FAN5358 — 2MHz, 500mA, SC70 Synchronous Buck Regulato

March 2013



# FAN5358 2MHz, 500mA, SC70 Synchronous Buck Regulator

# Features

- 2MHz Nominal-Frequency Operation
- 25µA Typical Quiescent Current
- 500mA Output Current Capability
- 2.7V to 5.5V Input Voltage Range
- 1.0 to 1.8V Fixed Output Voltages
- Low Ripple, Light-Load PFM Mode
- Internal Soft-Start
- Input Under-Voltage Lockout (UVLO)
- Thermal Shutdown and Overload Protection
- 6-lead 2 x 2.2mm SC70

# Applications

- Cell Phones, Smart Phones
- 3G, 4G, WiFi<sup>®</sup>, WiMAX<sup>™</sup>, and WiBro<sup>®</sup> Data Cards
- Netbooks<sup>®</sup>, Ultra-Mobile PCs

# Description

The FAN5358 is a step-down switching voltage regulator that delivers a fixed output from an input voltage supply of 2.7V to 5.5V. Using a proprietary architecture with synchronous rectification, the device is capable of delivering 500mA and maintaining a very high efficiency of over 80% at load currents as low as 1mA. The regulator operates at a nominal frequency of 2MHz, which reduces the value of the external components to as low as 2.2 $\mu$ H for the output inductor and 4.7 $\mu$ F for the output capacitor.

At moderate and light loads, pulse frequency modulation is used to operate the device in power-save mode with a typical quiescent current of  $25\mu$ A. Even with such a low quiescent current, the part exhibits excellent transient response during large load swings. In shutdown mode, the supply current drops below 1µA, reducing power consumption.

FAN5358 is available in a 6-lead SC70 package.

# Typical Application

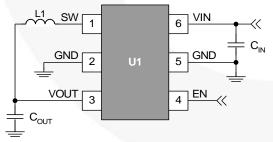


Figure 1. FAN5358 Typical Application

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#### Table 1. External Components for Figure 1

U1	f <sub>sw</sub>	L1	CIN	C <sub>OUT</sub>
FAN5358	2MHz	2.2µH	2.2μF	4.7μF

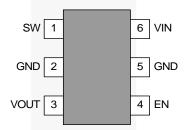
# **Ordering Information**

Part Number	Switching Frequency	Output Voltage <sup>(1)</sup>	Temperature Range	Package	Packing Method
FAN5358S710X		1.0V			
FAN5358S712X	2MHz	1.2V	40 to 195%	SC70 6	Topo and Dool
FAN5358S713X		1.3V	–40 to +85°C	SC70-6	Tape and Reel
FAN5358S718X		1.8V			

#### Note:

1. Other voltage options are available on request. Contact a Fairchild representative.

# **Pin Configuration**



### Figure 2. Pin Assignments (Top View)

# **Pin Definitions**

Pin #	Name	Description
1	SW	Switching Node. Connect to output inductor.
2, 5	GND	Ground. Power and IC ground. All signals are referenced to this pin.
3	VOUT	Vour / Feedback. Connect to output voltage.
4	EN	<b>Enable</b> . The device is in shutdown mode when the voltage to this pin is <0.4V and enabled when >1.2V. Do not leave this pin floating.
6	VIN	Input Voltage. Connect to input power source and C <sub>IN</sub> .

# **Absolute Maximum Ratings**

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

Symbol	Parameter			Max.	Units
V	Input Voltage with Respect to GND		-0.3	6.0	V
V <sub>IN</sub>	Voltage on Any Other Pin with Respect to GNE	)	-0.3	V <sub>IN</sub> +0.3V <sup>(2)</sup>	V
TJ	Junction Temperature		-40	+150	°C
T <sub>STG</sub>	Storage Temperature		-65	+150	°C
TL	Lead Temperature (Soldering 10 Seconds)			+260	°C
	Electrostatio Discharge Dretection Lovel	Human Body Model, JESD22-A114	2		kV
ESD	Electrostatic Discharge Protection Level	Charged Device Model, JESD22-C101	1		κV

Note:

2. Lesser of 6.0V or  $V_{IN}$  + 0.3V

# **Recommended Operating Conditions**

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.

