16K-Bit Microwire Serial EEPROM

FEATURES

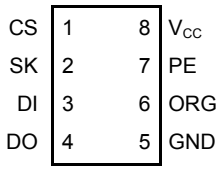
- **High speed operation: 3MHz**
- **Low power CMOS technology**
- **1.8 to 5.5 volt operation**
- **Selectable x8 or x16 memory organization**
- **Self-timed write cycle with auto-clear**
- **Hardware and software write protection**
- **Power-up inadvertant write protection**
- **Sequential read**
- **Program enable (PE) pin**
- **1,000,000 Program/erase cycles**
- **100 year data retention**
- **Commercial, industrial and automotive temperature ranges**
- **RoHS-compliant packages**

DESCRIPTION

The CAT93C86 is a 16K-bit Serial EEPROM memory device which is configured as either registers of 16 bits (ORG pin at V_{CC}) or 8 bits (ORG pin at GND). Each register can be written (or read) serially by using the DI (or DO) pin. The CAT93C86 is manufactured using Catalyst's advanced CMOS EEPROM floating gate technology. The device is designed to endure 1,000,000 program/erase cycles and has a data retention of 100 years. The device is available in 8-pin DIP, 8-pin SOIC and 8-pad TDFN packages.

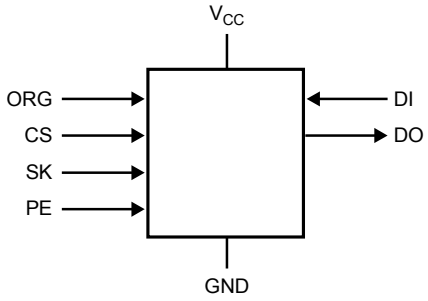
PIN CONFIGURATION

PDIP (L)
SOIC (V, X)
TDFN (ZD4)



SOIC (W)

FUNCTIONAL SYMBOL



PIN FUNCTION (1)

Pin Name	Function
CS	Chip Select
SK	Clock Input
DI	Serial Data Input
DO	Serial Data Output
V_{CC}	Power Supply
GND	Ground
ORG	Memory Organization
PE	Program Enable

Notes:

(1) When the ORG pin is connected to V_{CC}, x16 organization is selected. When it is connected to ground, x8 pin is selected. If the ORG pin is left unconnected, then an internal pull-up device will select the x16 organization.

For Ordering Information details, see page 12.

ABSOLUTE MAXIMUM RATINGS [1]

Parameters	Ratings	Units
Temperature Under Bias	–55 to +125	ºC
Storage Temperature	–65 to 150	ºC
Voltage on any Pin with Respect to Ground[2]	-2.0 to +V_{CC} +2.0	V
V_{CC} with Respect to Ground	-2.0 to +7.0	V
Package Power Dissipation Capability (T_A = 25ºC)	1.0	W
Lead Soldering Temperature (10 seconds)	300	ºC
Output Short Circuit Current[3]	100	mA

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Reference Test Method	Min	Units
N_{END}[4]	Endurance	MIL-STD-883, Test Method 1033	1,000,000	Cycles/Byte
T_{DR}[4]	Data Retention	MIL-STD-883, Test Method 1008	100	Years
V_{ZAP}[4]	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000	V
I_{LTH}[4][5]	Latch-Up	JEDEC Standard 17	100	mA

D.C. OPERATING CHARACTERISTICS

V_{CC} = +1.8V to +5.5V unless otherwise specified.

