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## LMH6622 Dual Wideband, Low Noise, 160MHz, Operational **Amplifiers General Description**

The LMH6622 is a dual high speed voltage feedback operational amplifier specifically optimized for low noise. A voltage noise specification of  $1.6nV/\sqrt{Hz}$  , a current noise specification 1.5pA/ $\sqrt{\text{Hz}}$ , a bandwidth of 160MHz, and a harmonic distortion specification that exceeds 90dBc combine to make the LMH6622 an ideal choice for the receive channel amplifier in ADSL, VDSL, or other xDSL designs. The LMH6622 operates from ±2.5V to ±6V in dual supply mode and from +5V to +12V in single supply configuration. The LMH6622 is stable for  $A_V \ge 2$  or  $A_V \le -1$ . The fabrication of the LMH6622 on National Semiconductor's advanced VIP10 process enables excellent (160MHz) bandwidth at a current consumption of only 4.3mA/amplifier. Packages for this dual amplifier are the 8-lead SOIC and the 8-lead MSOP.

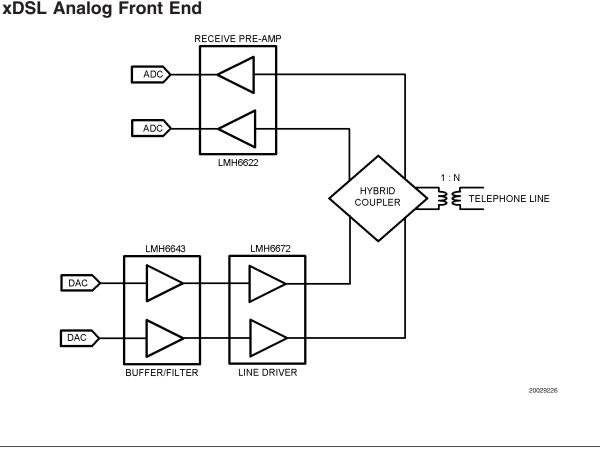
#### Features

 $V_{S} = \pm 6V$ ,  $T_{A} = 25^{\circ}C$ , Typical values unless specified • Bandwidth  $(A_V = +2)$ 160MHz ±2.5V to ±6V +5V to +12 Supply Voltage Range Slew rate 85V/µs Supply current 4.3mA/amp -4.75V to +5.7V

- Input common mode voltage
- ±4.6V • Output Voltage Swing ( $R_L = 100\Omega$ ) 1.6nV/ √Hz Input voltage noise
- Input current noise 1.5pA/ √Hz
- 90mA Linear output current
- Excellent harmonic distortion

### Applications

- xDSL receiver
- Low noise instrumentation front end
- Ultrasound preamp
- Active filters
- Cellphone basestation



90dBc

#### Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

ESD Tolerance	
Human Body Model	2kV (Note 2)
Machine Model	200V (Note 2)
V <sub>IN</sub> Differential	±1.2V
Supply Voltage (V <sup>+</sup> - V <sup>-</sup> )	13.2V
Voltage at Input Pins	$V^+$ +0.5V, $V^-$ -0.5V
Soldering Information	
Infrared or Convection (20 sec)	235°C

Wave Soldering (10 sec)	260°C
Storage Temperature Range	–65°C to +150°C
Junction Temperature (Note 4)	+150°C

## Operating Ratings (Note 1)

Supply Voltage (V <sup>+</sup> - V <sup>-</sup> )	±2.25V to ±6V
Junction Temperature Range	–40°C to +85°C
(Note 3), (Note 4)	
Package Thermal Resistance (Note 4)	$(\theta_{JA})$
8-pin SOIC	166°C/W
8-pin MSOP	211°C/W