Symbol	Parameter	Min.	Тур.	Max.	Units
V <sub>cc</sub>	Supply Voltage Range	2.7		5.5	V
I <sub>OUT</sub>	Output Current	0		500	mA
L	Inductor		2.2		μH
CIN	Input Capacitor		2.2		μF
COUT	Output Capacitor <sup>(3)</sup>		4.7		μF
T <sub>A</sub>	Operating Ambient Temperature	-40		+85	°C
TJ	Operating Junction Temperature	-40		+125	°C

# **Thermal Properties**

Symbol	Parameter	Min.	Тур.	Max.	Units
Θ <sub>JA</sub>	Junction-to-Ambient Thermal Resistance <sup>(4)</sup>		285	- V	°C/W

#### Notes:

3. Refer to Operation Description section for guidance on maximum C<sub>OUT</sub> capabilities.

 Junction-to-ambient thermal resistance is a function of application and board layout. This data is measured with four-layer 2s2p boards in accordance to JESD51- JEDEC standard. Special attention must be paid not to exceed junction temperature T<sub>J(max)</sub> at a given ambient temperate T<sub>A</sub>.

# **Electrical Characteristics**

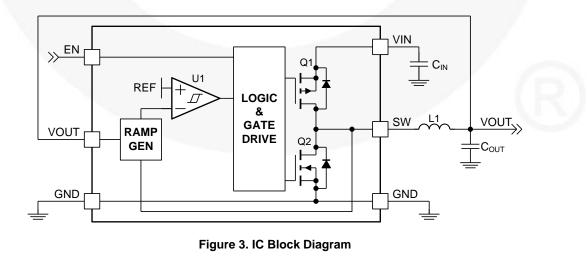
Minimum and maximum values are at  $V_{IN}$  = 2.7V to 5.5V,  $T_A$  = -40°C to +85°C, circuit of Figure 1 unless otherwise noted. Typical values are at  $T_A$  = 25°C,  $V_{IN}$  =3.6V.