Symbol	Parameter	Test Conditions	Min	Typ	Max	Units
I_{CC1}	Power Supply Current (Write)	f_{SK} = 1MHz; V_{CC} = 5.0V			3	mA
I_{CC2}	Power Supply Current (Read)	f_{SK} = 1MHz; V_{CC} = 5.0V			500	µA
I_{SB1}	Power Supply Current (Standby) (x8 Mode)	CS = 0V ORG = GND			10	µA
I_{SB2}	Power Supply Current (Standby) (x16Mode)	CS = 0V ORG = Float or V_{CC}		0	10	µA
I_{LI}	Input Leakage Current	V_{IN} = 0V to V_{CC}			1	µA
I_{LO}	Output Leakage Current (Including ORG pin)	V_{OUT} = 0V to V_{CC}, CS = 0V			1	µA
V_{IL1}	Input Low Voltage	4.5V ≤ V_{CC} < 5.5V	-0.1		0.8	V
V_{IH1}	Input High Voltage	4.5V ≤ V_{CC} < 5.5V	2		V_{CC} + 1	V
V_{IL2}	Input Low Voltage	1.8V ≤ V_{CC} < 4.5V	0		V_{CC} x 0.2	V
V_{IH2}	Input High Voltage	1.8V ≤ V_{CC} < 4.5V	V_{CC} x 0.7		V_{CC} + 1	V
V_{OL1}	Output Low Voltage	4.5V ≤ V_{CC} < 5.5V; I_{OL} = 2.1mA			0.4	V
V_{OH1}	Output High Voltage	4.5V ≤ V_{CC} < 5.5V; I_{OH} = -400µA	2.4			V
V_{OL2}	Output Low Voltage	1.8V ≤ V_{CC} < 4.5V; I_{OL} = 1mA			0.2	V
V_{OH2}	Output High Voltage	1.8V ≤ V_{CC} < 4.5V; I_{OH} = -100µA	V_{CC} - 0.2			V

Notes:

(1) Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

(2) The minimum DC input voltage is –0.5V. During transitions, inputs may undershoot to –2.0V for periods of less than 20ns. Maximum DC voltage on output pins is V_{CC} +0.5V, which may overshoot to V_{CC} +2.0V for periods of less than 20ns.

(3) Output shorted for no more than one second. No more than one output shorted at a time.

(4) These parameters are tested initially and after a design or process change that affects the parameter.

(5) Latch-up protection is provided for stresses up to 100 mA pn address and data pins from –1V to V_{CC} +1V.

PIN CAPACITANCE [1]

Symbol	Test	Conditions	Min	Typ	Max	Units
C_{OUT}	Output Capacitance (DO)	V_{OUT} = 0V			5	pF
C_{IN}	Input Capacitance (CS, SK, DI, ORG)	V_{IN} = 0V			5	pF

POWER-UP TIMING [1][2]

Symbol	Parameter	Max	Units
t_{PUR}	Power-up to Read Operation	1	ms
t_{PUW}	Power-up to Write Operation	1	ms

A.C. TEST CONDITIONS

Input Rise and Fall Times	≤ 50ns	
Input Pulse Voltages	0.4V to 2.4V	$4.5V \le V_{CC} \le 5.5V$
Timing Reference Voltages	0.8V, 2.0V	$4.5V \le V_{CC} \le 5.5V$
Input Pulse Voltages	$0.2V_{CC}$ to $0.7V_{CC}$	$1.8V \le V_{CC} \le 4.5V$
Timing Reference Voltages	$0.5V_{CC}$	$1.8V \le V_{CC} \le 4.5V$

A.C. CHARACTERISTICS

Symbol	Parameter	Test Conditions	V_{CC} = 1.8V-5.5V		V_{CC} = 2.5V-5.5V		V_{CC} = 4.5V-5.5V		Units
			Min	Max	Min	Max	Min	Max	
t_{CSS}	CS Setup Time		200		100		50		ns
t_{CSH}	CS Hold Time		0		0		0		ns
t_{DIS}	DI Setup Time		200		100		50		ns
t_{DIH}	DI Hold Time		200		100		50		ns
t_{PD1}	Output Delay to 1			1		0.5		0.15	µs
t_{PD0}	Output Delay to 0	C_L = 100pF[3]		1		0.5		0.15	µs
t_{HZ}[1]	Output Delay to High-Z			400		200		100	ns
t_{EW}	Program/Erase Pulse Width			5		5		5	ms
t_{CSMIN}	Minimum CS Low Time		1		0.5		0.15		µs
t_{SKHI}	Minimum SK High Time		1		0.5		0.15		µs
t_{SKLOW}	Minimum SK Low Time		1		0.5		0.15		µs
t_{SV}	Output Delay to Status Valid			1		0.5		0.1	µs
SK_{MAX}	Maximum Clock Frequency		DC	500	DC	1000	DC	3000	kHz

Notes:

(1) These parameters are tested initially and after a design or process change that affects the parameter.

(2) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated.

(3) The input levels and timing reference points are shown in the “AC Test Conditions” table.