## **±6V Electrical Characteristics**

Unless otherwise specified,  $T_J = 25^{\circ}C$ ,  $V^+ = 6V$ ,  $V^- = -6V$ ,  $V_{CM} = 0V$ ,  $A_V = +2$ ,  $R_F = 500\Omega$ ,  $R_L = 100\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
Dynamic	Performance		(11010-0)	(14010-0)		
f <sub>CL</sub>	-3dB BW	$V_{O} = 200 \text{mV}_{PP}$		160		MHz
BW <sub>0.1dB</sub>	0.1dB Gain Flatness	$V_{\rm O} = 200 \text{mV}_{\rm PP}$		30		MHz
SR	Slew Rate (Note 8)	$V_{O} = 2V_{PP}$		85		V/µs
TS	Settling Time	$V_{O} = 2V_{PP}$ to ±0.1%		40		1,40
		$V_{O} = 2V_{PP}$ to ±1.0%		35		ns
Tr	Rise Time	$V_{O} = 0.2V$ Step, 10% to 90%		2.3		ns
Tf	Fall Time	$V_{\rm O} = 0.2V$ Step, 10% to 90%		2.3		ns
	and Noise Response			2.0		110
e <sub>n</sub>	Input Referred Voltage Noise	f = 100kHz		1.6		nV/√H:
i <sub>n</sub>	Input Referred Current Noise	f = 100kHz		1.5		pA/√H
DG	Differential Gain	$R_{L} = 150\Omega, R_{F} = 470\Omega, NTSC$		0.03		%
DP	Differential Phase	$R_{\rm L} = 150\Omega, R_{\rm F} = 470\Omega, NTSC$		0.03		deg
HD2	2 <sup>nd</sup> Harmonic Distortion	$f_c = 1MHz, V_O = 2V_{PP}, R_L = 100\Omega$		-90		- dBc
		$f_c = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega$		-100		
HD3	3 <sup>rd</sup> Harmonic Distortion	$f_{c} = 1MHz, V_{O} = 2V_{PP}, R_{L} = 100\Omega$		-94		
		$f_c = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega$		-100		- dBc
MTPR	Upstream	$V_{O} = 0.6 V_{BMS}$ , 26kHz to 132kHz		-78		
		(see test circuit 5)				
	Downstream	$V_{O} = 0.6 V_{RMS}$ , 144kHz to 1.1MHz		-70		dBc
		(see test circuit 5)				
Input Cha	racteristics					
V <sub>OS</sub>	Input Offset Voltage	$V_{CM} = 0V$	-1.2	+0.2	+1.2	mV
			-2		+2	
TC V <sub>OS</sub>	Input Offset Average Drift	V <sub>CM</sub> = 0V (Note 7)		-2.5		µV/°C
l <sub>os</sub>	Input Offset Current	$V_{CM} = 0V$	-1	-0.04	1	μΑ
			-1.5		1.5	
I <sub>B</sub>	Input Bias Current	$V_{CM} = 0V$		4.7	10	μΑ
					15	
R <sub>IN</sub>	Input Resistance	Common Mode		17		MΩ
		Differential Mode		12		kΩ
CIN	Input Capacitance	Common Mode		0.9		pF
		Differential Mode		1.0		pF

# LMH6622

## ±6V Electrical Characteristics (Continued)

Unless otherwise specified, $T_J = 25^{\circ}C$ , $V^+ = 6V$ , $V^- = -6V$ , $V_{CM} = 0V$ , $A_V = +2$ , $R_F = 500\Omega$ , $R_L = 100\Omega$ . Boldface limits apply
at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
CMVR	Input Common Mode Voltage	CMRR ≥ 60dB		-4.75	-4.5	
	Range		5.5	+5.7		V
CMRR	Common-Mode Rejection Ratio	Input Referred,	80	100		dB
		$V_{CM} = -4.2$ to +5.2V	75			
Transfer C	haracteristics		-1			
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 4V_{PP}$	74	83		dB
			70			
X <sub>t</sub>	Crosstalk	f = 1MHz		-75		dB
Output Ch	aracteristics	•			·	
Vo	Output Swing	No Load, Positive Swing	4.8	5.2		
			4.6			
		No Load, Negative Swing		-5.0	-4.6	
					-4.4	V
		$R_L = 100\Omega$ , Positive Swing	4.0	4.6		v
			3.8			
		$R_L = 100\Omega$ , Negative Swing		-4.6	-4	
					-3.8	
Ro	Output Impedance	f = 1MHz		0.08		Ω
I <sub>sc</sub>	Output Short Circuit Current	Sourcing to Ground	100	135		
		$\Delta V_{IN} = 200 \text{mV}$ (Note 3), (Note 9)				mA
		Sinking to Ground	100	130		IIIA
		$\Delta V_{IN} = -200 \text{mV}$ (Note 3), (Note 9)				
I <sub>OUT</sub>	Output Current	Sourcing, $V_{O} = +4.3V$		90		mA
		Sinking, $V_{O} = -4.3V$				
Power Sup	oply				,	
+PSRR	Positive Power Supply	Input Referred,	80	95		
	Rejection Ratio	$V_{\rm S} = +5V$ to $+6V$	74			dB
-PSRR	Negative Power Supply	Input Referred,	75	90		чD
	Rejection Ratio	$V_{\rm S} = -5V$ to $-6V$	69			
I <sub>S</sub>	Supply Current (per amplifier)	No Load		4.3	6	mA
					6.5	

## ±2.5V Electrical Characteristics

Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}C$ ,  $V^+ = 2.5V$ ,  $V^- = -2.5V$ ,  $V_{CM} = 0V$ ,  $A_V = +2$ ,  $R_F = 500\Omega$ ,  $R_L = 100\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
Dynamic I	Performance					
f <sub>CL</sub>	–3dB BW	$V_{O} = 200 \text{mV}_{PP}$		150		MHz
BW <sub>0.1dB</sub>	0.1dB Gain Flatness	$V_{O} = 200 \text{mV}_{PP}$		20		MHz
SR	Slew Rate (Note 8)	$V_{O} = 2V_{PP}$		80		V/µs
Ts	Settling Time	$V_{O} = 2V_{PP}$ to ±0.1%		45		
		$V_{O} = 2V_{PP}$ to ±1.0%		40		ns
T <sub>r</sub>	Rise Time	V <sub>O</sub> = 0.2V Step, 10% to 90%		2.5		ns
T <sub>f</sub>	Fall Time	V <sub>O</sub> = 0.2V Step, 10% to 90%		2.5		ns
Distortion	and Noise Response	•	·		•	
e <sub>n</sub>	Input Referred Voltage Noise	f = 100kHz		1.7		nV/√Hz
i <sub>n</sub>	Input Referred Current Noise	f = 100kHz		1.5		pA/ √Hz