Diles Quiescent Currer Shutdown Supply Under-Voltage Lo		No Load, EN=V <sub>IN</sub>		25	40	<u> </u>
Shutdown Supply Under-Voltage Lo				25	40	
Under-Voltage Lo	/ Current			20	48	μA
•		EN = GND		0.05	1.00	μA
	ockout Threshold	Rising V <sub>IN</sub>		2.4	2.6	V
Under-Voltage Lo	ockout Hysteresis			225		mV
Enable HIGH-Lev	/el Input Voltage		1.2			V
Enable LOW-Level Input Voltage					0.4	V
Enable Input Leakage Current		EN = V <sub>IN</sub> or GND	1	0.01	1.00	μA
Switching Freque	ency	In PWM Mode		2		MHz
	1.0V	$I_{LOAD} = 0$ to 500mA	-4.5		+4.5	
Output Voltage	1.2V	$I_{LOAD} = 0$ to 500mA	-4.5		+4.5	0/
Accuracy	1.3V	$I_{LOAD} = 0$ to 500mA	-4.5		+4.5	%
	1.8V	$I_{LOAD} = 0$ to 500mA	-4.0		+4.0	
Soft-Start		From EN Rising Edge		70		μs
er						<u>.</u>
PMOS On Resist	ance	$V_{IN} = V_{GS} = 3.6V$		750		mΩ
NMOS On Resist	ance	$V_{IN} = V_{GS} = 3.6V$		650		mΩ
PMOS Peak Curr	rent Limit	Open-Loop <sup>(5)</sup>	750	850	1150	mA
Thermal Shutdow	'n			150		°C
Thermal Shutdow	n Hysteresis			20		°C
	Enable HIGH-Lev Enable LOW-Lev Enable Input Lea Switching Freque Output Voltage Accuracy Soft-Start er PMOS On Resist NMOS On Resist PMOS Peak Curr Thermal Shutdow	Enable HIGH-Level Input Voltage Enable LOW-Level Input Voltage Enable Input Leakage Current Switching Frequency Output Voltage Accuracy 1.2V 1.3V 1.8V Soft-Start	Enable HIGH-Level Input Voltage         Enable LOW-Level Input Voltage         Enable Input Leakage Current       EN = V <sub>IN</sub> or GND         Switching Frequency       In PWM Mode         Output Voltage       1.0V       I <sub>LOAD</sub> = 0 to 500mA         Accuracy       1.2V       I <sub>LOAD</sub> = 0 to 500mA         1.3V       I <sub>LOAD</sub> = 0 to 500mA         1.8V       I <sub>LOAD</sub> = 0 to 500mA         Soft-Start       From EN Rising Edge         er       PMOS On Resistance       V <sub>IN</sub> = V <sub>GS</sub> = 3.6V         NMOS On Resistance       V <sub>IN</sub> = V <sub>GS</sub> = 3.6V         PMOS Peak Current Limit       Open-Loop <sup>(5)</sup> Thermal Shutdown       I	Enable HIGH-Level Input Voltage1.2Enable LOW-Level Input VoltageEnable Input Leakage CurrentEN = $V_{IN}$ or GNDSwitching FrequencyIn PWM ModeOutput Voltage $1.2V$ $Accuracy$ $1.0V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.2V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.3V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.8V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.8V$ $I_{LOAD} = 0$ to 500mA-4.0Soft-StartFrom EN Rising EdgeerPMOS On Resistance $V_{IN} = V_{GS} = 3.6V$ PMOS Peak Current LimitOpen-Loop <sup>(5)</sup> 750Thermal ShutdownIntervalue of the state of the	Enable HIGH-Level Input Voltage1.2Enable LOW-Level Input VoltageEnable LOW-Level Input VoltageEnable Input Leakage CurrentEN = $V_{IN}$ or GNDSwitching FrequencyIn PWM ModeQutput Voltage $1.0V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.2V$ $I_{LOAD} = 0$ to 500mA $1.3V$ $I_{LOAD} = 0$ to 500mA $1.3V$ $I_{LOAD} = 0$ to 500mA $1.3V$ $I_{LOAD} = 0$ to 500mA $-4.5$ $1.3V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.3V$ $I_{LOAD} = 0$ to 500mA $-4.5$ $70$ Soft-StartFrom EN Rising EdgePMOS On Resistance $V_{IN} = V_{GS} = 3.6V$ PMOS On Resistance $V_{IN} = V_{GS} = 3.6V$ PMOS Peak Current LimitOpen-Loop <sup>(5)</sup> Thermal Shutdown150	Enable HIGH-Level Input Voltage1.2Enable LOW-Level Input Voltage0.4Enable Input Leakage CurrentEN = V_IN or GNDSwitching FrequencyIn PWM ModeQutput Voltage1.0V $I_{LOAD} = 0$ to 500mA-4.5 $Accuracy$ $1.2V$ $I_{LOAD} = 0$ to 500mA-4.5 $1.2V$ $I_{LOAD} = 0$ to 500mA $1.3V$ $I_{LOAD} = 0$ to 500mA $1.3V$ $I_{LOAD} = 0$ to 500mA $4.5$ +4.5 $1.3V$ $I_{LOAD} = 0$ to 500mA $-4.5$ +4.5 $1.8V$ $I_{LOAD} = 0$ to 500mA $-4.0$ +4.0Soft-StartFrom EN Rising EdgePMOS On Resistance $V_{IN} = V_{GS} = 3.6V$ PMOS On Resistance $V_{IN} = V_{GS} = 3.6V$ PMOS Peak Current LimitOpen-Loop <sup>(5)</sup> Thermal Shutdown150