INSTRUCTION SET

Instruction	Start Bit	Opcode	Address		Data		Comments
			x8	x16	x8	x16	
READ	1	10	A10-A0	A9-A0			Read Address AN– A0
ERASE	1	11	A10-A0	A9-A0			Clear Address AN– A0
WRITE	1	01	A10-A0	A9-A0	D7-D0	D15-D0	Write Address AN– A0
EWEN	1	00	11XXXXXXXXX	11XXXXXXXX			Write Enable
EWDS	1	00	00XXXXXXXXX	00XXXXXXXX			Write Disable
ERAL	1	00	10XXXXXXXXX	10XXXXXXXX			Clear All Addresses
WRAL	1	00	01XXXXXXXXX	01XXXXXXXX	D7-D0	D15-D0	Write All Addresses

DEVICE OPERATION

The CAT93C86 is a 16,384-bit nonvolatile memory intended for use with industry standard microprocessors. The CAT93C86 can be organized as either registers of 16 bits or 8 bits. When organized as X16, seven 13-bit instructions control the reading, writing and erase operations of the device. When organized as X8, seven 14-bit instructions control the reading, writing and erase operations of the device. The CAT93C86 operates on a single power supply and will generate on chip, the high voltage required during any write operation.

Instructions, addresses, and write data are clocked into the DI pin on the rising edge of the clock (SK). The DO pin is normally in a high impedance state except when reading data from the device, or when checking the ready/busy status after a write operation.

The ready/busy status can be determined after the start of a write operation by selecting the device (CS high) and polling the DO pin; DO low indicates that the write operation is not completed, while DO high indicates that the device is ready for the next instruction. If necessary, the DO pin may be placed back into a high impedance state during chip select by shifting a dummy "1" into the DI pin. The DO pin will enter the high impedance state on the falling edge of the clock (SK). Placing the DO pin into the high impedance state is recommended in applications where the DI pin and the DO pin are to be tied together to form a common DI/O pin.

The format for all instructions sent to the device is a logical "1" start bit, a 2-bit (or 4-bit) opcode, 10-bit address (an additional bit when organized X8) and for write operations a 16-bit data field (8-bit for X8 organizations).

Note: The Write, Erase, Write all and Erase all instructions require PE=1. If PE is left floating, 93C86 is in Program Enabled mode. For Write Enable and Write Disable instruction PE = don't care.

Read

Upon receiving a READ command and an address (clocked into the DI pin), the DO pin of the CAT93C86 will come out of the high impedance state and, after sending an initial dummy zero bit, will begin shifting out the data addressed (MSB first). The output data bits will toggle on the rising edge of the SK clock and are stable after the specified time delay (t_{PD0} or t_{PD1}).

After the initial data word has been shifted out and CS remains asserted with the SK clock continuing to toggle, the device will automatically increment to the next address and shift out the next data word in a sequential READ mode. As long as CS is continuously asserted and SK continues to toggle, the device will keep incrementing to the next address automatically until it reaches to the end of the address space, then loops back to address 0. In the sequential READ mode, only the initial data word is preceeded by a dummy zero bit. All subsequent data words will follow without a dummy zero bit.

Write

After receiving a WRITE command, address and the data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear and data store cycle of the memory location specified in the instruction. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C86 can be determined by selecting the device and polling the DO pin. Since this device features Auto-Clear before write, it is NOT necessary to erase a memory location before it is written into.

