

Features

260MHz bandwidth

FAIRCHIL

SEMICONDUCTOR

- Fully specified at +2.7V and +5V supplies
- Output voltage range: 0.036V to 4.953V;

 $V_{S} = +5; R_{I} = 2k\Omega$

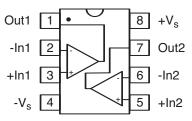
- Input voltage range: -0.3V to +3.8V; V_S = +5
- 145V/µs slew rate
- 4.2mA supply current per amplifier
- ±55mA linear output current
- ±85mA short circuit current
- Directly replaces AD8052 and AD8042 in single supply applications
- Small package options (SOIC and MSOP)

Applications

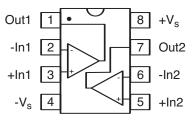
- A/D driver
- Active filters
- CCD imaging systems
- CD/DVD ROM
- Coaxial cable drivers
- High capacitive load driver
- Portable/battery-powered applications
- Twisted pair driver
- Video driver

KM4200 Packages

SOIC





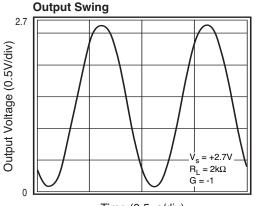


General Description

The KM4200 is a dual, low cost, voltage feedback amplifier. This amplifier is designed to operate on +2.7V, +5V, or $\pm 2.5V$ supplies. The input voltage range extends 300mV below the negative rail and 1.2V below the positive rail. The KM4100 (single) and KM4101 (single with disable) are also available.

The KM4200 offers superior dynamic performance with a 260MHz small signal bandwidth and $145V/\mu s$ slew rate. The combination of low power, high output current drive, and rail-to-rail performance make the KM4200 well suited for battery-powered communication/ computing systems.

The combination of low cost and high performance make the KM4200 suitable for high volume applications in both consumer and industrial applications such as wireless phones, scanners, and color copiers.



Time (0.5µs/div)

KM4200 Electrical Characteristics (V_s = +2.7V, G = 2, R_L = $2k\Omega$ to V_s/2; unless noted)

PARAMETERS	CONDITIONS	ТҮР	MIN & MAX	UNITS	NOTES
Case Temperature		+25°C	+25°C		
Frequency Domain Response -3dB bandwidth full power bandwidth		215 85 36		MHz MHz MHz	1
gain bandwidth product	- FF	86		MHz	
Time Domain Response rise and fall time settling time to 0.1% overshoot slew rate	0.2V step 1V step 0.2V step, 2.7V step, G = -1	3.7 40 9 130		ns ns % V/μs	1
Distortion and Noise Response 2nd harmonic distortion 3rd harmonic distortion THD input voltage noise input current noise	1V _{pp} , 5MHz 1V _{pp} , 5MHz 1V _{pp} , 5MHz >1MHz >1MHz	79 82 77 16 1.3		dBc dBc dB nV/√Hz pA/√Hz	1 1 1
crosstalk	10MHz	65		dB	1
DC Performance input offset voltage average drift input bias current average drift input offset current power supply rejection ratio open loop gain quiescent current per amplifier	DC	-1.6 10 3 7 0.1 57 75 3.9	±8 ±8 ±1 52 65 5	mV μV/°C μA nA/°C μA dB dB mA	2 2 2 2 2 2 2 2
Input Characteristics input resistance input capacitance input common mode voltage range common mode rejection ratio	DC, $V_{cm} = 0V$ to $V_s - 1.5$	4.3 1.8 -0.3 to 1.5 87	72	MΩ pF V dB	2
Output Characteristics output voltage swing linear output current	$R_{L} = 10k\Omega \text{ to } V_{s}/2$ $R_{L} = 2k\Omega \text{ to } V_{s}/2$ $R_{L} = 150\Omega \text{ to } V_{s}/2$	0.023 to 2.66 0.025 to 2.653 0.065 to 2.55 ±55	0.1 to 2.6 0.3 to 2.325	V V V mA	2 2
short circuit output current power supply operating range	-40°C to +85°C	±50 ±85 2.7	2.5 to 5.5	mA mA V	

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

NOTES:

1) $R_f = 1k\Omega$ was used used for optimal performance. (For G = +1, $R_f = 0$) 2) 100% tested at +25°C.

