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# LMV2011

## High Precision, Rail-to-Rail Output Operational Amplifier

### General Description

The LMV2011 is a new precision amplifier that offers unprecedented accuracy and stability at an affordable price and is offered in miniature (SOT23-5) package and in 8 lead SOIC package. This device utilizes patented techniques to measure and continually correct the input offset error voltage. The result is an amplifier which is ultra stable over time and temperature. It has excellent CMRR and PSRR ratings, and does not exhibit the familiar 1/f voltage and current noise increase that plagues traditional amplifiers. The combination of the LMV2011 characteristics makes it a good choice for transducer amplifiers, high gain configurations, ADC buffer amplifiers, DAC I-V conversion, and any other 2.7V-5V application requiring precision and long term stability.

Other useful benefits of the LMV2011 are rail-to-rail output, a low supply current of 930 $\mu$ A, and wide gain-bandwidth product of 3MHz. These extremely versatile features found in the LMV2011 provide high performance and ease of use.

### Features

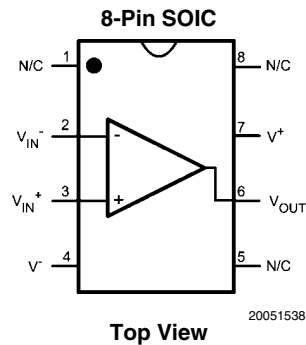
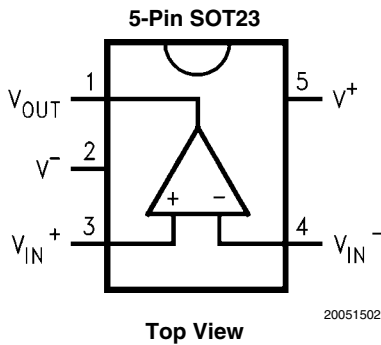
(For  $V_s = 5V$ , Typical unless otherwise noted)

- Low Guaranteed  $V_{os}$  over temperature 35 $\mu$ V
- Low Noise with no 1/f 35nV/ $\sqrt$ Hz
- High CMRR 130dB
- High PSRR 120dB
- High  $A_{VOL}$  130dB
- Wide gain-bandwidth product 3MHz
- High slew rate 4V/ $\mu$ s
- Low supply current 930 $\mu$ A
- Rail-to-rail output 30mV
- No external capacitors required

### Applications

- Precision Instrumentation Amplifiers
- Thermocouple Amplifiers
- Strain Gauge Bridge Amplifier

### Connection Diagrams



### Ordering Information

| Package     | Part Number | Package Marking | Transport Media          | NSC Drawing |
|-------------|-------------|-----------------|--------------------------|-------------|
| 5-Pin SOT23 | LMV2011MF   | A84A            | 1k Units Tape and Reel   | MF05A       |
|             | LMV2011MFX  |                 | 3k Units Tape and Reel   |             |
| 8-Pin SOIC  | LMV2011MA   | LMV2011MA       | 95 Units/Rail            | M08A        |
|             | LMV2011MAX  |                 | 2.5k Units Tape and Reel |             |

**Absolute Maximum Ratings** (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

|                            |                                       |
|----------------------------|---------------------------------------|
| ESD Tolerance              |                                       |
| Human Body Model           | 2000V                                 |
| Machine Model              | 200V                                  |
| Supply Voltage             | 5.5V                                  |
| Common-Mode Input Voltage  | $-0.3 \leq V_{CM} \leq V_{CC} + 0.3V$ |
| Differential Input Voltage | $\pm$ Supply Voltage                  |
| Current At Input Pin       | 30mA                                  |

|                                      |        |
|--------------------------------------|--------|
| Current At Output Pin                | 30mA   |
| Current At Power Supply Pin          | 50mA   |
| Junction Temperature ( $T_J$ )       | 150°C  |
| Lead Temperature (soldering 10 sec.) | +300°C |

**Operating Ratings** (Note 1)

|                             |                |
|-----------------------------|----------------|
| Supply Voltage              | 2.7V to 5.25V  |
| Storage Temperature Range   | -65°C to 150°C |
| Operating Temperature Range | 0°C to 70°C    |

**2.7V DC Electrical Characteristics** Unless otherwise specified, all limits guaranteed for  $T_J = 25^\circ\text{C}$ ,  $V^+ = 2.7V$ ,  $V^- = 0V$ ,  $V_{CM} = 1.35V$ ,  $V_O = 1.35V$  and  $R_L > 1M\Omega$ . **Boldface** limits apply at the temperature extremes.

| Symbol     | Parameter   | Conditions   | Min          | Typ                   | Max                   | Units                        |
|------------|---|--|--------------|-----------------------|-----------------------|------------------------------|
| $V_{OS}$   | Input Offset Voltage  |  |              | 0.8                   | 25<br><b>35</b>       | $\mu\text{V}$                |
|            | Offset Calibration Time                                       |  |              | 0.5                   | 10<br><b>12</b>       | ms                           |
| $TCV_{OS}$ | Input Offset Voltage  |  |              | 0.015                 |                       | $\mu\text{V}/^\circ\text{C}$ |
|            | Long-Term Offset Drift  |  |              | 0.006                 |                       | $\mu\text{V}/\text{month}$   |
|            | Lifetime $V_{OS}$ Drift                                       |  |              | 2.5                   | 5                     | $\mu\text{V}$                |
| $I_{IN}$   | Input Current   |  |              | -3                    |                       | pA                           |
| $I_{OS}$   | Input Offset Current  |  |              | 6                     |                       | pA                           |
| $R_{IND}$  | Input Differential Resistance                                 |  |              | 9                     |                       | $M\Omega$                    |
| CMRR       | Common Mode Rejection Ratio                                   | $-0.3 \leq V_{CM} \leq 0.9V$                                   |              | 130                   | 95                    | dB                           |
|            |   | $0 \leq V_{CM} \leq 0.9V$                                      |              |                       | <b>90</b>             |                              |
| PSRR       | Power Supply Rejection Ratio                                  | $2.7V \leq V^+ \leq 5V$  |              | 120                   | 95<br><b>90</b>       | dB                           |
| $A_{VOL}$  | Open Loop Voltage Gain  | $R_L = 10k\Omega$  |              | 130                   | 95<br><b>90</b>       | dB                           |
|            |   | $R_L = 2k\Omega$   |              | 124                   | 90<br><b>85</b>       |                              |
| $V_O$      | Output Swing  | $R_L = 10k\Omega$ to 1.35V<br>$V_{IN}(\text{diff}) = \pm 0.5V$ | 2.665        | 2.68                  |                       | V                            |
|            |   |  | <b>2.655</b> | 0.033                 | 0.060<br><b>0.075</b> |                              |
|            | $R_L = 2k\Omega$ to 1.35V<br>$V_{IN}(\text{diff}) = \pm 0.5V$ | 2.630  | 2.65         |                       | V                     |                              |
|            |   | <b>2.615</b>   | 0.061        | 0.085<br><b>0.105</b> |                       |                              |
| $I_O$      | Output Current  | Sourcing, $V_O = 0V$<br>$V_{IN}(\text{diff}) = \pm 0.5V$       |              | 12                    | 5<br><b>3</b>         | mA                           |
|            |   | Sinking, $V_O = 5V$<br>$V_{IN}(\text{diff}) = \pm 0.5V$        |              | 18                    | 5<br><b>3</b>         |                              |
| $R_{OUT}$  | Output Impedance  |  |              | 0.05                  |                       | $\Omega$                     |
| $I_S$      | Supply Current  |  |              | 0.919                 | 1.20<br><b>1.50</b>   | mA                           |