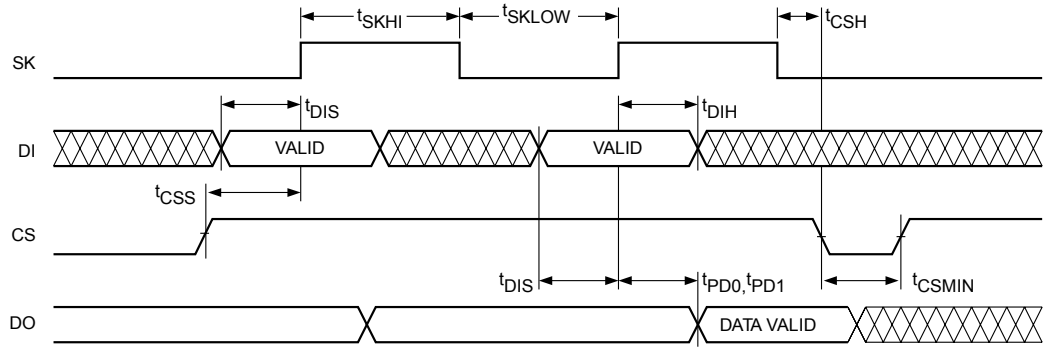


Figure 1. Sychronous Data Timing

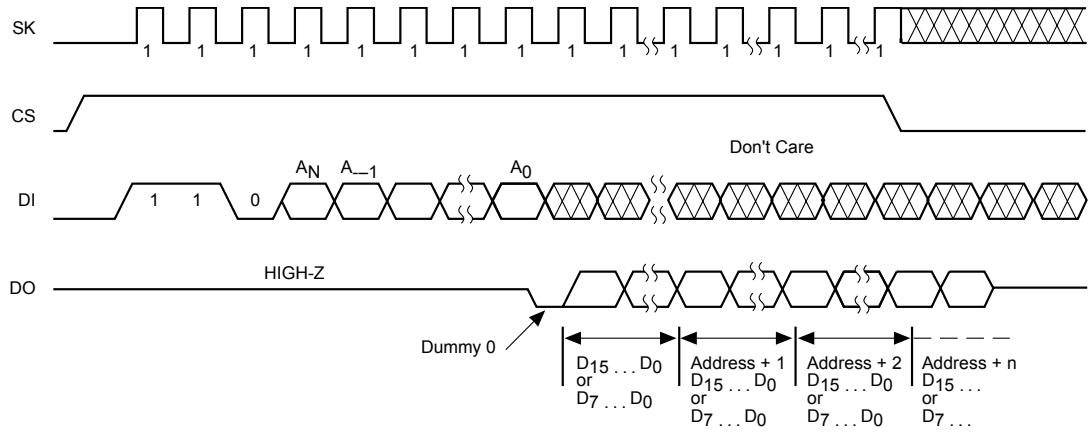


Figure 2. Read Instruction Timing

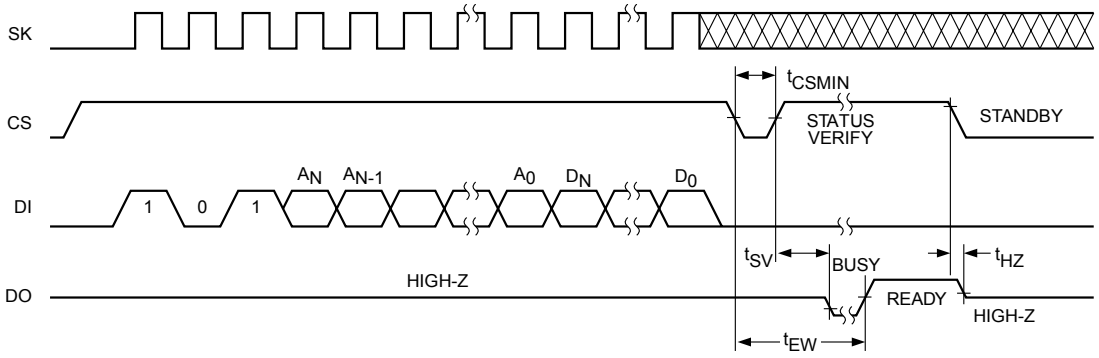


Figure 3. Write Instruction Timing

Erase

Upon receiving an ERASE command and address, the CS (Chip Select) pin must be deasserted for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear cycle of the selected memory location. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C86 can be determined by selecting the device and polling the DO pin. Once cleared, the content of a cleared location returns to a logical “1” state.

Erase/Write Enable and Disable

The CAT93C86 powers up in the write disable state. Any writing after power-up or after an EWDS (write disable) instruction must first be preceded by the EWEN (write enable) instruction. Once the write instruction is enabled, it will remain enabled until power to the device is removed, or the EWDS instruction is sent. The EWDS instruction can be used to disable all CAT93C86 write and clear instructions, and will prevent any accidental writing or clearing of the device. Data can be read normally from the device regardless of the write enable/disable status.

Erase All

Upon receiving an ERAL command, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear cycle of all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C86 can be determined by selecting the device and polling the DO pin. Once cleared, the contents of all memory bits return to a logical “1” state.