## ±2.5V Electrical Characteristics (Continued)

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$ , $V^+ = 2.5V$ , $V^- = -2.5V$ , $V_{CM} = 0V$ , $A_V = +2$ , $R_F = 500\Omega$ ,
$R_L = 100\Omega$ . Boldface limits apply at the temperature extremes.

Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
2 <sup>nd</sup> Harmonic Distortion	$fc = 1MHz, V_{\Omega} = 2V_{PP}, R_{I} = 100\Omega$		-88	. ,	
			-98		dBc
3 <sup>rd</sup> Harmonic Distortion			-92		
					dBc
LInstream					
	(see test circuit 5)				dBc
Downstream	$V_{O} = 0.4V_{RMS}$ , 144kHz to 1.1MHz (see test circuit 5)		-68		
racteristics					
Input Offset Voltage	$V_{CM} = 0V$	-1.5	+0.3	+1.5	
		-2.3		+2.3	mV
Input Offset Average Drift	V <sub>CM</sub> = 0V (Note 7)		-2.5		µV/°C
Input Offset Current	V <sub>CM</sub> = 0V	-1.5 -2.5	+0.01	1.5 2.5	μΑ
Input Bias Current	V <sub>CM</sub> = 0V		4.6	10	μΑ
				15	
Input Resistance	Common Mode		17		MΩ
	Differential Mode		12		kΩ
Input Capacitance	Common Mode		0.9		pF
	Differential Mode		1.0		pF
Input Common Mode Voltage	CMRR ≥ 60dB		-1.25	-1	V
Range		2	+2.2		V
Common Mode Rejection Ratio	Input Referred,	80	100		dB
	$V_{CM} = -0.7$ to +1.7V	75			
Characteristics	1		1	1	
Large Signal Voltage Gain	$V_{O} = 1V_{PP}$	74	82		dB
	f = 1MHz		-75		dB
					1
	No Load, Positive Swing	1.4	1.7		
	No Load Negative Swing		-1.5	-12	1
			1.0	1	
	B <sub>1</sub> = 1000 Positive Swing	12	1.5	-	V
			1.0		
	B <sub>1</sub> = 1000 Negative Swing	-	_14	_1 1	1
Output Impedance	f = 1MHz		0.1		Ω
		100			
			107		
		100	13/		mA
Output Current			<u>an</u>		mA
nniv				1	1
	Input Referred	79	03		
Ratio	$V_{\rm S}$ = +2.5V to +3V	78 72	30		dB
		1 16			
Negative Power Supply	Input Referred,	75	88		dB
	3rd Harmonic Distortion   Upstream   Downstream   racteristics   Input Offset Voltage   Input Offset Average Drift   Input Offset Current   Input Bias Current   Input Capacitance   Input Common Mode Voltage   Range   Common Mode Rejection Ratio   Characteristics   Large Signal Voltage Gain   Crosstalk   maracteristics   Output Swing   Output Impedance   Output Short Circuit Current   Output Current	$\begin{tabular}{ c c c c c } \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega\\ \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 100\Omega\\ \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega\\ \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega\\ \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega\\ \hline fc = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega\\ \hline fc = 1MHz, V_O = 0.4V_{RMS,1}26kHz to 132kHz\\ \hline (see test circuit 5)\\ \hline Downstream V_O = 0.4V_{RMS,1}44kHz to 1.1MHz\\ \hline (see test circuit 5)\\ \hline racteristics \\ \hline Input Offset Voltage V_{CM} = 0V\\ \hline Input Offset Voltage Drift V_{CM} = 0V (Note 7)\\ \hline Input Offset Average Drift V_{CM} = 0V\\ \hline Input Offset Current V_{CM} = 0V\\ \hline Input Grass Current V_{CM} = 0V\\ \hline Input Capacitance Common Mode Differential Mode\\ \hline Input Common Mode Voltage Range Common Mode Differential Mode\\ \hline Input Common Mode Voltage Range Common Mode Poly + 2000 (Note 7) + 1.7V\\ \hline Characteristics \\ \hline Large Signal Voltage Gain V_O = 1V_{PP} \\ \hline Crosstalk f = 1MHz \\ \hline aracteristics \\ \hline Output Swing No Load, Positive Swing \\ \hline R_L = 100\Omega, Positive Swing \\ \hline R_L = 100\Omega, Negative Swing \\ \hline R_L = 100\Omega, Negative Swing \\ \hline Output Short Circuit Current \\ \hline Sourcing to Ground \\ \Delta V_{IN} = -200mV (Note 3), (Note 9) \\ \hline Sinking to Ground \\ \Delta V_{IN} = -0.8V\\ \hline \end{array}$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $

## ±2.5V Electrical Characteristics (Continued)

Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}$ C, V<sup>+</sup> = 2.5V, V<sup>-</sup> = -2.5V, V<sub>CM</sub> = 0V, A<sub>V</sub> = +2, R<sub>F</sub> = 500 $\Omega$ , R<sub>L</sub> = 100 $\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Тур	Мах	Units
			(Note 6)	(Note 5)	(Note 6)	
I <sub>S</sub>	Supply Current (per amplifier)	No Load		4.1	5.8	mA
					6.4	

**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics. **Note 2:** Human body model,  $1.5k\Omega$  in series with 100pF. Machine model,  $0\Omega$  in series with 200pF.

Note 3: Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.

Note 4: The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$  and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC board.

Note 5: Typical values represent the most likely parametric norm.

Note 6: All limits are guaranteed by testing or statistical analysis.

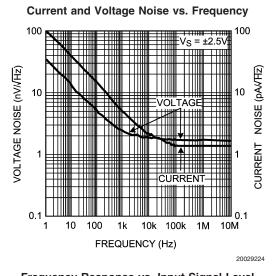
Note 7: Offset voltage average drift is determined by dividing the change in VOS at temperature extremes into the total temperature change.

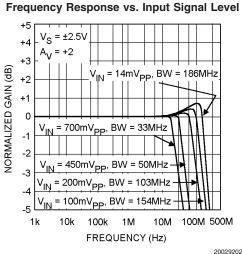
Note 8: Slew rate is the slowest of the rising and falling slew rates.

Note 9: Short circuit test is a momentary test. Output short circuit duration is infinite for  $V_S \le \pm 2.5V$ , at room temperature and below. For  $V_S > \pm 2.5V$ , allowable short circuit duration is 1.5ms.

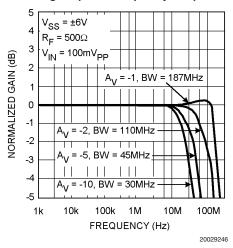


## **Typical Performance Characteristics**

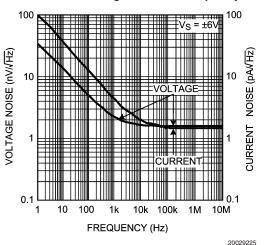




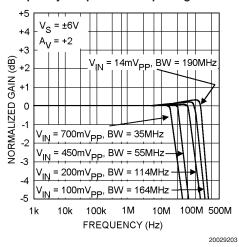
**Inverting Amplifier Frequency Response** 