## 2.7V AC Electrical Characteristics

$T_J = 25^\circ\text{C}$ ,  $V^+ = 2.7\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{\text{CM}} = 1.35\text{V}$ ,  $V_O = 1.35\text{V}$ , and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

| Symbol             | Parameter                    | Conditions                                      | Min   | Typ | Max | Units                        |
|--------------------|------------------------------|---|-------|-----|-----|------------------------------|
| GBW                | Gain-Bandwidth Product       |   |       | 3   |     | MHz                          |
| SR                 | Slew Rate                    |   |       | 4   |     | V/ $\mu\text{s}$             |
| $\theta_m$         | Phase Margin                 |   |       | 60  |     | Deg                          |
| $G_m$              | Gain Margin                  |   |       | -14 |     | dB                           |
| $e_n$              | Input-Referred Voltage Noise |   |       | 35  |     | $\text{nV}/\sqrt{\text{Hz}}$ |
| $i_n$              | Input-Referred Current Noise |   |       | 150 |     | $\text{fA}/\sqrt{\text{Hz}}$ |
| $e_{\text{n-p-p}}$ | Input-Referred Voltage Noise | $R_S = 100\Omega$ , DC to 10Hz                  |       | 850 |     | $\text{nV}_{\text{pp}}$      |
| $t_{\text{rec}}$   | Input Overload Recovery Time |   |       | 50  |     | ms                           |
| $t_s$              | Output Settling Time         | $A_V = -1$ , $R_L = 2\text{k}\Omega$<br>1V Step | 1%    | 0.9 |     | $\mu\text{s}$                |
|                    |                              |   | 0.1%  | 49  |     |                              |
|                    |                              |   | 0.01% | 100 |     |                              |

## 5V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for  $T_J = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{\text{CM}} = 2.5\text{V}$ ,  $V_O = 2.5\text{V}$  and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

| Symbol                   | Parameter                      | Conditions   | Min          | Typ   | Max                 | Units                        |
|--------------------------|--------------------------------|--|--------------|-------|---------------------|------------------------------|
| $V_{\text{OS}}$          | Input Offset Voltage           |  |              | 0.12  | 25<br><b>35</b>     | $\mu\text{V}$                |
|                          | Offset Calibration Time        |  |              | 0.5   | 10<br><b>12</b>     | ms                           |
| $\text{TCV}_{\text{OS}}$ | Input Offset Voltage           |  |              | 0.015 |                     | $\mu\text{V}/^\circ\text{C}$ |
|                          | Long-Term Offset Drift         |  |              | 0.006 |                     | $\mu\text{V}/\text{month}$   |
|                          | Lifetime $V_{\text{OS}}$ Drift |  |              | 2.5   | 5                   | $\mu\text{V}$                |
| $I_{\text{IN}}$          | Input Current                  |  |              | -3    |                     | pA                           |
| $I_{\text{OS}}$          | Input Offset Current           |  |              | 6     |                     | pA                           |
| $R_{\text{IND}}$         | Input Differential Resistance  |  |              | 9     |                     | $\text{M}\Omega$             |
| CMRR                     | Common Mode Rejection Ratio    | $-0.3 \leq V_{\text{CM}} \leq 3.2$   |              | 130   | 100                 | dB                           |
|                          |                                | $0 \leq V_{\text{CM}} \leq 3.2$  |              |       | <b>90</b>           |                              |
| PSRR                     | Power Supply Rejection Ratio   | $2.7\text{V} \leq V^+ \leq 5\text{V}$  |              | 120   | 95<br><b>90</b>     | dB                           |
| $A_{\text{VOL}}$         | Open Loop Voltage Gain         | $R_L = 10\text{k}\Omega$   |              | 130   | 105<br><b>100</b>   | dB                           |
|                          |                                | $R_L = 2\text{k}\Omega$  |              | 132   | 95<br><b>90</b>     |                              |
| $V_O$                    | Output Swing                   | $R_L = 10\text{k}\Omega$ to 2.5V<br>$V_{\text{IN}}(\text{diff}) = \pm 0.5\text{V}$ | 4.96         | 4.978 |                     | V                            |
|                          |                                |  | <b>4.95</b>  |       | 0.040               |                              |
|                          |                                | $R_L = 2\text{k}\Omega$ to 2.5V<br>$V_{\text{IN}}(\text{diff}) = \pm 0.5\text{V}$  | 4.895        | 4.919 |                     | V                            |
|                          |                                |  | <b>4.875</b> |       | 0.091               |                              |
| $I_O$                    | Output Current                 | Sourcing, $V_O = 0\text{V}$<br>$V_{\text{IN}}(\text{diff}) = \pm 0.5\text{V}$      |              | 15    | 8<br><b>6</b>       | mA                           |
|                          |                                | Sinking, $V_O = 5\text{V}$<br>$V_{\text{IN}}(\text{diff}) = \pm 0.5\text{V}$       |              | 17    | 8<br><b>6</b>       |                              |
| $R_{\text{OUT}}$         | Output Impedance               |  |              | 0.05  |                     | $\Omega$                     |
| $I_S$                    | Supply Current per Channel     |  |              | 0.930 | 1.20<br><b>1.50</b> | mA                           |

## 5V AC Electrical Characteristics

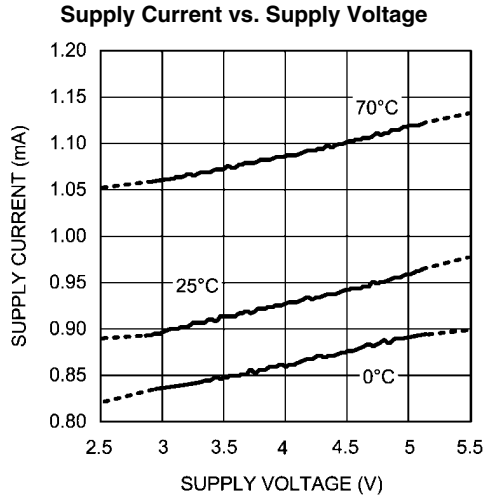
 $T_J = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{\text{CM}} = 2.5\text{V}$ ,  $V_O = 2.5\text{V}$ , and  $R_L > 1\text{M}\Omega$ .

**Boldface** limits apply at the temperature extremes.

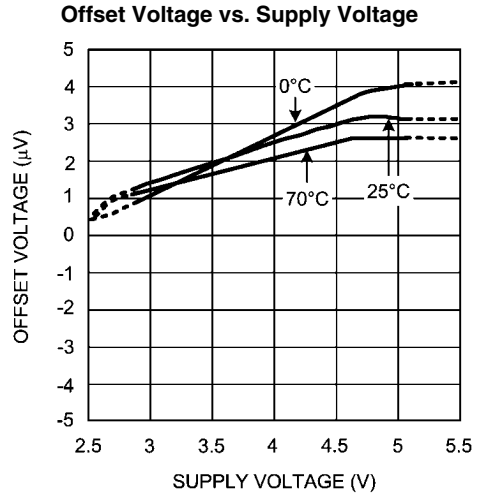
| Symbol           | Parameter                    | Conditions                                      | Min   | Typ | Max | Units                  |
|------------------|------------------------------|---|-------|-----|-----|------------------------|
| GBW              | Gain-Bandwidth Product       |   |       | 3   |     | MHz                    |
| SR               | Slew Rate                    |   |       | 4   |     | V/ $\mu\text{s}$       |
| $\theta_m$       | Phase Margin                 |   |       | 60  |     | deg                    |
| $G_m$            | Gain Margin                  |   |       | -15 |     | dB                     |
| $e_n$            | Input-Referred Voltage Noise |   |       | 35  |     | nV/ $\sqrt{\text{Hz}}$ |
| $i_n$            | Input-Referred Current Noise |   |       | 150 |     | fA/ $\sqrt{\text{Hz}}$ |
| $e_{n,p-p}$      | Input-Referred Voltage Noise | $R_S = 100\Omega$ , DC to 10Hz                  |       | 850 |     | nV <sub>pp</sub>       |
| $t_{\text{rec}}$ | Input Overload Recovery Time |   |       | 50  |     | ms                     |
| $t_s$            | Output Settling Time         | $A_V = -1$ , $R_L = 2\text{k}\Omega$<br>1V Step | 1%    | 0.8 |     | us                     |
|                  |                              |   | 0.1%  | 36  |     |                        |
|                  |                              |   | 0.01% | 100 |     |                        |