Write All

Upon receiving a WRAL command and data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking data write to all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93C86 can be determined by selecting the device and polling the DO pin. It is not necessary for all memory locations to be cleared before the WRAL command is executed.

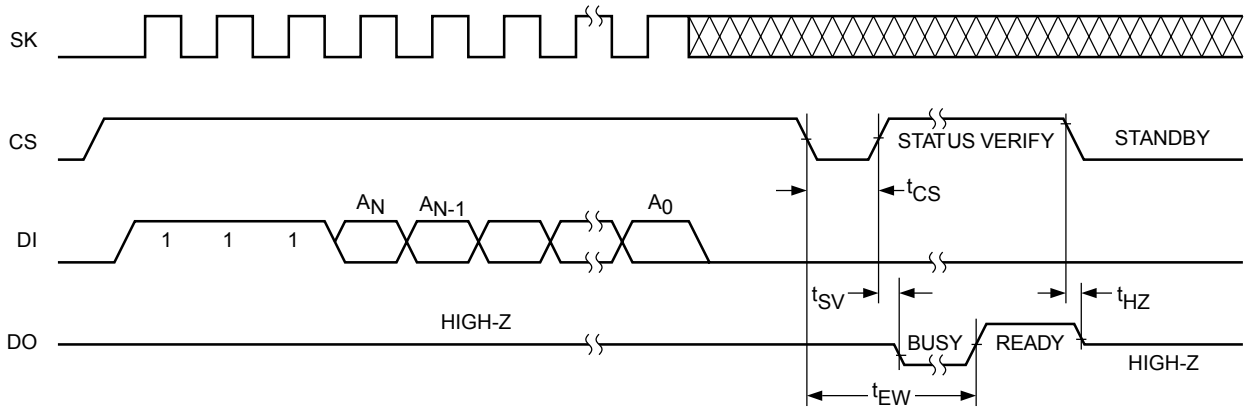
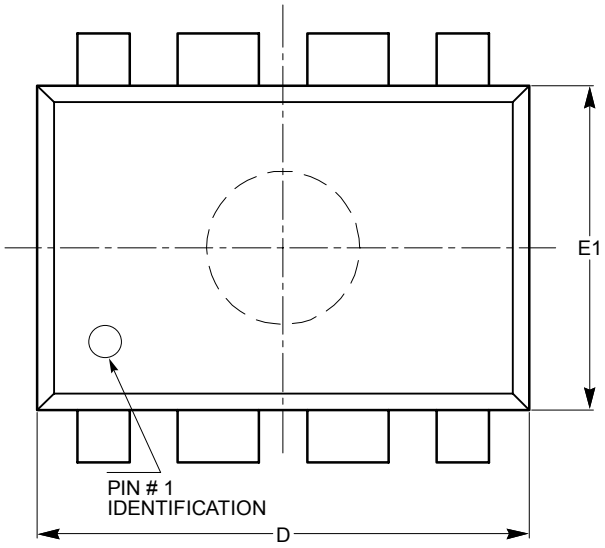


Figure 4. Erase Instruction Timing

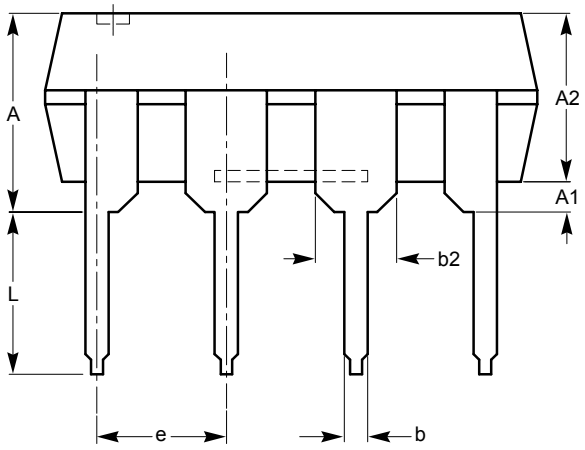
PACKAGE OUTLINE DRAWINGS

PDIP 8-Lead 300mils (L) (1)(2)

