | 0.25 U.L. |
| J | First Stage J (Active HIGH) Input | 0.5 U.L. | 0.25 U.L. |
| $\overline{\mathrm{K}}$ | First Stage K (Active LOW) Input | 0.5 U.L. | 0.25 U.L. |
| CP | Clock (Active HIGH Going Edge) Input | 0.5 U.L. | 0.25 U.L. |
| MR | Master Reset (Active LOW) Input | 0.5 U.L. | 0.25 U.L. |
| $\mathrm{Q}_{0}-\mathrm{Q}_{3}$ | Parallel Outputs | 10 U.L. | 5 U.L. |
| $\bar{Q}_{3}$ | Complementary Last Stage Output | 10 U.L. | 5 U |

NOTES: a) 1 TTL Unit Load (U.L.) $=40 \mu \mathrm{~A}$ HIGH/1. 6 mA LOW.

LOGIC SYMBOL


LOGIC DIAGRAM


## FUNCTIONAL DESCRIPTION

The Logic Diagram and Truth Table indicate the functional characteristics of the LS195A 4-Bit Shift Register. The device is useful in a wide variety of shifting, counting and storage applications. It performs serial, parallel, serial to parallel, or parallel to serial data transfers at very high speeds.

The LS195A has two primary modes of operation, shift right $\left(\mathrm{Q}_{0} \rightarrow \mathrm{Q}_{1}\right)$ and parallel load which are controlled by the state of the Parallel Enable ( $\overline{\mathrm{PE}}$ ) input. When the PE input is HIGH, serial data enters the first flip-flop $Q_{0}$ via the $J$ and $\overline{\mathrm{K}}$ inputs and is shifted one bit in the direction $\mathrm{Q}_{0} \rightarrow \mathrm{Q}_{1} \rightarrow$ $\mathrm{Q}_{2} \rightarrow \mathrm{Q}_{3}$ following each LOW to HIGH clock transition, The $\overline{\mathrm{JK}}$ inputs provide the flexibility of the JK type input for special applications, and the simple D type input for general applications by tying the two pins together. When the PE
input is LOW, the LS195A appears as four common clocked D flip-flops. The data on the parallel inputs $\mathrm{P}_{0}, \mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}$ is transferred to the respective $\mathrm{Q}_{0}, \mathrm{Q}_{1}, \mathrm{Q}_{2}, \mathrm{Q}_{3}$ outputs following the LOW to HIGH clock transition. Shift left operations $\left(\mathrm{Q}_{3} \rightarrow\left[\mathrm{O}_{2}\right)\right.$ can be achieved by tying the $\mathrm{Q}_{\mathrm{n}}$ Outputs to the $\mathrm{P}_{\mathrm{n}-1}$ inputs and holding the $\overline{\mathrm{PE}}$ input LOW. All serial and parallel data transfers are synchronous, occurring after each LOW to HIGH clock transition. Since the LS195A utilizes edge-triggering, there is no restriction on the activity of the $\mathrm{J}, \overline{\mathrm{K}}, \mathrm{P}_{\mathrm{n}}$ and $\overline{\mathrm{PE}}$ inputs for logic operation - except for the set-up and release time requirements.
A LOW on the asynchronous Master Reset (MR) input sets all Q outputs LOW, independent of any other input condition.

MODE SELECT - TRUTH TABLE

| OPERATING MODES | INPUTS |  |  |  |  | OUTPUTS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MR | PE | $J$ | K | $\mathrm{P}_{\mathrm{n}}$ | $Q_{0}$ | $Q_{1}$ | $Q_{2}$ | $Q_{3}$ | $\bar{Q}_{3}$ |
| Asynchronous Reset | L | X | X | X | X | L | L | L | L | H |
| Shift, Set First Stage | H | h | h | h | X | H | $\mathrm{q}_{0}$ | $\mathrm{q}_{1}$ | $\mathrm{q}_{2}$ | $\overline{\mathrm{q}}_{2}$ |
| Shift, Reset First | H | h | 1 | 1 | X | L | $\mathrm{q}_{0}$ | $\mathrm{q}_{1}$ | $\mathrm{q}_{2}$ | $\overline{\mathrm{q}}_{2}$ |
| Shift, Toggle First Stage | H | h | h | 1 | X | $\bar{q}_{0}$ | $\mathrm{q}_{0}$ | $\mathrm{q}_{1}$ | $\mathrm{q}_{2}$ | $\overline{\mathrm{q}}_{2}$ |
| Shift, Retain First Stage | H | h | 1 | h | X | $\mathrm{q}_{0}$ | $\mathrm{q}_{0}$ | $\mathrm{q}_{1}$ | $\mathrm{q}_{2}$ | $\overline{\mathrm{q}}_{2}$ |
| Parallel Load | H | 1 | X | X | $\mathrm{p}_{\mathrm{n}}$ | $\mathrm{p}_{0}$ | $\mathrm{p}_{1}$ | $\mathrm{p}_{2}$ | $\mathrm{p}_{3}$ | $\overline{\mathrm{p}}_{3}$ |