**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and test conditions, see the Electrical Characteristics.

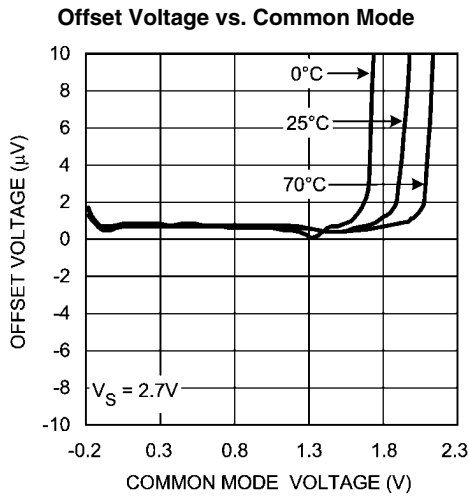
**Typical Performance Characteristics**  $T_A=25^\circ\text{C}$ ,  $V_S=5\text{V}$  unless otherwise specified.



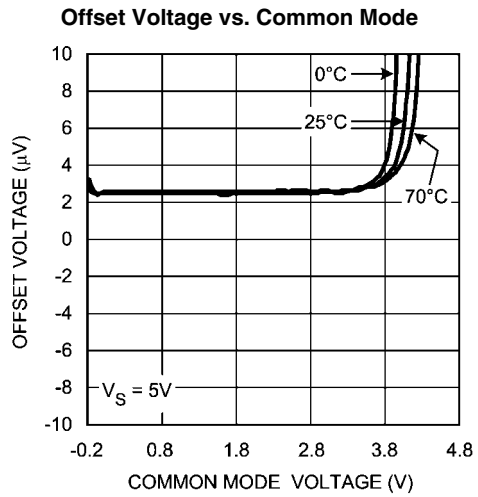
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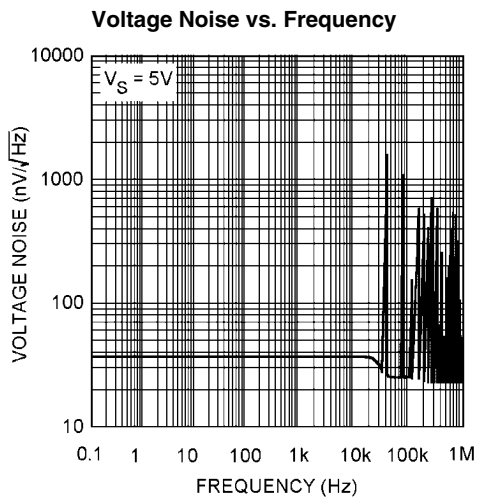
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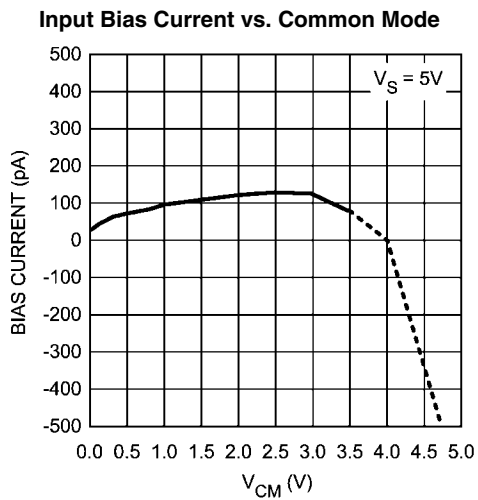
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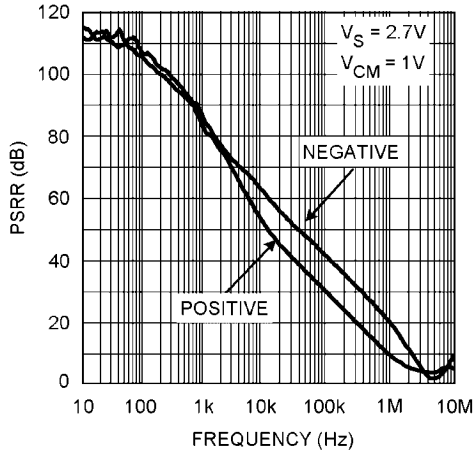