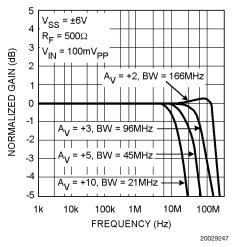
Current and Voltage Noise vs. Frequency

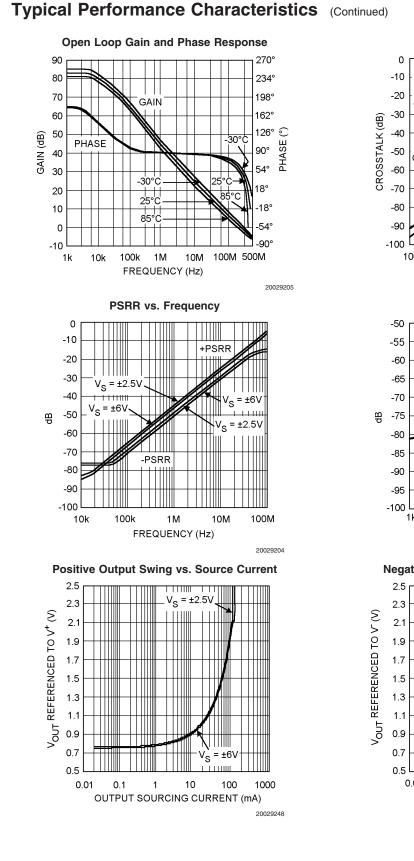


Frequency Response vs. Input Signal Level

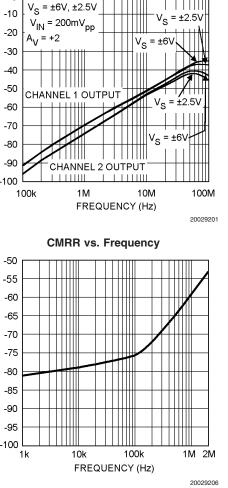


Non-Inverting Amplifier Frequency Response

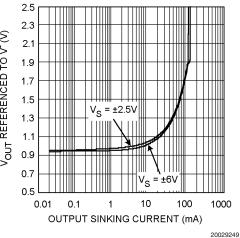






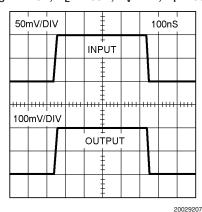


Negative Output Swing vs. Sink Current

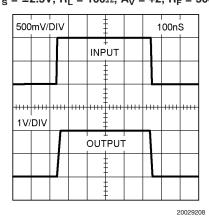


## Typical Performance Characteristics (Continued)

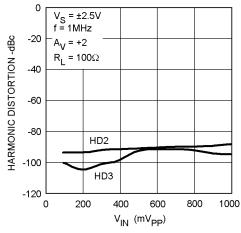
Non-Inverting Small Signal Pulse Response  $V_S = \pm 2.5V$ ,  $R_L = 100\Omega$ ,  $A_V = +2$ ,  $R_F = 500\Omega$ 



Non-Inverting Large Signal Pulse Response  $V_S = \pm 2.5V$ ,  $R_L = 100\Omega$ ,  $A_V = +2$ ,  $R_F = 500\Omega$ 

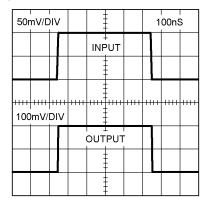


Harmonic Distortion vs. Input Signal Level



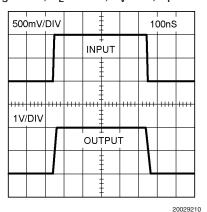
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Non-Inverting Small Signal Pulse Response  $V_S = \pm 6V, R_L = 100\Omega, A_V = +2, R_F = 500\Omega$ 



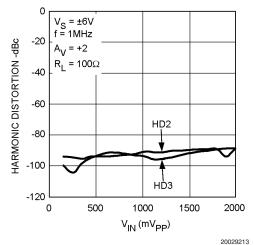
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Non-Inverting Large Signal Pulse Response  $V_S = \pm 6V$ ,  $R_L = 100\Omega$ ,  $A_V = +2$ ,  $R_F = 500\Omega$ 



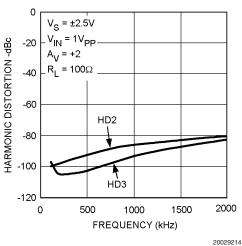
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#### Harmonic Distortion vs. Input Signal Level

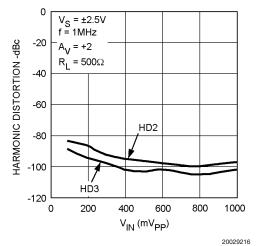


## Typical Performance Characteristics (Continued)

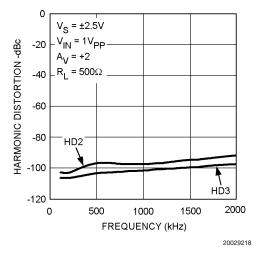
Harmonic Distortion vs. Frequency



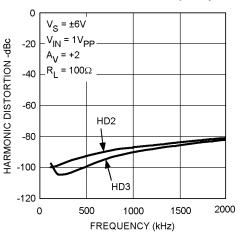
#### Harmonic Distortion vs. Input Signal Level



#### Harmonic Distortion vs. Input Frequency

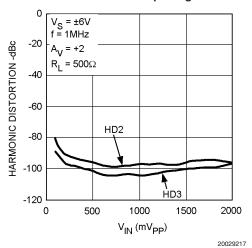


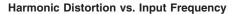
Harmonic Distortion vs. Frequency

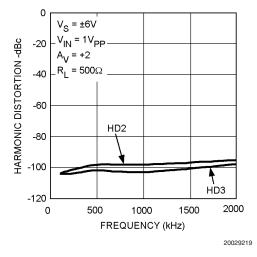


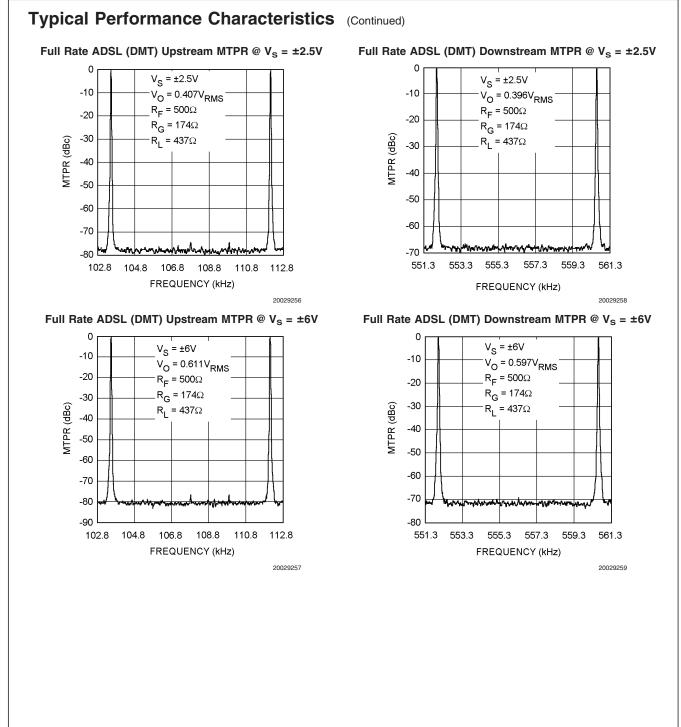
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Harmonic Distortion vs. input Signal Level