#### Note:

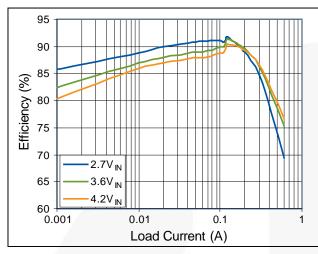
5. The Electrical Characteristics table reflects open-loop data. *Refer to Operation Description and Typical Characteristic for closed-loop data.* 

# **Block Diagram**

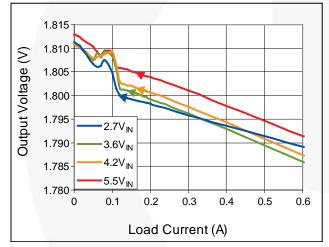


# **Typical Characteristics**

Unless otherwise noted,  $V_{IN} = V_{EN} = 3.6V$ ,  $V_{OUT} = 1.8V$ , and  $T_A = 25^{\circ}C$ .









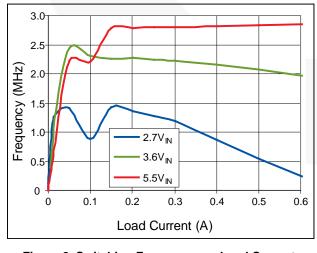
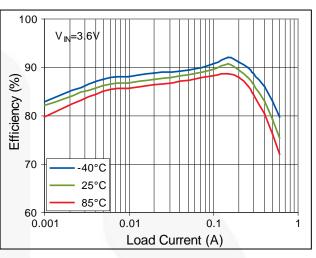
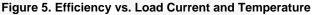


Figure 8. Switching Frequency vs. Load Current





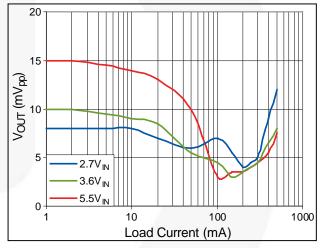
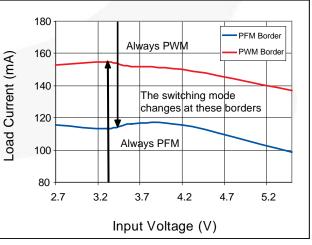


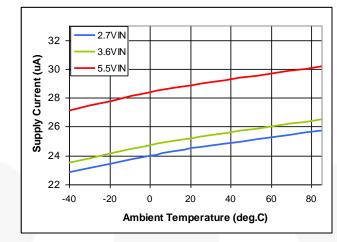
Figure 7. Peak-to-Peak Output Voltage Ripple

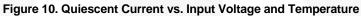




# **Typical Characteristics**

Unless otherwise noted,  $V_{IN}$  =  $V_{EN}$  = 3.6V,  $V_{OUT}$  = 1.8V, and  $T_A$  = 25°C.





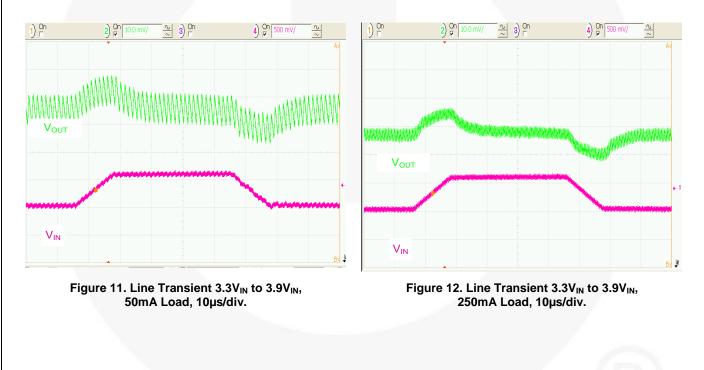


Figure 15. Load Transient 200 to 500mA, 3.6V<sub>IN</sub>, 5µs/div.

### **Typical Characteristics**

Unless otherwise noted,  $V_{\text{IN}}$  =  $V_{\text{EN}}$  = 3.6V,  $V_{\text{OUT}}$  = 1.8V, and  $T_{\text{A}}$  = 25°C.