20051504



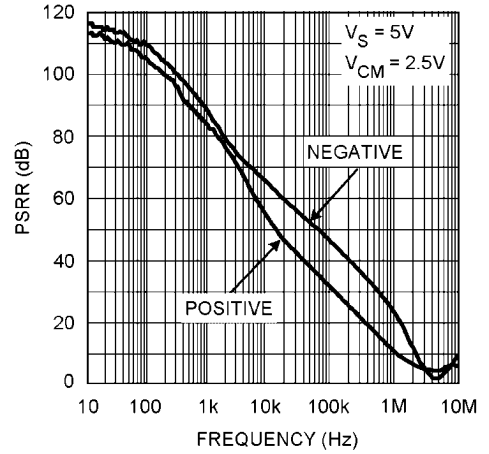
20051503

PSRR vs. Frequency



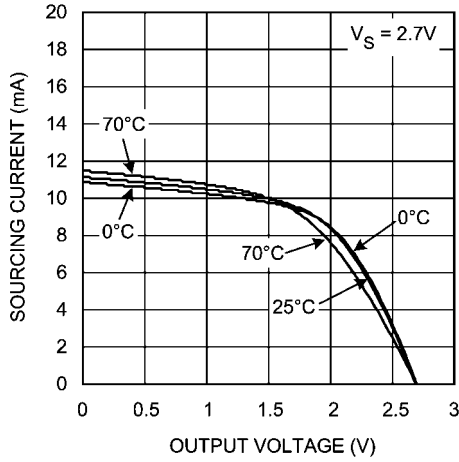
20051507

PSRR vs. Frequency



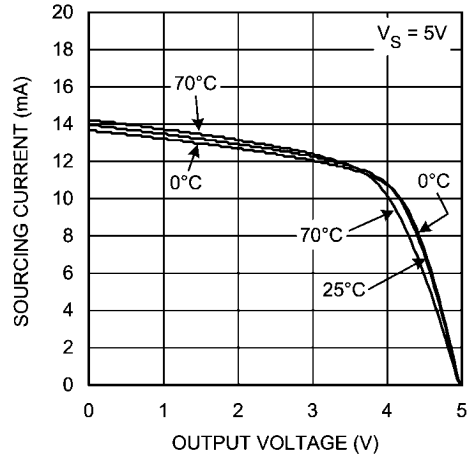
20051506

Output Sourcing @ 2.7V



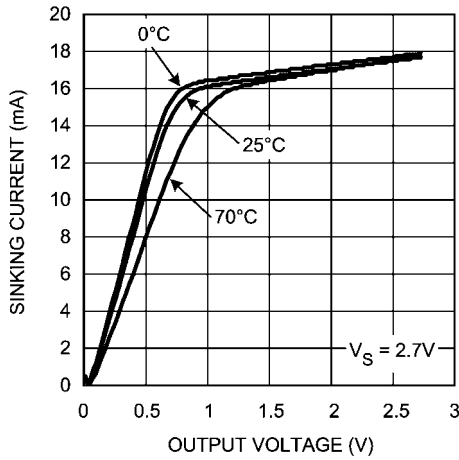
20051526

Output Sourcing @ 5V



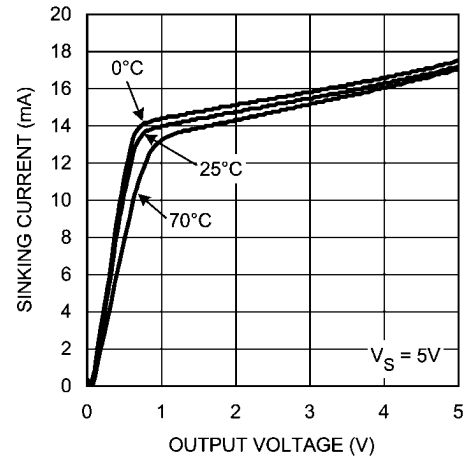
20051527

Output Sinking @ 2.7V



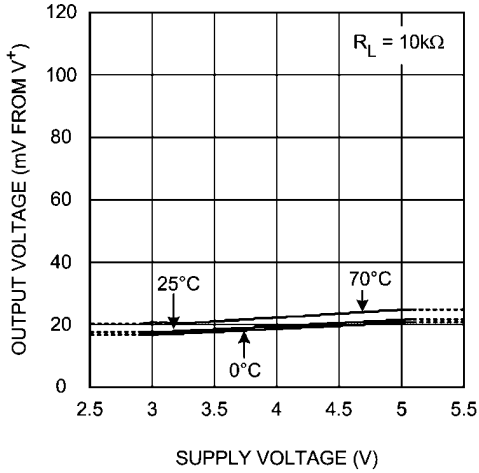
20051528

Output Sinking @ 5V



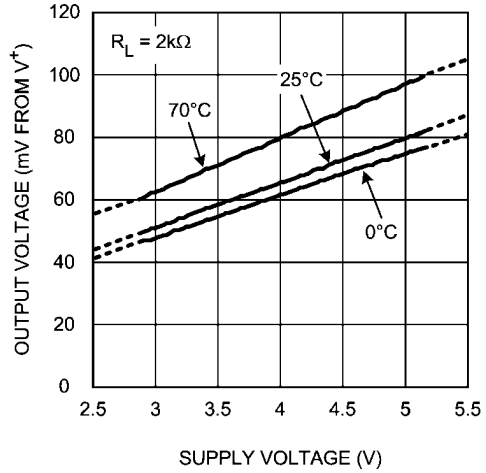
20051529

Max Output Swing vs. Supply Voltage



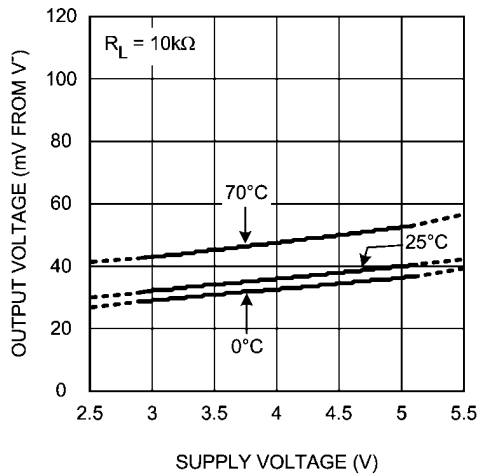
20051530

Max Output Swing vs. Supply Voltage



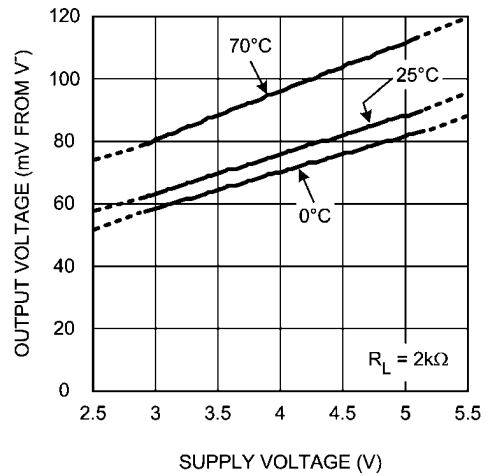
20051531

Min Output Swing vs. Supply Voltage



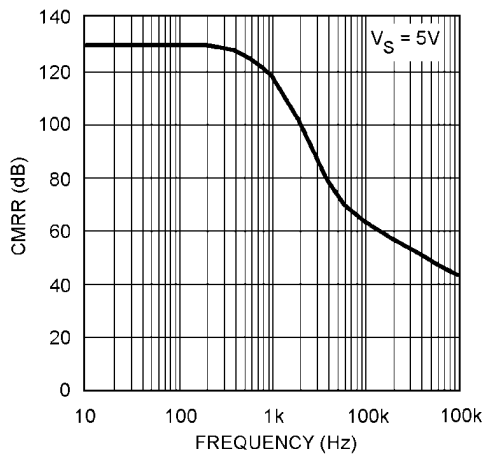
20051532

Min Output Swing vs. Supply Voltage



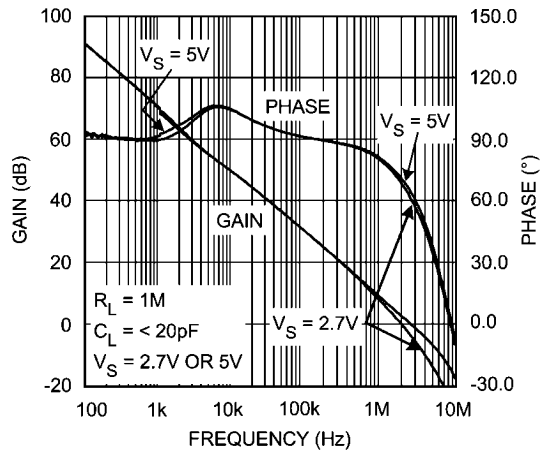
20051533

CMRR vs. Frequency



20051505

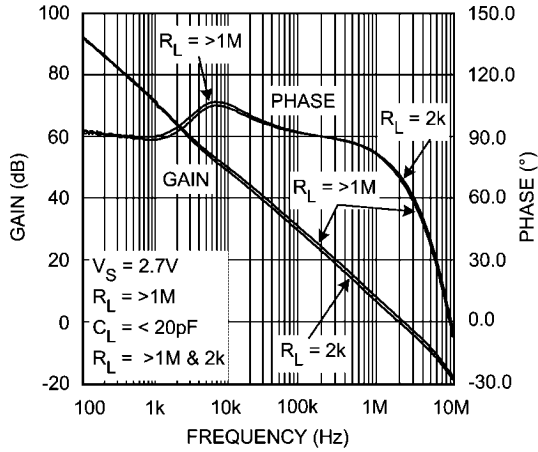
Open Loop Gain and Phase vs. Supply Voltage