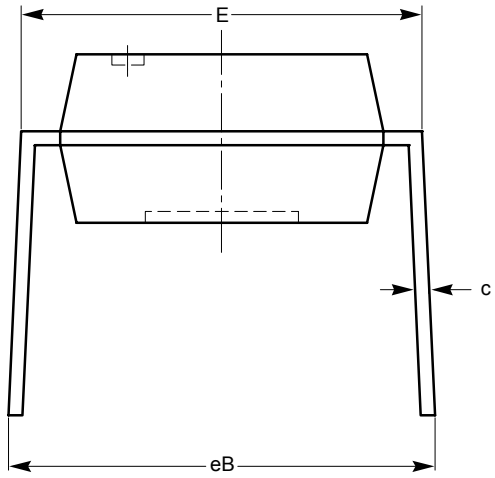


TOP VIEW

SYMBOL	MIN	NOM	MAX
A			5.33
A1	0.38		
A2	2.92	3.30	4.95
b	0.36	0.46	0.56
b2	1.14	1.52	1.78
c	0.20	0.25	0.36
D	9.02	9.27	10.16
E	7.62	7.87	8.25
e		2.54 BSC	
E1	6.10	6.35	7.11
eB	7.87		10.92
L	2.92	3.30	3.80



SIDE VIEW



END VIEW

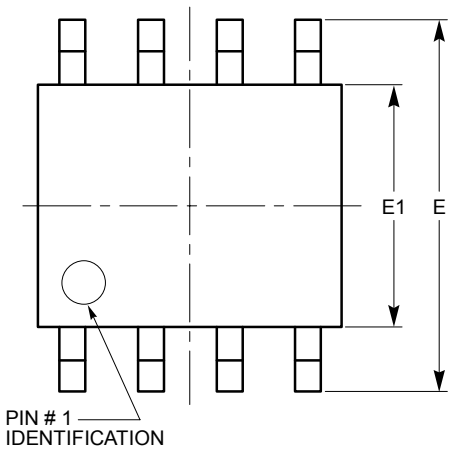
For current Tape and Reel information, download the PDF file from: http://www.catsemi.com/documents/tapeandreel.pdf.

Notes:

(1) All dimensions are in millimeters. Angles in degrees.

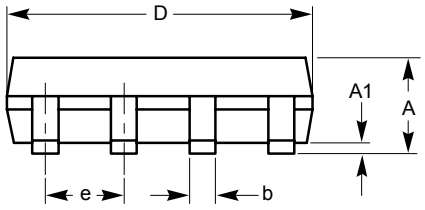
(2) Complies with JEDEC standard MS-001.

SOIC 8-Lead 150mils (V) [(1)(2)]

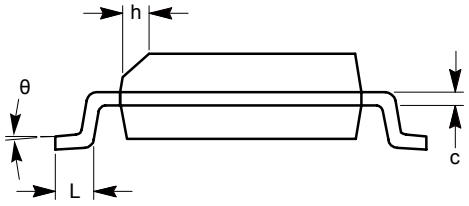


TOP VIEW

SYMBOL	MIN	NOM	MAX
A	1.35		1.75
A1	0.10		0.25
b	0.33		0.51
c	0.19		0.25
D	4.80		5.00
E	5.80		6.20
E1	3.80		4.00
e		1.27 BSC	
h	0.25		0.50
L	0.40		1.27
θ	0º		8º



SIDE VIEW



END VIEW

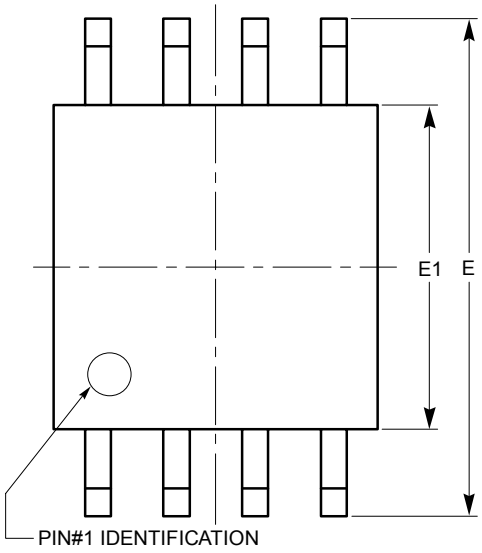
For current Tape and Reel information, download the PDF file from: http://www.catsemi.com/documents/tapeandreel.pdf.

Notes:

(1) All dimensions are in millimeters. Angles in degrees.