Absolute Maximum Ratings

Package Thermal Resistance

supply voltage	0 to +6V	Package	θ_{JA}	
maximum junction temperature	+175°C	8 lead SOIC	152°C/W	
storage temperature range	-65°C to +150°C	8 lead MSOP	206°C/W	
lead temperature (10 sec)	+300°C			
operating temperature range (recor	nmended) -40°C to +85°C			
input voltage range	+V _s +0.5V; -V _s -0.5V			
internal power dissipation	see power derating curves			

KM4200 Electrical Characteristics (V_s = +5V, G = 2, R_L = $2k\Omega$ to V_s/2; unless noted)

Parameters	Conditions	ТҮР	Min & Max	UNITS	NOTES
Case Temperature		+25°C	+25°C		
Frequency Domain Response -3dB bandwidth full power bandwidth gain bandwidth product	$\begin{array}{l} G = +1, V_{0} = 0.05 V_{pp} \\ G = +2, V_{0} = 0.2 V_{pp} \\ G = +2, V_{0} = 2 V_{pp} \end{array}$	260 90 40 90		MHz MHz MHz MHz	1
Time Domain Response rise and fall time settling time to 0.1% overshoot slew rate	0.2V step 2V step 0.2V step, 5V step, G = -1	3.6 40 7 145		ns ns % V/μs	1
Distortion and Noise Response 2nd harmonic distortion 3rd harmonic distortion THD input voltage noise input current noise crosstalk	2V _{pp} , 5MHz 2V _{pp} , 5MHz 2V _{pp} , 5MHz >1MHz >1MHz 10MHz	71 78 70 16 1.3 62		dBc dBc nV/√Hz pA/√Hz dB	1 1 1
DC Performance input offset voltage average drift input bias current average drift input offset current power supply rejection ratio open loop gain quiescent current per amplifier	DC	1.4 10 3 7 0.1 57 78 4.2	±8 ±8 ±0.8 52 68 5.2	mV μV/°C μA nA/°C μA dB dB mA	2 2 2 2 2 2 2
Input Characteristics input resistance input capacitance input common mode voltage range common mode rejection ratio	DC, $V_{cm} = 0V$ to $V_s - 1.5$	4.3 1.8 -0.3 to 3.8 87	72	MΩ pF V dB	2
Output Characteristics output voltage swing linear output current short circuit output current power supply operating range	$\begin{aligned} R_L &= 10 k\Omega \text{ to } V_s/2 \\ R_L &= 2 k\Omega \text{ to } V_s/2 \\ R_L &= 150\Omega \text{ to } V_s/2 \\ -40^\circ\text{C to } +85^\circ\text{C} \end{aligned}$	$\begin{array}{c} 0.027 \text{ to } 4.97 \\ 0.036 \text{ to } 4.953 \\ 0.12 \text{ to } 4.8 \\ \pm 55 \\ \pm 50 \\ \pm 85 \\ 5 \end{array}$	0.1 to 4.9 0.3 to 4.625 2.5 to 5.5	V V MA MA MA V	2 2

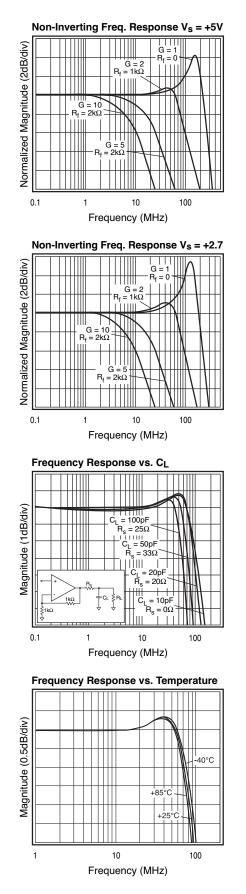
Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

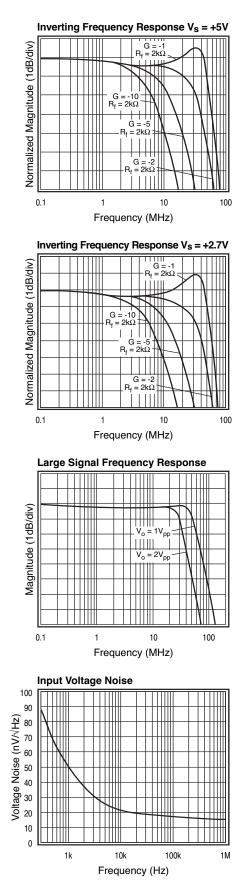
NOTES:

1) R_f = 1k $\!\Omega$ was used used for optimal performance. (For G = +1, R_f = 0)

2) 100% tested at +25°C.