20051508

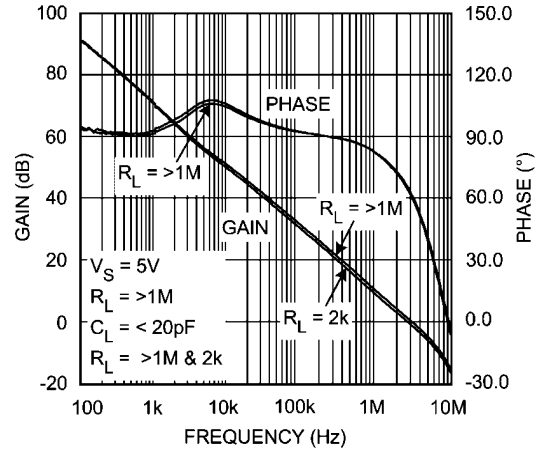


Open Loop Gain and Phase vs.  $R_L$  @ 2.7V



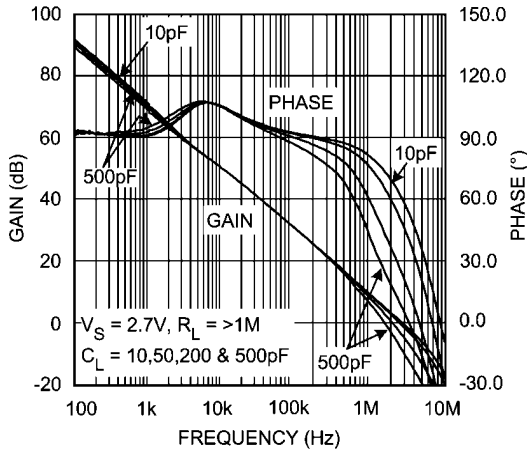
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Open Loop Gain and Phase vs.  $R_L$  @ 5V



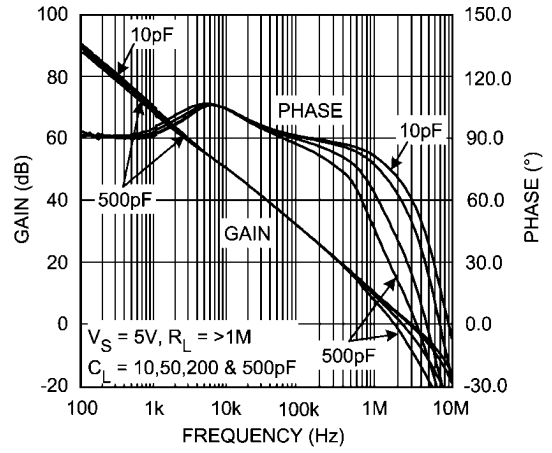
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Open Loop Gain and Phase vs.  $C_L$  @ 2.7V



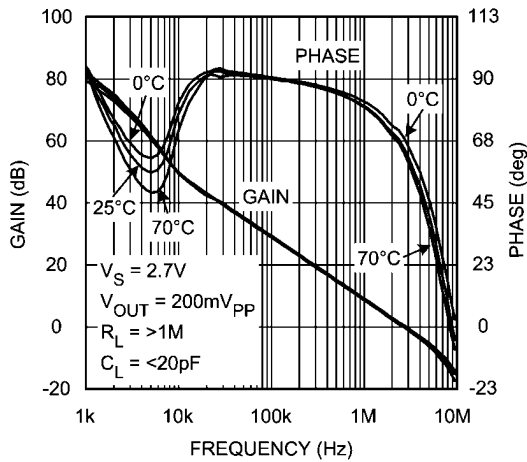
20051511

Open Loop Gain and Phase vs.  $C_L$  @ 5V



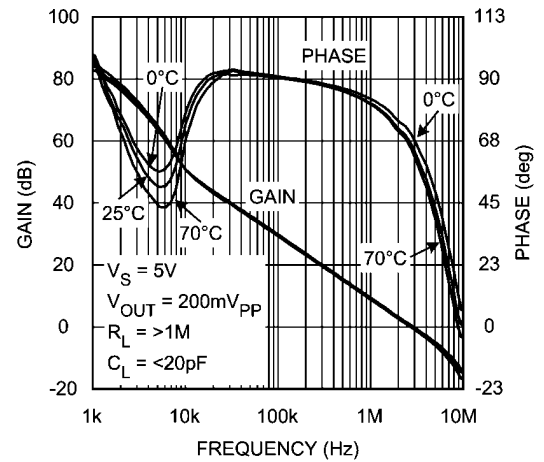
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Open Loop Gain and Phase vs. Temperature @ 2.7V

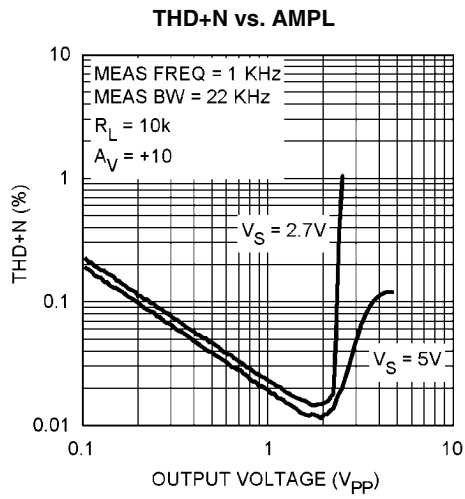


20051536

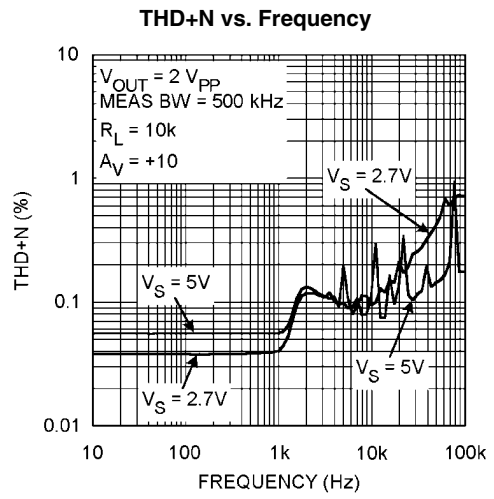
Open Loop Gain and Phase vs. Temperature @ 5V



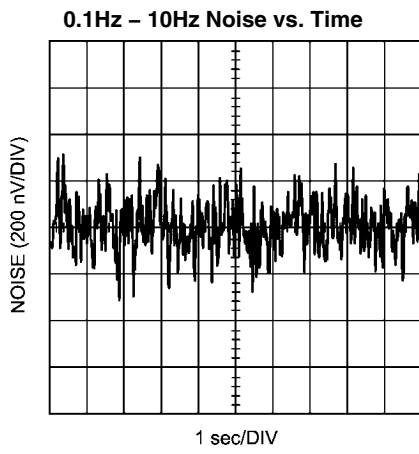
20051537



20051514



20051513



20051515

## Application Information

### THE BENEFITS OF LMV2011 NO 1/f NOISE

Using patented methods, the LMV2011 eliminates the 1/f noise present in other amplifiers. That noise, which increases as frequency decreases, is a major source of measurement error in all DC-coupled measurements. Low-frequency noise appears as a constantly-changing signal in series with any measurement being made. As a result, even when the measurement is made rapidly, this constantly-changing noise signal will corrupt the result. The value of this noise signal can be surprisingly large. For example: If a conventional amplifier has a flat-band noise level of  $10\text{nV}/\sqrt{\text{Hz}}$  and a noise corner of 10Hz, the RMS noise at 0.001Hz is  $1\mu\text{V}/\sqrt{\text{Hz}}$ . This is equivalent to a 0.50 $\mu\text{V}$  peak-to-peak error, in the frequency range 0.001 Hz to 1.0 Hz. In a circuit with a gain of 1000, this produces a 0.50mV peak-to-peak output error. This number of 0.001 Hz might appear unreasonably low, but when a data acquisition system is operating for 17 minutes, it has been on long enough to include this error. In this same time, the LMV2011 will only have a 0.21mV output error. This is smaller by 2.4 x. Keep in mind that this 1/f error gets even larger at lower frequencies. At the extreme, many people try to reduce this error by integrating or taking several samples of the same signal. This is also doomed to failure because the 1/f nature of this noise means that taking longer samples just moves the measurement into lower frequencies where the noise level is even higher.