Figure 13. Load Transient 0 to 150mA, 3.6V<sub>IN</sub>, 5µs/div.





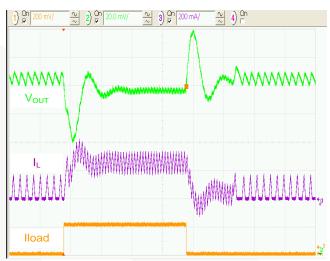


Figure 14. Load Transient 50 to 250mA, 3.6V<sub>IN</sub>, 5µs/div.

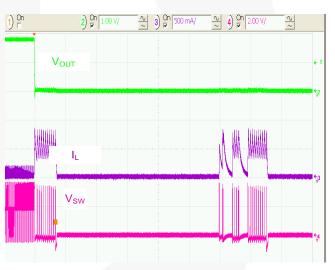


Figure 16. Metallic Short Applied at Vout, 50µs/div.

# **Typical Characteristics**

Unless otherwise noted,  $V_{\text{IN}}$  =  $V_{\text{EN}}$  = 3.6V,  $V_{\text{OUT}}$  = 1.8V, and  $T_{\text{A}}$  = 25°C.

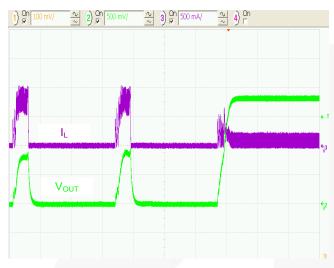


Figure 17. Overload Recovery to Light Load, 100µs/div.



Figure 19. Power Supply Rejection Ratio at 200mA Load

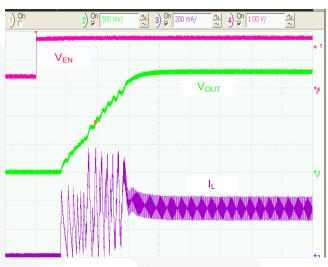


Figure 18. Soft-Start,  $R_{LOAD} = 6\Omega$ , 20µs/div.

# **Operation Description**

The FAN5358 is a step-down switching voltage regulator that delivers a fixed output from an input voltage supply of 2.7V to 5.5V. Using a proprietary architecture with synchronous rectification, the device is capable of delivering 500mA and maintaining a very high efficiency of over 80% at load currents as low as 1mA. The regulator operates at a nominal frequency of 2MHz, which reduces the value of the external components to as low as 2.2 $\mu$ H for the output inductor and 4.7 $\mu$ F for the output capacitor.

### **Control Scheme**

The FAN5358 uses a proprietary, non-linear, quasi fixedfrequency PWM modulator to deliver a fast load transient response, while maintaining a nominal switching frequency over a wide range of load conditions. The regulator performance is independent of the output capacitor ESR, allowing the use of ceramic output capacitors.

For very light loads, the device operates in discontinuous current (DCM) single-pulse PFM mode, which produces low output ripple compared with other PFM architectures. Transition between PWM and PFM is near seamless, exhibiting very little  $V_{OUT}$  glitch.

Combined with exceptional transient response characteristics, the very low quiescent current of the controller (25 $\mu$ A) maintains high efficiency, even at very light loads, while preserving fast transient response for applications requiring very tight output regulation.

# Enable and Soft Start

Maintaining the EN pin LOW keeps the FAN5358 in nonswitching mode in which all circuits are off and the part draws ~50nA of current. Increasing EN above its threshold voltage activates the part and starts the soft-start cycle. During soft start, the output is ramped using a slow RC time constant. This minimizes any large surge currents on the input and prevents any overshoot of the output voltage. Current limit is enforced in case the output cannot keep pace with the reference or in case of a shorted output.

The current-limit fault response protects the IC in the event of an over-current condition present during soft-start. This protection can cause the IC to fail to start if heavy load is applied during startup or if excessive  $C_{\text{OUT}}$  is used.