KM4200 Performance Characteristics (V_s = +5V, G = 2, R_f = 2k Ω , R_L = 2k Ω to V_s/2; unless noted)





2nd

R $= 2k\Omega$

15

20

2.5

100

100

= 2kΩ

20MHz

10MHz

5MHz

2MHz

2.0

10

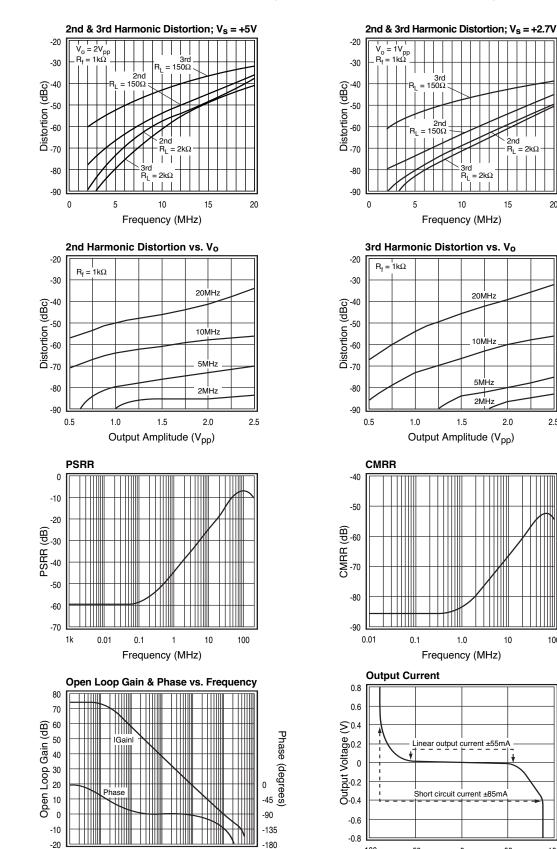
50

-100

-50

0

Output Current (mA)



KM4200 Performance Characteristics (V_s = +5V, G = 2, R_f = 2k Ω , R_L = 2k Ω to V_s/2; unless noted)

0.01

0.1

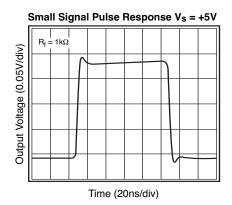
10

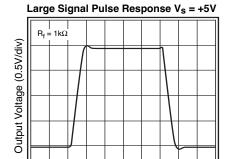
1

Frequency (MHz)

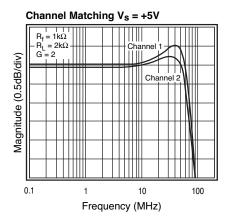
100

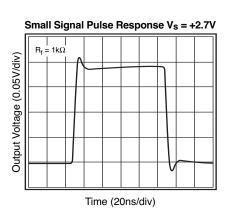
KM4200 Performance Characteristics (V_s = +5V, G = 2, R_f = 2k Ω , R_L = 2k Ω to V_s/2; unless noted)

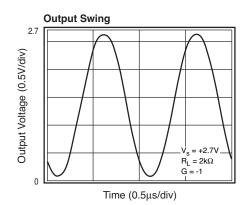


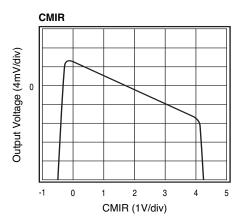


Time (20ns/div)











The KM4200 is a single supply, general purpose, voltagefeedback amplifier fabricated on a complementary bipolar process using a patent pending topography. It features a rail-to-rail output stage and is unity gain stable. Both gain bandwidth and slew rate are insensitive to temperature.

The common mode input range extends to 300mV below ground and to 1.2V below V_s . Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition.

The design uses a Darlington output stage. The output stage is short circuit protected and offers "soft" saturation protection that improves recovery time.

The typical circuit schematic is shown in Figure 1.

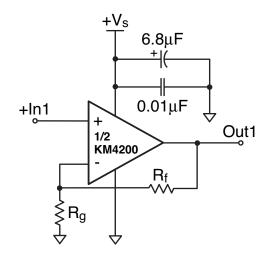


Figure 1: Typical Configuration

At non-inverting gains other than G = +1, keep R_g below 1k Ω to minimize peaking; thus, for optimum response at a gain of +2, a feedback resistor of 1k Ω is recommended. Figure 2 illustrates the KM4200 frequency response with both 1k Ω and 2k Ω feedback resistors.