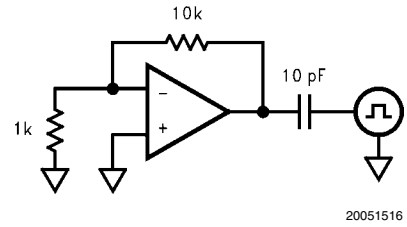
The LMV2011 eliminates this source of error. The noise level is constant with frequency so that reducing the bandwidth reduces the errors caused by noise.

Another source of error that is rarely mentioned is the error voltage caused by the inadvertent thermocouples created when the common "Kovar type" IC package lead materials are soldered to a copper printed circuit board. These steel-based leadframe materials can produce over  $35\mu\text{V}/^\circ\text{C}$  when soldered onto a copper trace. This can result in thermocouple noise that is equal to the LMV2011 noise when there is a temperature difference of only  $0.0014^\circ\text{C}$  between the lead and the board!

For this reason, the lead-frame of the LMV2011 is made of copper. This results in equal and opposite junctions which cancel this effect. The extremely small size of the SOT-23 package results in the leads being very close together. This further reduces the probability of temperature differences and hence decreases thermal noise.

### OVERLOAD RECOVERY

The LMV2011 recovers from input overload much faster than most chopper-stabilized opamps. Recovery from driving the amplifier to 2X the full scale output, only requires about 40ms. Many chopper-stabilized amplifiers will take from 250ms to several seconds to recover from this same overload. This is because large capacitors are used to store the unadjusted offset voltage.



20051516

FIGURE 1. Overload Recovery Test

The wide bandwidth of the LMV2011 enhances performance when it is used as an amplifier to drive loads that inject transients back into the output. ADCs (Analog-to-Digital Converters) and multiplexers are examples of this type of load. To simulate this type of load, a pulse generator producing a 1V peak square wave was connected to the output through a 10pF capacitor. (Figure 1) The typical time for the output to recover to 1% of the applied pulse is 80ns. To recover to 0.1% requires 860ns. This rapid recovery is due to the wide bandwidth of the output stage and large total GBW.

### NO EXTERNAL CAPACITORS REQUIRED

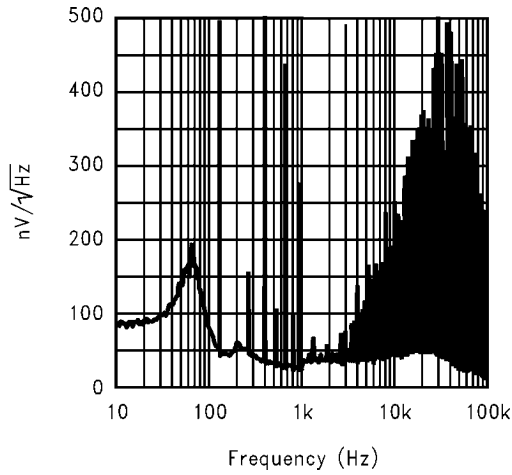
The LMV2011 does not need external capacitors. This eliminates the problems caused by capacitor leakage and dielectric absorption, which can cause delays of several seconds from turn-on until the amplifier's error has settled.

### MORE BENEFITS

The LMV2011 offers the benefits mentioned above and more. It has a rail-to-rail output and consumes only 950 $\mu\text{A}$  of supply current while providing excellent DC and AC electrical performance. In DC performance, the LMC2001 achieves 130dB of CMRR, 120dB of PSRR and 130dB of open loop gain. In AC performance, the LMV2011 provides 3MHz of gain-bandwidth product and 4V/ $\mu\text{s}$  of slew rate.

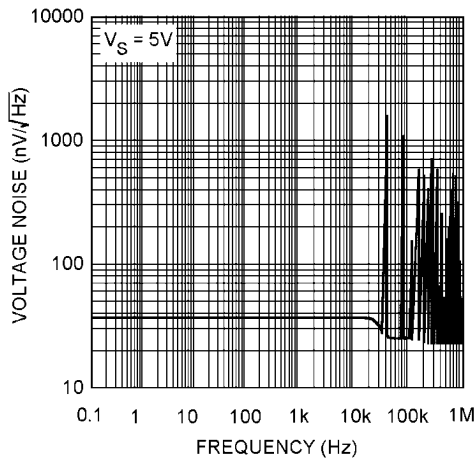
### HOW THE LMV2011 WORKS

The LMV2011 uses new, patented techniques to achieve the high DC accuracy traditionally associated with chopper-stabilized amplifiers without the major drawbacks produced by chopping. The LMV2011 continuously monitors the input offset and corrects this error. The conventional chopping process produces many mixing products, both sums and differences, between the chopping frequency and the incoming signal frequency. This mixing causes large amounts of distortion, particularly when the signal frequency approaches the chopping frequency. Even without an incoming signal, the chopper harmonics mix with each other to produce even more trash. If this sounds unlikely or difficult to understand, look at the plot (Figure 2), of the output of a typical (MAX432) chopper-stabilized opamp. This is the output when there is no incoming signal, just the amplifier in a gain of -10 with the input grounded. The chopper is operating at about 150Hz; the rest is mixing products. Add an input signal and the noise gets much worse. Compare this plot with Figure 3 of the LMV2011. This data was taken under the exact same conditions. The auto-zero action is visible at about 30kHz but note the absence of mixing products at other frequencies. As a result, the LMV2011 has very low distortion of 0.02% and very low mixing products.



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FIGURE 2. The Output of a Chopper Stabilized Op Amp (MAX432)



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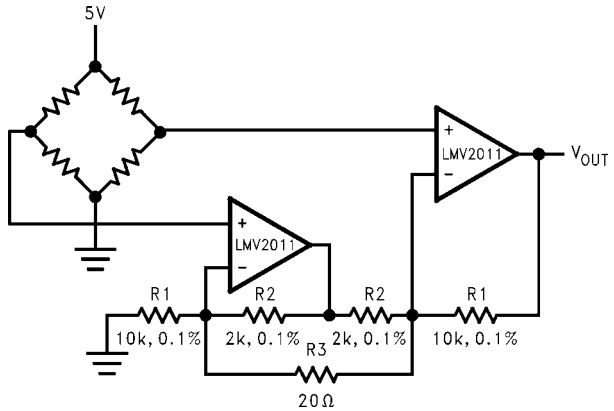
FIGURE 3. The Output of the LMV2011

**INPUT CURRENTS**

The LMV2011's input currents are different than standard bipolar or CMOS input currents in that it appears as a current flowing in one input and out the other. Under most operating conditions, these currents are in the picoamp level and will have little or no effect in most circuits. These currents tend to increase slightly when the common-mode voltage is near the minus supply. (See the typical curves.) At high temperatures such as 85°C, the input currents become larger, 0.5nA typical, and are both positive except when the  $V_{CM}$  is near  $V^-$ . If operation is expected at low common-mode voltages and high temperature, do not add resistance in series with the inputs to balance the impedances. Doing this can cause an increase in offset voltage. A small resistance such as 1kΩ can provide some protection against very large transients or overloads, and will not increase the offset significantly.

**PRECISION STRAIN-GAUGE AMPLIFIER**

This Strain-Gauge amplifier (Figure 4) provides high gain (1006 or ~60 dB) with very low offset and drift. Using the resistors' tolerances as shown, the worst case CMRR will be greater than 108 dB. The CMRR is directly related to the resistor mismatch. The rejection of common-mode error, at the output, is independent of the differential gain, which is set by R3. The CMRR is further improved, if the resistor ratio matching is improved, by specifying tighter-tolerance resistors, or by trimming.