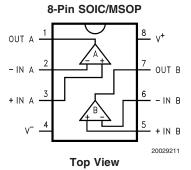






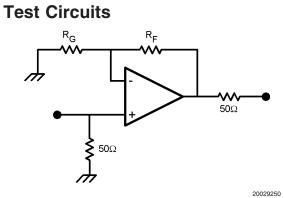


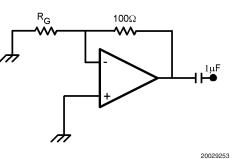
## **Connection Diagram**

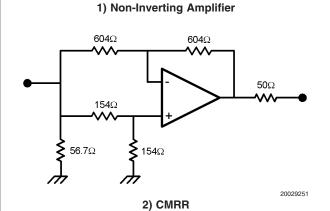


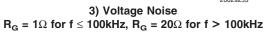
## **Ordering Information**

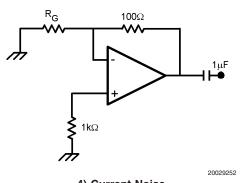
Package	Part Number	Package Marking	Transport Media	NSC Drawing
8-Pin SOIC	LMH6622MA	LMH6622MA	95 Units per Rail	M08A
	LMH6622MAX		2.5k Units Tape and Reel	*
8-Pin MSOP	LMH6622MM	A80A	1k Units Tape and Reel	MUA08A
	LMH6622MMX		3.5k Units Tape and Reel	*

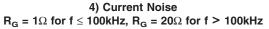


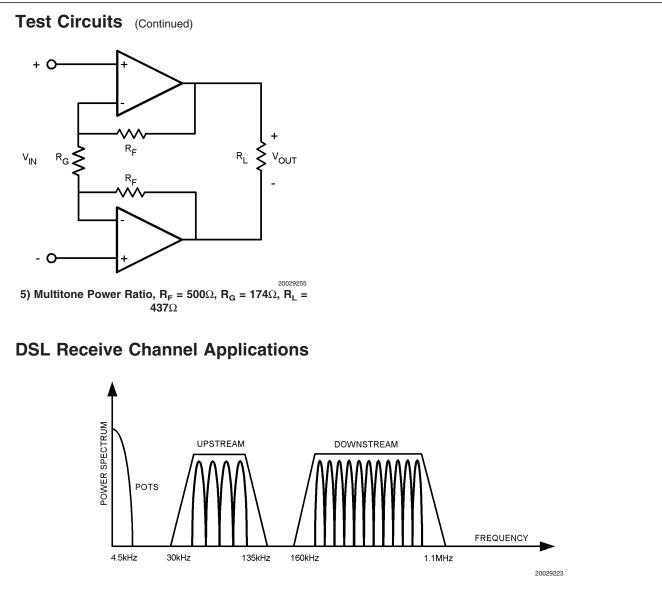














The LMH6622 is a dual, wideband operational amplifier designed for use as a DSL line receiver. In the receive band of a Customer Premises Equipment (CPE) ADSL modem it is possible that as many as 255 Discrete Multi-Tone (DMT) QAM signals will be present, each with its own carrier frequency, modulation, and signal level. The ADSL standard requires a line referred noise power density of -140dBm/Hz within the CPE receive band of 100KHz to 1.1MHz. The CPE driver output signal will leak into the receive path because of full duplex operation and the imperfections of the hybrid coupler circuit. The DSL analog front end must incorporate a receiver pre-amp which is both low noise and highly linear for ADSL-standard operation. The LMH6622 is designed for the twin performance parameters of low noise and high linearity.

Applications ranging from +5V to +12V or  $\pm 2.5V$  to  $\pm 6V$  are fully supported by the LMH6622. In *Figure 2*, the LMH6622 is used as an inverting summing amplifier to provide both received pre-amp channel gain and driver output signal cancellation, i.e., the function of a hybrid coupler.

## DSL Receive Channel Applications (Continued)

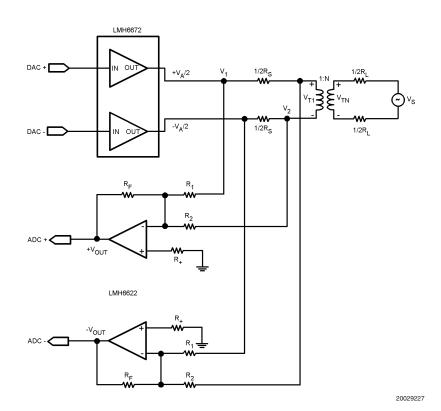


FIGURE 2. ADSL Receive Applications Circuit

# DSL Receive Channel Applications (Continued)

The two  $R_{\rm S}$  resistors are used to provide impedance matching through the 1:N transformer.

$$R_{S} = \frac{R_{L}}{N^{2}}$$

Where  $R_L$  is the impedance of the twisted pair line.