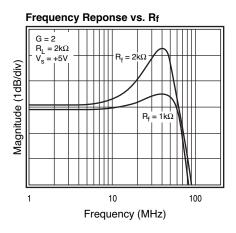


Figure 2: Frequency Response vs. R_f

Power Dissipation

The maximum internal power dissipation allowed is directly related to the maximum junction temperature. If the maximum junction temperature exceeds 150°C, some reliability degradation will occur. If the maximum junction temperature exceeds 175°C for an extended time, device failure may occur.

The KM4200 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions. Follow the maximum power derating curves shown in Figure 3 to ensure proper operation.

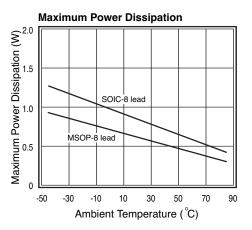


Figure 3: Power Derating Curves

Overdrive Recovery

For an amplifier, an overdrive condition occurs when the output and/or input ranges are exceeded. The recovery time varies based on whether the input or output is overdriven and by how much the ranges are exceeded. The KM4200 will typically recover in less than 20ns from an overdrive condition. Figure 4 shows the KM4200 in an overdriven condition.

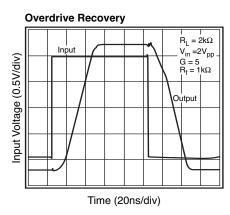


Figure 4: Overdrive Recovery

Driving Capacitive Loads

The Frequency Response vs. C_L plot on page 4, illustrates the response of the KM4200. A small series resistance (R_s) at the output of the amplifier, illustrated in Figure 5, will improve stability and settling performance. R_s values in the Frequency Response vs. C_L plot were chosen to achieve maximum bandwidth with less than 1dB of peaking. For maximum flatness, use a larger R_s .

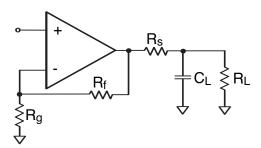


Figure 5: Typical Topology for driving a capacitive load

Layout Considerations

General layout and supply bypassing play major roles in high frequency performance. Fairchild has evaluation boards to use as a guide for high frequency layout and to aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8µF and 0.01µF ceramic capacitors
- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.01µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts shown in Figure 7

for more information.

When evaluating only one channel, complete the following on the unused channel

- 1. Ground the non-inverting input
- 2. Short the output to the inverting input

Evaluation Board Information

The following evaluation boards are available to aid in the testing and layout of this device:

Eval Board	Description	Products
KEB006	Dual Channel, Dual Supply 8 lead SOIC	KM4200IC8
KEB010	Dual Channel, Dual Supply 8 lead MSOP	KM4200IM8

Evaluation board schematics and layouts are shown in Figure 6 and Figure 7.

The KEB006 evaluation board is built for dual supply operation. Follow these steps to use the board in a single supply application:

- 1. Short -V_s to ground
- 2. Use C3 and C4, if the -V_s pin of the KM4200 is not directly connected to the ground plane.

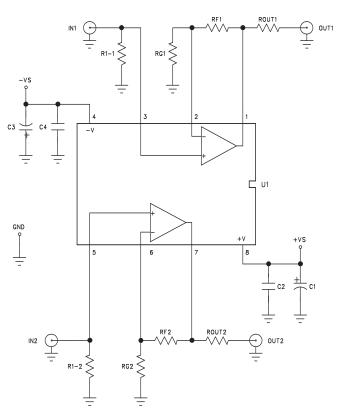


Figure 6: Evaluation Board Schematic

KM4200 Evaluation Board Layout

KOTA LAYER1 SILK

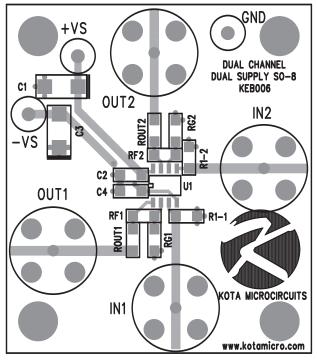


Figure 7a: KEB006 (top side)

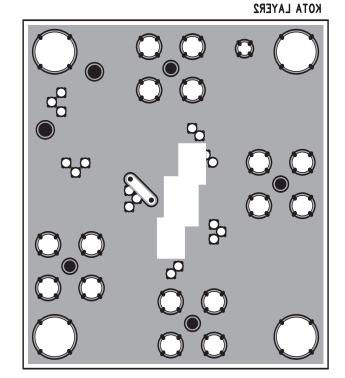


Figure 7b: KEB006 (bottom side)