L = LOW voltage levels
$\mathrm{H}=\mathrm{HIGH}$ voltage levels
X = Don't Care
I = LOW voltage level one set-up time prior to the LOW to HIGH clock transition.
$h=$ HIGH voltage level one set-up time prior to the LOW to HIGH clock transition.
$\mathrm{p}_{\mathrm{n}}\left(\mathrm{q}_{\mathrm{n}}\right)=$ Lower case letters indicate the state of the referenced input (or output) one set-up time prior to the LOW to HIGH clock transition.

DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

| Symbol | Parameter |  | Limits |  |  | Test Conditions |
| :--- | :--- | :---: | :---: | :---: | :---: | :--- | :--- |

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.
AC CHARACTERISTICS $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$


AC SETUP REQUIREMENTS $\left(T_{A}=25^{\circ} \mathrm{C}\right)$

| Symbol | Parameter | $\begin{array}{\|l\|} \hline \operatorname{Min} \\ \hline \end{array}$ | $\begin{aligned} & \hline \text { Limits } \\ & \hline \text { Typ } \end{aligned}$ | Max | Unit | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tw | CP Clock Pulse Width | 16 | $\checkmark$ |  | ns | $\mathrm{V}_{C C}=5.0 \mathrm{~V}$ |
| $\mathrm{t}_{\mathrm{W}}$ | MR Pulse Width | 12 | - |  | ns |  |
| $\mathrm{t}_{\mathrm{s}}$ | PE Setup Time | 25 |  |  | ns |  |
| $\mathrm{t}_{\text {s }}$ | Data Setup Time | 15 |  |  | ns |  |
| $\mathrm{t}_{\text {rec }}$ | Recovery Time S | 25 |  |  | ns |  |
| $\mathrm{t}_{\text {rel }}$ | PE Release Time |  |  | 10 | ns |  |
| $t_{\text {h }}$ | Data Hold Time | 0 |  |  | ns |  |

## DEFINITIONS OF TERMS

$\operatorname{SETUP} \operatorname{TIME}\left(\mathrm{t}_{\mathrm{s}}\right)$-is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.
HOLD TIME ( $\mathrm{t}_{\mathrm{h}}$ ) - is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure
continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.
RECOVERY TIME ( $\mathrm{t}_{\text {rec }}$ ) - is defined as the minimum time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognize and transfer HIGH Data to the Q outputs.

## AC WAVEFORMS

The shaded areas indicate when the input is permitted to change for predictable output performance.


Figure 1. Clock to Output Delays and Clock Pulse Width


CONDITIONS: $\mathrm{PE}=\mathrm{L}$
$P O=P_{1}=P_{2}=P_{3}=H$
Figure 2. Master Reset Pulse Width, Master Reset to Output Delay and Master Reset to Clock Recovery Time


Figure 3. Setup ( $\mathrm{t}_{\mathrm{s}}$ ) and Hold ( $\mathrm{t}_{\mathrm{h}}$ ) Time for Serial Data (J \& K) and Parallel Data ( $\mathrm{P}_{0}, \mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}$ )


CONDITIONS: $\overline{M R}=\mathrm{H}$
${ }^{*} \mathrm{Q}_{0}$ STATE WILL BE DETERMINED BY J AND K INPUTS.
Figure 4. Setup ( $\mathrm{t}_{\mathrm{s}}$ ) and Hold ( $\mathrm{t}_{\mathrm{h}}$ ) Time for PE Input

## PACKAGE DIMENSIONS

N SUFFIX
PLASTIC PACKAGE
CASE 648-08
ISSUE R


## SN74LS195A

## D SUFFIX

PLASTIC SOIC PACKAGE
CASE 751B-05
ISSUE J


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