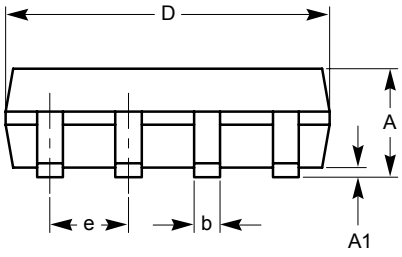
(2) Complies with JEDEC standard MS-012.

SOIC 8-Lead EIAJ 208mils (X) [1][2]

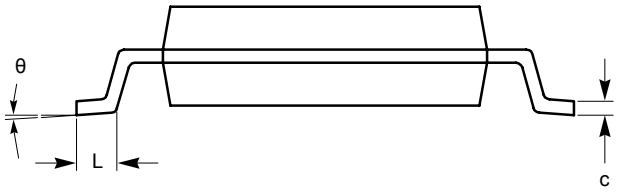


TOP VIEW

SYMBOL	MIN	NOM	MAX
A			2.03
A1	0.05		0.25
b	0.36		0.48
c	0.19		0.25
D	5.13		5.33
E	7.75		8.26
E1	5.13		5.38
e	1.27 BSC		
L	0.51		0.76
θ	0º		8º



SIDE VIEW



END VIEW

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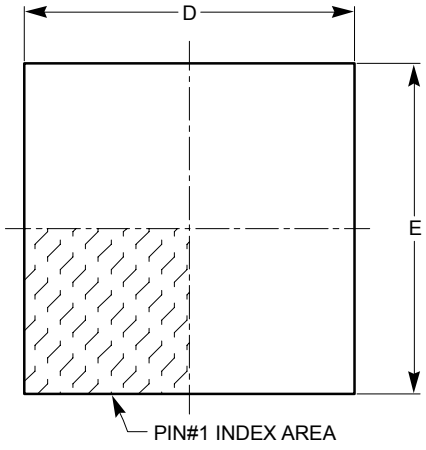
For current Tape and Reel information, download the PDF file from: http://www.catsemi.com/documents/tapeandreel.pdf.

Notes:

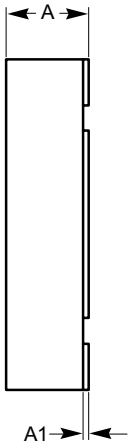
(1) All dimensions are in millimeters. Angles in degrees.

(2) Complies with EIAJ standard EDR-7320.

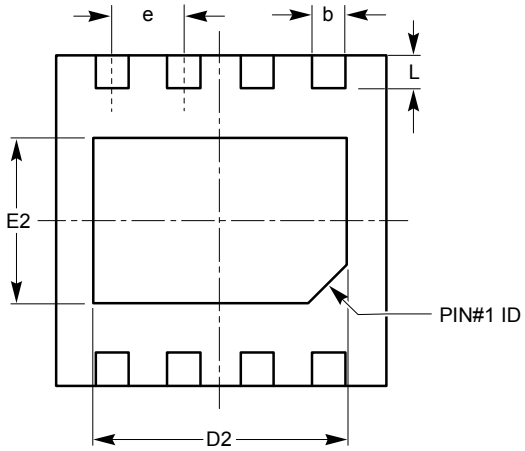
TDFN 8-Pad 3 x 3mm (ZD4) (1)(2)



TOP VIEW

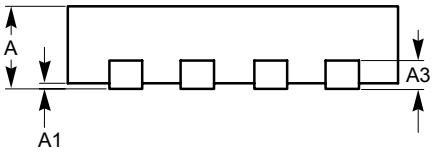


SIDE VIEW



BOTTOM VIEW

SYMBOL	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3		0.20 REF	
b	0.23	0.30	0.37
D	2.90	3.00	3.10
D2	2.20	—	2.50
E	2.90	3.00	3.10
E2	1.40	—	1.80
e		0.65 TYP	
L	0.20	0.30	0.40