#### N is the turns ratio of the transformer.

The resistors  $\mathsf{R}_2$  and  $\mathsf{R}_{\mathsf{F}}$  are used to set the receive gain of the pre-amp. The receive gain is selected to meet the ADC full-scale requirement of a DSL chipset.

Resistor  $R_1$  and  $R_2$  along with  $R_{\rm F}$  are used to achieve cancellation of the output driver signal at the output of the receiver.

Since the LMH6622 is configured as an inverting summing amplifier,  $\rm V_{OUT}$  is found to be,

$$V_{OUT} = -R_F \left[ \frac{V_1}{R_1} + \frac{V_2}{R_2} \right]$$

The expression for  $V_1$  and  $V_2$  can be found by using superposition principle.

When  $V_{S} = 0$ ,

$$V_1 = \frac{1}{2}V_A$$
 and  $V_2 = -\frac{1}{4}V_A$ 

When  $V_A = 0$ ,

$$V_1 = 0$$
 and  $V_2 = -\frac{1}{2}V_{T1}$ 

Therefore,

$$V_1 = \frac{1}{2}V_A$$
 and  $V_2 = -\frac{1}{4}V_A - \frac{1}{2}V_{T1}$ 

And then,

$$V_{OUT} = -R_F \left[ \frac{V_A}{2R_1} - \frac{V_A}{4R_2} - \frac{V_{T1}}{2R_2} \right]$$

Setting  $\mathsf{R}_1$  =  $2^*\mathsf{R}_2$  to cancel unwanted driver signal in the receive path, then we have

$$V_{OUT} = \frac{R_F}{2R_2}V_{T1}$$

We can also find that,

ν

$$V_{TN} = \frac{1}{2}V_{S}$$
 and  $V_{T1} = \frac{1}{N}V_{TN} = \frac{1}{2N}V_{S}$ 

And then

$$V_{OUT} = \frac{R_F}{4NR_2}V_S$$

In conclusion, the peak-to-peak voltage to the ADC would be,

$$2 V_{OUT} = \frac{R_F}{2NR_2} V_S$$

#### **RECEIVE CHANNEL NOISE CALCULATION**

The circuit of *Figure 2* also has the characteristic that it cancels noise power from the drive channel. The noise gain of the receive pre-amp is found to be:

$$A_{N} = 1 + \frac{R_{F}}{R_{1}//R_{2}}$$

Noise power at each of the output of LMH6622:

$$e_{o}^{2} = A_{n}^{2} [V_{n}^{2} + i_{non-inv}^{2} R_{+}^{2} + 4kT R_{+}] + i_{inv}^{2} R_{F}^{2} + 4kT R_{F} A_{n}$$

where

V <sub>n</sub>	Input referred voltage noise
i <sub>n</sub>	Input referred current noise
İ <sub>non-inv</sub>	Input referred non-inverting current noise
İ <sub>inv</sub>	Input referred inverting current noise
k	Boltzmann's constant, K = 1.38 x 10 <sup>-23</sup>
Т	Resistor temperature in k
$R_{+}$	Source resistance at the non-inverting input
	to balance offset voltage, typically very small
	for this inverting summing applications

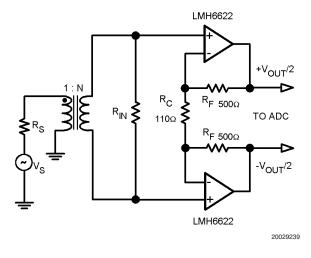
For a voltage feedback amplifier,

Therefore, total output noise from the differential pre-amp is:

$$e^{2}_{TotalOutput} = 2 e^{2}_{otalOutput}$$

The factor '2' appears here because of differential output.

#### DIFFERENTIAL ANALOG-TO-DIGITAL DRIVER



#### FIGURE 3. Circuit for Differential A/D Driver

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# LMH6622

## **DSL Receive Channel Applications**

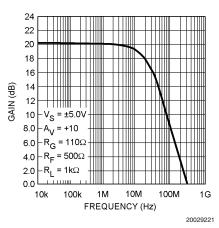
#### (Continued)

The LMH6622 is a low noise, low distortion high speed operational amplifier. The LMH6622 comes in either SOIC-8 or MSOP-8 packages. Because two channels are available in each package the LMH6622 can be used as a high dynamic range differential amplifier for the purpose of driving a high speed analog-to-digital converter. Driving a 1k $\Omega$  load, the differential amplifier of *Figure 3* provides 20dB gain, a flat frequency response up to 6MHz, and harmonic distortion that is lower than 80dBc. This circuit makes use of a transformer to convert a single-ended signal to a differential signal. The input resistor R<sub>IN</sub> is chosen by the following equation,

$$R_{IN} = \frac{1}{N^2} R_S$$

The gain of this differential amplifier can be adjusted by  $\rm R_{\rm C}$  and  $\rm R_{\rm F},$ 