Table 2 shows combinations of  $C_{\text{OUT}}$  that allow the IC to start successfully with the minimum  $R_{\text{LOAD}}$  that can be supported.

# Table 2. Minimum $R_{\text{LOAD}}$ Values for Soft-Start with Various $C_{\text{OUT}}$ Values

C <sub>OUT</sub>	Minimum R <sub>LOAD</sub>
4.7μF	No restriction
10µF	V <sub>OUT</sub> / 0.40

# Under-Voltage Lockout (UVLO)

When EN is HIGH, the under-voltage lockout keeps the part from operating until the input supply voltage rises high enough to properly operate. This ensures no misbehavior of the regulator during startup or shutdown.

# **Current Limiting**

A heavy load or short circuit on the output causes the current in the inductor to increase until a maximum current threshold is reached in the high-side switch. Upon reaching this point, the high-side switch turns off, preventing current from increasing further.

After 12 consecutive PWM cycles that terminate in current limit, the IC shuts down. About  $275\mu s$  after shutting down, the IC attempts to restart. If the fault has not cleared, the IC continues to shut down, then attempts to restart as shown in Figure 16.

# **Thermal Shutdown**

When the die temperature increases, due to a heavy load condition and/or high ambient temperature, output switching is disabled until the die temperature falls sufficiently. The junction temperature at which the thermal shutdown activates is nominally 150°C with a 20°C hysteresis. Upon cooling, the output is enabled and goes through the regular soft start.

# **Applications Information**

#### Selecting the Inductor

The output inductor must meet both the required inductance and the energy handling capability of the application.

The inductor value affects the average current limit, the PWM-to-PFM transition point, the output voltage ripple, and the efficiency.

The ripple current ( $\Delta I$ ) of the regulator is:

$$\Delta I \approx \frac{V_{OUT}}{V_{IN}} \bullet \left( \frac{V_{IN} - V_{OUT}}{L \bullet f_{SW}} \right)$$
(1)

The maximum average load current,  $I_{MAX(LOAD)}$ , is related to the peak current limit,  $I_{LIM(PK)}$  by the ripple current:

$$I_{MAX(LOAD)} = I_{LIM(PK)} - \frac{\Delta I}{2}$$
(2)

The transition between PFM and PWM operation is determined by the point at which the inductor valley current crosses zero. The regulator DC current when the inductor current crosses zero,  $I_{DCM}$ , is:

$$I_{\text{DCM}} = \frac{\Delta I}{2} \tag{3}$$

The FAN5358 is optimized for operation with L=2.2 $\mu H.$  The inductor should be rated to maintain at least 70% of its value at  $I_{LIM(PK)}.$ 

Efficiency is affected by the inductor DCR and inductance value. Decreasing the inductor value for a given physical size typically decreases the DCR; but since  $\Delta I$  increases, the RMS current increases, as do core and skin effect losses.

$$I_{\text{RMS}} = \sqrt{I_{\text{OUT}(\text{DC})}^2 + \frac{\Delta l^2}{12}}$$
(4)

The increased RMS current produces higher losses through the  $R_{DS(ON)}$  of the IC MOSFETs as well as the inductor ESR.

Increasing the inductor value produces lower RMS currents, but degrades transient response. For a given physical inductor size, increased inductance usually results in an inductor with lower saturation current. Table 3 shows the effects of inductance higher or lower than the recommended inductor on regulator performance.

### **Thermal Considerations**

The FAN5358 is designed to supply a maximum of 500mA, at the specified output voltage, with an operating junction temperature of up to 125°C. Once the power dissipation and thermal resistance is known, the maximum junction temperature of the device can be calculated. The power dissipation by the IC can be calculated from the power efficiency diagram Figure 5 and subtracting the power dissipated by the inductor due to its serial resistance (ESR).