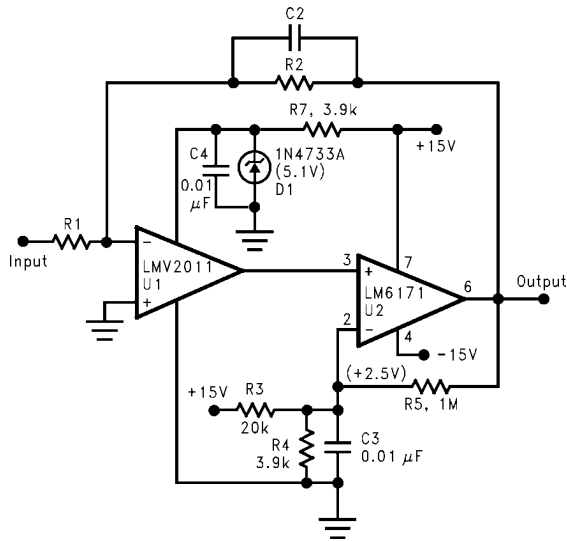


20051518

FIGURE 4. Precision Strain Gauge Amplifier

**Extending Supply Voltages and Output Swing by Using a Composite Amplifier Configuration:**

In cases where substantially higher output swing is required with higher supply voltages, arrangements like the ones shown in Figure 5 and Figure 6 could be used. These configurations utilize the excellent DC performance of the LMV2011 while at the same time allow the superior voltage and frequency capabilities of the LM6171 to set the dynamic performance of the overall amplifier. For example, it is possible to achieve ±12V output swing with 300MHz of overall GBW ( $A_v = 100$ ) while keeping the worst case output shift due to  $V_{OS}$  less than 4mV. The LMV2011 output voltage is kept at about mid-point of its overall supply voltage, and its input common mode voltage range allows the  $V^-$  terminal to be grounded in one case (Figure 5, inverting operation) and tied to a small non-critical negative bias in another (Figure 6, non-inverting operation). Higher closed-loop gains are also possible with a corresponding reduction in realizable bandwidth. Table 1 shows some other closed loop gain possibilities along with the measured performance in each case.



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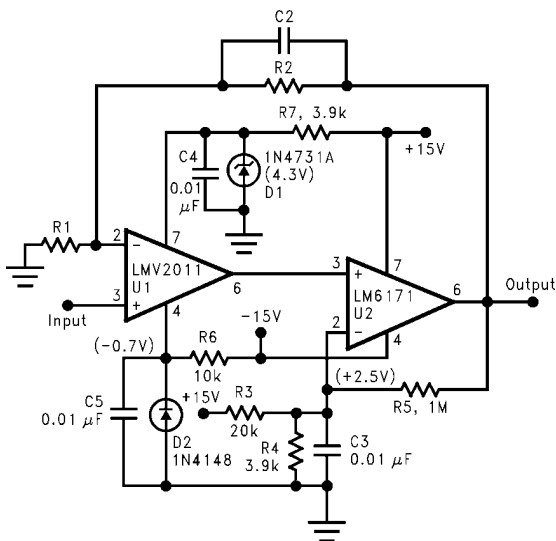
FIGURE 5. Composite Amplifier Configuration

TABLE 1. Composite Amplifier Measured Performance

| $A_V$ | R1<br>( $\Omega$ ) | R2<br>( $\Omega$ ) | C2<br>(pF) | BW<br>(MHz) | SR<br>(V/ $\mu$ s) | $e_{n\text{ p-p}}$<br>(mV <sub>PP</sub> ) |
|-------|--------------------|--------------------|------------|-------------|--------------------|---|
| 50    | 200                | 10k                | 8          | 3.3         | 178                | 37  |
| 100   | 100                | 10k                | 10         | 2.5         | 174                | 70  |
| 100   | 1k                 | 100k               | 0.67       | 3.1         | 170                | 70  |
| 500   | 200                | 100k               | 1.75       | 1.4         | 96                 | 250                                       |
| 1000  | 100                | 100k               | 2.2        | 0.98        | 64                 | 400                                       |

In terms of the measured output peak-to-peak noise, the following relationship holds between output noise voltage,  $e_{n\text{ p-p}}$ , for different closed-loop gain,  $A_V$ , settings, where -3dB Bandwidth is BW:

$$\frac{e_{npp1}}{e_{npp2}} = \sqrt{\frac{BW1}{BW2}} \cdot \frac{A_V1}{A_V2} \quad (1)$$

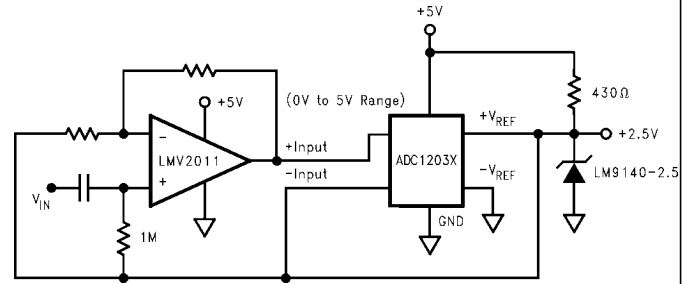


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FIGURE 6. Composite Amplifier Configuration

It should be kept in mind that in order to minimize the output noise voltage for a given closed-loop gain setting, one could minimize the overall bandwidth. As can be seen from Equation 1 above, the output noise has a square-root relationship to the Bandwidth.

In the case of the inverting configuration, it is also possible to increase the input impedance of the overall amplifier, by raising the value of R1, without having to increase the feed-back resistor, R2, to impractical values, by utilizing a "Tee" network as feedback. See the LMC6442 data sheet (Application Notes section) for more details on this.



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FIGURE 7. AC Coupled ADC Driver

### LMV2011 AS ADC INPUT AMPLIFIER

The LMV2011 is a great choice for an amplifier stage immediately before the input of an ADC (Analog-to-Digital Converter), whether AC or DC coupled. See Figure 7 and Figure 8. This is because of the following important characteristics:

- A) Very low offset voltage and offset voltage drift over time and temperature allow a high closed-loop gain setting without introducing any short-term or long-term errors. For example, when set to a closed-loop gain of 100 as the analog input amplifier for a 12-bit A/D converter, the overall conversion error over full operation temperature and 30 years life of the part (operating at 50°C) would be less than 5 LSBs.
- B) Fast large-signal settling time to 0.01% of final value (1.4 $\mu$ s) allows 12 bit accuracy at 100KHz or more sampling rate.
- C) No flicker (1/f) noise means unsurpassed data accuracy over any measurement period of time, no matter how long. Consider the following opamp performance, based on a typical low-noise, high-performance commercially-available device, for comparison:

$$\text{Opamp flatband noise} = 8nV/\sqrt{\text{Hz}}$$

$$1/f \text{ corner frequency} = 100\text{Hz}$$

$$A_V = 2000$$

$$\text{Measurement time} = 100 \text{ sec}$$

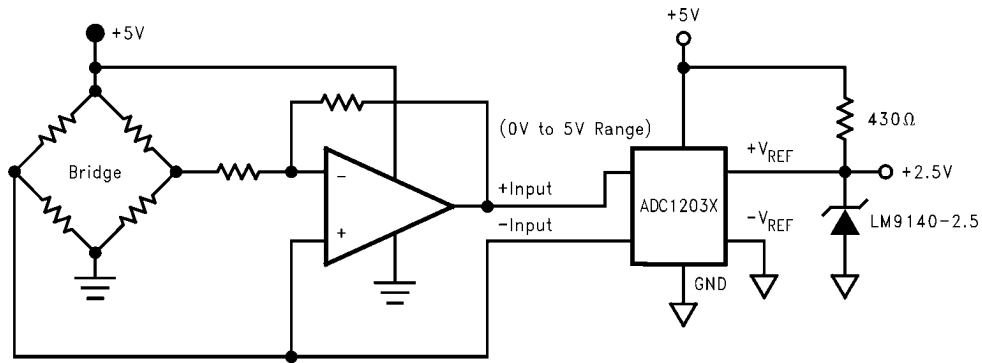
$$\text{Bandwidth} = 2\text{Hz}$$

This example will result in about 2.2 mV<sub>PP</sub> (1.9 LSB) of output noise contribution due to the opamp alone, compared to about 594 $\mu$ V<sub>PP</sub> (less than 0.5 LSB) when that opamp is replaced with the LMV2011 which has no 1/f contribution. If the measurement time is increased from 100 seconds to 1 hour, the improvement realized by using the LMV2011 would be a factor of about 4.8 times (2.86mV<sub>PP</sub> compared to 596 $\mu$ V when LMV2011 is used) mainly because the LMV2011 accuracy is not compromised by increasing the observation time.