#### FIGURE 4. Frequency Response

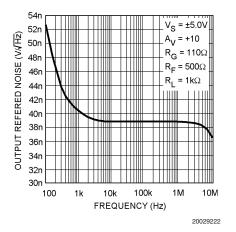


FIGURE 5. Total Output Referred Noise Density

#### **CIRCUIT LAYOUT CONSIDERATIONS**

National Semiconductor suggests the copper patterns on the evaluation boards listed below as a guide for high frequency layout. These boards are also useful as an aid in device testing and characterization. As is the case with all highspeed amplifiers, accepted-practice R<sub>E</sub> design technique on the PCB layout is mandatory. Generally, a good high frequency layout exhibits a separation of power supply and ground traces from the inverting input and output pins. Parasitic capacitances between these nodes and ground will cause frequency response peaking and possible circuit oscillations (see Application Note OA-15 for more information). High quality chip capacitors with values in the range of 1000pF to 0.1µF should be used for power supply bypassing. One terminal of each chip capacitor is connected to the ground plane and the other terminal is connected to a point that is as close as possible to each supply pin as allowed by the manufacturer's design rules. In addition, a tantalum capacitor with a value between 4.7µF and 10µF should be connected in parallel with the chip capacitor. Signal lines connecting the feedback and gain resistors should be as short as possible to minimize inductance and microstrip line effect. Input and output termination resistors should be placed as close as possible to the input/output pins. Traces greater than 1 inch in length should be impedance matched to the corresponding load termination.

Symmetry between the positive and negative paths in the layout of differential circuitry should be maintained so as to minimize the imbalance of amplitude and phase of the differential signal.

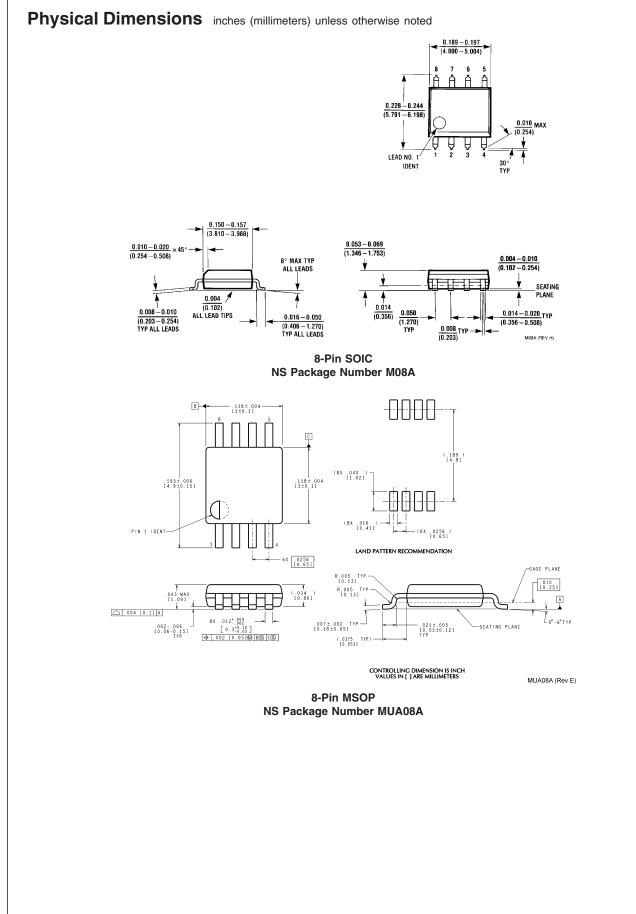
Device	Package	Evaluation Board P/N
LMH6622MA	SOIC-8	CLC730036
LMH6622MM	MSOP-8	CLC730123

These free evaluation boards are shipped when a device sample request is placed with National Semiconductor.

Component value selection is another important parameter in working with high speed/high performance amplifiers. Choosing external resistors that are large in value compared to the value of other critical components will affect the closed loop behavior of the stage because of the interaction of these resistors with parasitic capacitances. These parasitic capacitors could either be inherent to the device or be a by-product of the board layout and component placement. Moreover, a large resistor will also add more thermal noise to the signal path. Either way, keeping the resistor values low will diminish this interaction. On the other hand, choosing very low value resistors could load down nodes and will contribute to higher overall power dissipation and worse distortion.

#### DRIVING CAPACITIVE LOAD

Capacitive Loads decrease the phase margin of all op amps. The output impedance of a feedback amplifier becomes inductive at high frequencies, creating a resonant circuit when the load is capacitive. This can lead to overshoot, ringing and oscillation. To eliminate oscillation or reduce ringing, an isolation resistor can be placed between the load and the output. In general, the bigger the isolation resistor, the more damped the pulse response becomes. For initial evaluation, a 50 $\Omega$  isolation resistor is recommended.



Notes

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