GND +VS KOTA MICROCIRCUITS DUAL CHANNEL DUAL SUPPLY MSOP-8 **C1** OUT2 **KEB010 IN2** 2 RG2 ROL RF2 C2 4 **0UT1** C4 톱 RF1 ROUT1 R1-1 ß IN1 www.kotamicro.com

Figure 7c: KEB010 (top side)

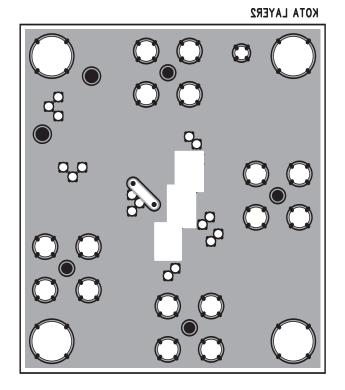
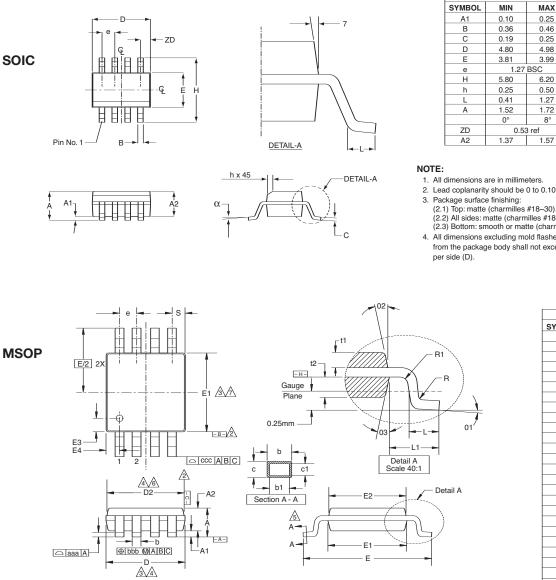


Figure 7d: KEB010 (bottom side)

KOTA LAYER1 SILK

KM4200 Package Dimensions



NOTE:

1 All dimensions are in millimeters (angle in degrees), unless otherwise specified.

 \triangle Datums -B- and -C- to be determined at datum plane -H-.

A Dimensions "D2" and "E2" are for top package and dimensions "D" and "E1" are for bottom package.

 \triangle Cross sections A – A to be determined at 0.13 to 0.25mm from the leadtip.

6 Dimension "D" and "D2" does not include mold flash, protrusion or gate burrs.

 \triangle Dimension "E1" and "E2" does not include interlead flash or protrusion.

0°	8°			
	3 ref			
.37	1.57			
n millime				
	0 to 0.10mm	(.004	") max.	
shing:	(10.00)			
	#18~30). nilles #18~30			
	te (charmille		~30)	
	old flashes a			
	I not exceed			
			MSOP-8	
	SYMB	OL	MIN	
	A		1.10	
	A1		0.10	
	A2		0.86	
	D		3.00	
	D2		2.95	
	E		4.90	
				1

SOIC-8

MSOP-8				
SYMBOL	MIN	MAX		
А	1.10	-		
A1	0.10	0.05		
A2	0.86	0.08		
D	3.00	0.10		
D2	2.95	0.10		
E	4.90	0.15		
E1	3.00	0.10		
E2	2.95	0.10		
E3	0.51	0.13		
E4	0.51	0.13		
R	0.15	+0.15/-0.06		
R1	0.15	+0.15/-0.06		
t1	0.31	0.08		
t2	0.41	0.08		
b	0.33	+0.07/-0.08		
b1	0.30	0.05		
С	0.18	0.05		
c1	0.15	+0.03/-0.02		
01	3.0	3.0		
02	12.0	3.0		
03	12.0	3.0		
L	0.55	0.15		
L1	0.95 BSC	-		
aaa	0.10	-		
bbb	0.08	-		
CCC	0.25	-		
е	0.65 BSC	-		
S	0.525 BSC	-		

Ordering Information

Model	Part Number	Lead-Free	Package	Container	Pack Qty
KM4200	KM4200IC8TR3	No	SOIC-8	Reel	3000
KM4200	KM4200IC8TR3_NL	Yes	SOIC-8	Reel	3000
KM4200	KM4200IM8TR3_NL	Yes	MSOP-8	Reel	3000

Temperature range for all parts: -40°C to +85°C.

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- A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.