The inductor ESR is dependent, not only upon the size and type of inductor, but also upon the switching frequency, which depends on the load and  $V_{\rm IN}$ . Some inductor manufacturers provide full information regarding the variation of the inductor ESR with the switching frequency. This information can be used to show that, at high switching frequency (~2 MHz) and maximum load, the power dissipated by the inductor can exceed the power dissipated by the IC package itself.

The actual thermal resistance depends upon the thermal characteristics of the SC-70 surface-mount package and the surrounding printed circuit board (PCB) copper to which it is mounted. This can be improved by providing a heat sink of surrounding copper ground on the PCB. Depending on the size of the copper area, the resulting  $\theta$  JA can be reduced below 280°C/W. The addition of backside copper with through holes, stiffeners, and other enhancements can also help reduce thermal resistance. The heat contributed by the dissipation of other devices, particularly the inductor, located nearby, must be included in the design considerations. Once the limiting parameters are determined, the design can be modified to ensure that the device remains within specified operating conditions even if the maximum load is applied permanently.

In short circuit V<sub>OUT</sub>-to-GND condition, the FAN5358 is fully protected and the power dissipated is internally reduced below 100mW. Overload conditions at minimum V<sub>IN</sub> should be considered as worst case, when it is possible for the device to enter a thermal cycling loop in which the circuit enters a shutdown condition, cools, re-enables, and again overheats and shuts down repeatedly due to an unmanaged fault condition. The diagram in Figure 20 was determined experimentally, using the recommended two-layer PCB in still air, to be used as a thermal guide.

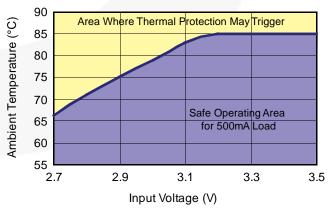


Figure 20. Maximum Ambient Temperature vs. Input Voltage at 500mA

### **PCB Layout Considerations**

There are only three external components: the inductor and the input and output capacitors. For any buck regulator IC, including the FAN5358, it is important to place a low-ESR input capacitor very close to the IC, as shown in Figure 21. The input capacitor ensures good input decoupling, which reduces noise appearing at the output terminals and ensures that the control sections of the IC do not behave erratically due to excessive noise. This reduces switching cycle jitter and ensures good overall performance. It is important to place the common GND of C<sub>IN</sub> and C<sub>OUT</sub> as close as possible to any of the FAN5358 GND terminals. There is some flexibility in moving the inductor further away from the IC; in that case,  $V_{OUT}$  should be considered at the C<sub>OUT</sub> terminal.

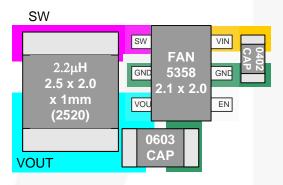


Figure 21. PCB Layout Guidance

### **Output Capacitor**

Table 4 suggests 0402 capacitors. 0603 capacitors may further improve performance in that the effective capacitance is higher. This improves the transient response and output ripple as shown in Table 3.

Increasing C<sub>OUT</sub> has no effect on loop stability and can therefore be increased to reduce output voltage ripple or to improve transient response. Output voltage ripple,  $\Delta V_{OUT}$ , is:

$$\Delta V_{OUT} = \Delta I \bullet \left( \frac{1}{8 \bullet C_{OUT} \bullet f_{SW}} + ESR \right)$$
(5)

### Input Capacitor

The 2.2 $\mu$ F ceramic input capacitor should be placed as close as possible between the VIN pin and GND to minimize the parasitic inductance. If a long wire is used to bring power to the IC, additional "bulk" capacitance (electrolytic or tantalum) should be placed between C<sub>IN</sub> and the power source lead to reduce ringing that can occur between the inductance of the power source leads and C<sub>IN</sub>.