- D) Copper leadframe construction minimizes any thermo-couple effects which would degrade low level/high gain

data conversion application accuracy (see discussion under "The Benefits of the LMV2011" section above).

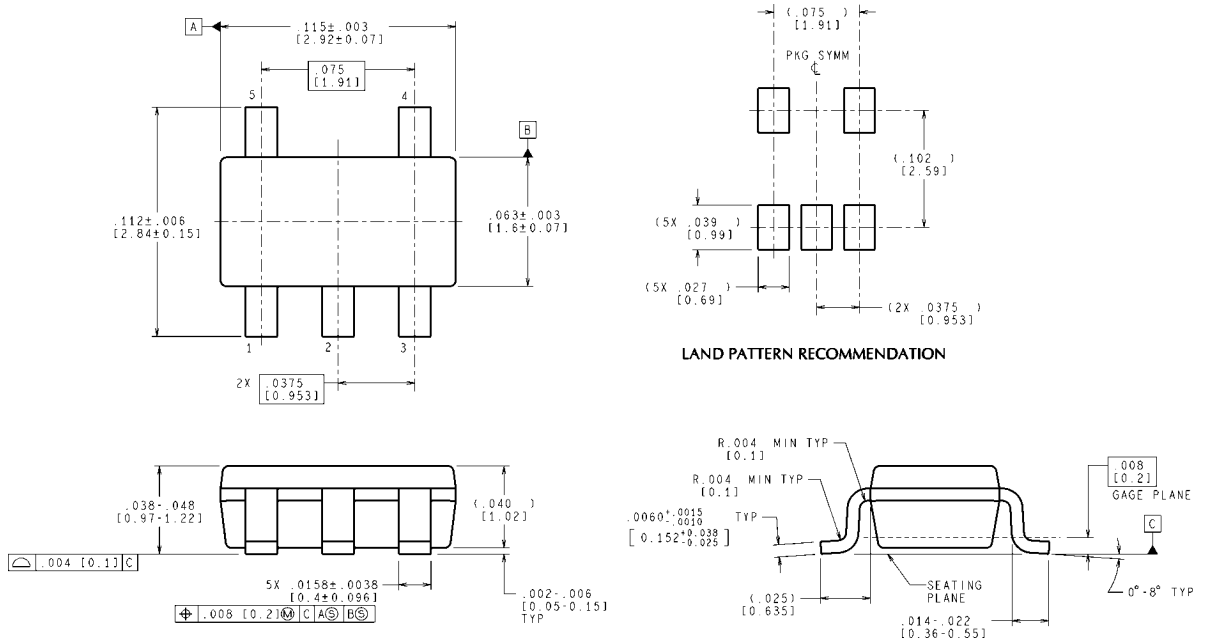
E) Rail-to-Rail output swing maximizes the ADC dynamic range in 5-Volt single-supply converter applications. Below are some typical block diagrams showing the LMV2011 used as an ADC amplifier (Figure 7 and Figure 8).



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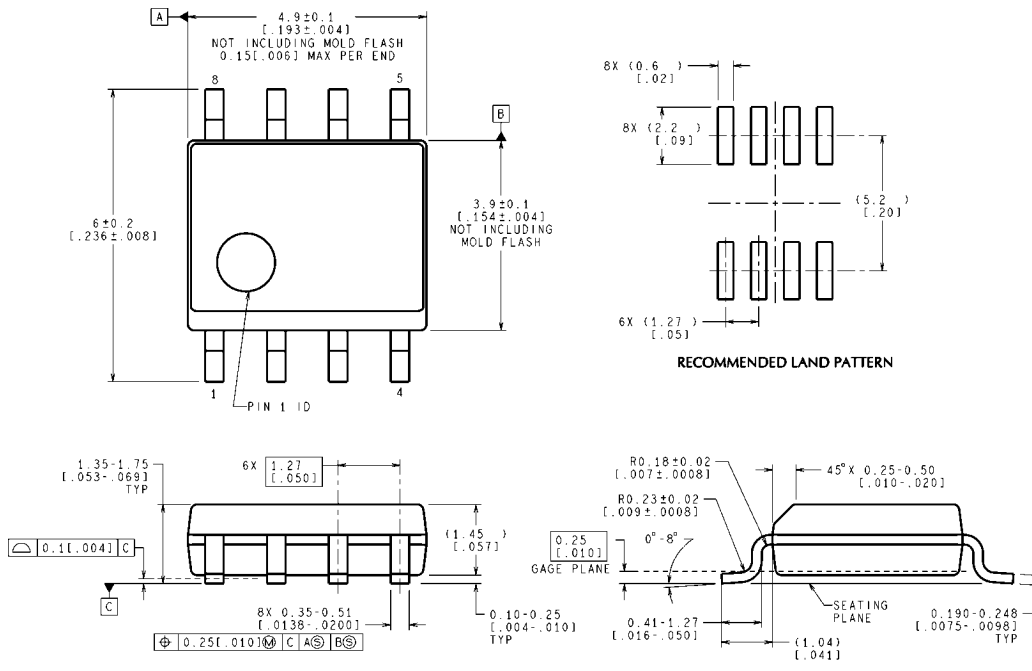
FIGURE 8. DC Coupled ADC Driver

**Physical Dimensions** inches (millimeters) unless otherwise noted



MF05A (Rev C)

**5-Pin SOT23  
NS Package Number MF0A5**



M08A (Rev L)

**8-Pin SOIC  
NS Package Number M08A**

# Notes

LMV2011



## Notes

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| Interface                      | <a href="http://www.national.com/interface">www.national.com/interface</a>     | Quality and Reliability | <a href="http://www.national.com/quality">www.national.com/quality</a>             |
| LVDS                           | <a href="http://www.national.com/lvds">www.national.com/lvds</a>               | Reference Designs       | <a href="http://www.national.com/refdesigns">www.national.com/refdesigns</a>       |
| Power Management               | <a href="http://www.national.com/power">www.national.com/power</a>             | Feedback                | <a href="http://www.national.com/feedback">www.national.com/feedback</a>           |
| Switching Regulators           | <a href="http://www.national.com/switchers">www.national.com/switchers</a>     |                         |  |
| LDOs                           | <a href="http://www.national.com/lido">www.national.com/lido</a>               |                         |  |
| LED Lighting                   | <a href="http://www.national.com/led">www.national.com/led</a>                 |                         |  |
| PowerWise                      | <a href="http://www.national.com/powerwise">www.national.com/powerwise</a>     |                         |  |
| Serial Digital Interface (SDI) | <a href="http://www.national.com/sdi">www.national.com/sdi</a>                 |                         |  |
| Temperature Sensors            | <a href="http://www.national.com/tempsensors">www.national.com/tempsensors</a> |                         |  |
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