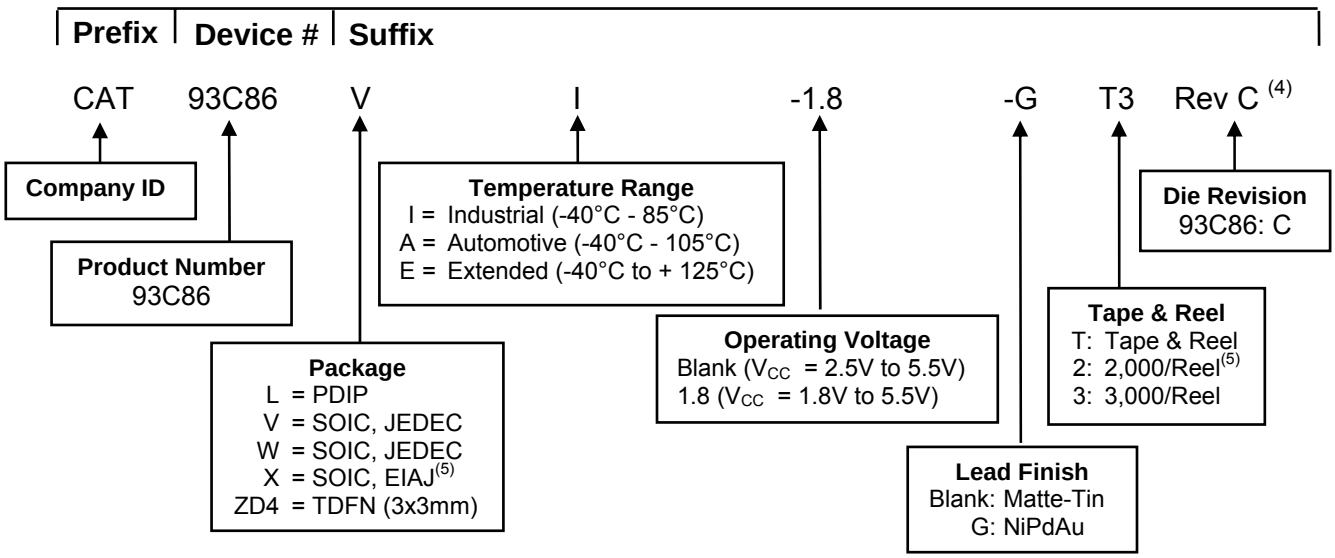


FRONT VIEW

For current Tape and Reel information, download the PDF file from: http://www.catsemi.com/documents/tapeandreel.pdf.

Notes:
(1) All dimensions are in millimeters. Angles in degrees.
(2) Complies with JEDEC standard MO-229.

EXAMPLE OF ORDERING INFORMATION



For Product Top Mark Codes, click here:
http://www.catsemi.com/techsupport/producttopmark.asp

Notes:

(1) All packages are RoHS-compliant (Lead-free, Halogen-free).

(2) The standard lead finish is NiPdAu.

(3) The device used in the above example is a 93C86VI-GT3 (SOIC, Industrial Temperature, 1.8V to 5.5V, NiPdAu, Tape & Reel, 3,000/Reel)

(4) Product die revision letter is marked on top of the package as a suffix to the production date code (e.g., AYWWE.) For additional information, please contact your Catalyst sales office.

(5) For SOIC, EIAJ (X) package the standard lead finish is Matte-Tin. This package is available in 2,000/Reel, i.e., CAT93C86XI-T2.

(6) For additional package and temperature options, please contact your nearest Catalyst Semiconductor Sales office.

REVISION HISTORY

Date	Rev.	Comments
14-May-04	L	New Data Sheet Created From CAT93C46/56/57/66/86. Parts CAT93C56, CAT93C56, CAT93C57, CAT93C66, CAT93C76 and CAT93C86 have been separated into single data sheets Add Die Revision ID Letter Update Features Update Description Update Pin Condition Add Functional Diagram Update Pin Function Update D.C. Operating Characteristics Update Pin Capacitance Update Instruction Set Update Device Operation Update Ordering Information
10-Aug-04	M	Added TDFN Package pin out
03-Sep-04	N	Minor changes
13-Oct-06	O	Update Features Update Pin Configuration Update Pin Functions Update D.C. Operating Characteristics (VCC Range) Update A.C. Characteristics (VCC Range) Update Ordering Information
21-May-08	P	Update Package Outline Drawings Add Top Mark Code Link Update Document Layout

Catalyst Semiconductor, Inc.
Corporate Headquarters
2975 Stender Way
Santa Clara, CA 95054
Phone: 408.542.1000
Fax: 408.542.1200
www.catsemi.com

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