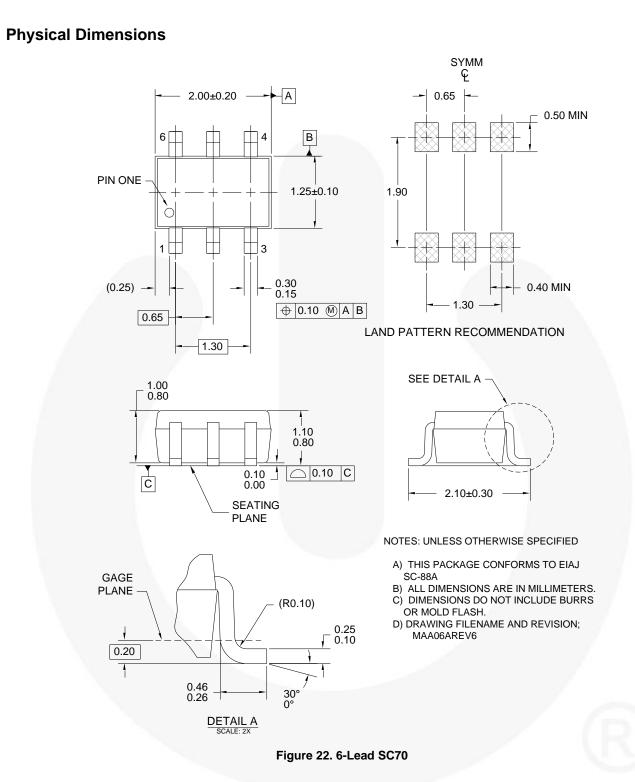
The effective capacitance value decreases as VIN increases due to DC Bias effects. This has no significant impact on regulator performance.

Table 3. Effects of Changes in Inductor Value (fr	rom Recommended Value) on Regulator Perform	ance
Table 5. Effects of offanges in inductor value (if	on Recommended value) on Regulator renorm	ance

Inductor Value	I <sub>MAX(LOAD)</sub>	I <sub>LIM(PK)</sub>	$\Delta V_{OUT}^{(5)}$	Transient Response
Increase	Increase	Decrease	Decrease	Degraded
Decrease	Decrease	Increase	Increase	Improved

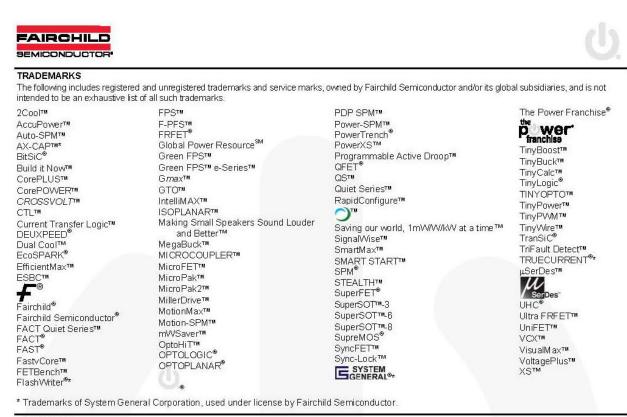
Table 4. Recommended Passive Components and Their Variation Due to DC Bias

Component	Description	Vendor	Min.	Тур.	Max.	Comment
	2.2μH, 2520, 100mΩ,1.3A	FDK MIPF2520D				
L1	2.2μH, 2520, 80mΩ,1.3A	Hitachi Metal:KSLI - 252010AG-2R2 Murata: LQM31PN2RM00L TOKO: MDT2520CN2R2M	1.5μΗ	2.2μΗ		Minimum value occurs at maximum current
C <sub>OUT</sub>	4.7μF, X5R, 0402	Murata or Equivalent GRM155R60G475M GRM155R60E475ME760	1.6μF	4.7μF	5.2µF	Decrease primarily due to DC bias (V <sub>OUT</sub> )
C <sub>IN</sub>	2.2μF, X5R, 0402	Murata or Equivalent GRM155R60J225ME15 GRM188R60J225KE19D	1.0μF	2.2µF	2.4µF	Decrease primarily due to DC bias (V <sub>IN</sub> ) and elevated temperature



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Rev. 157

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2MHz, 500mA, SC70 Synchronous Buck Regulator