

SANYO Semiconductors

DATA SHEET

STK621-061-E, STK621-061A-E

Thick-Film Hybrid IC 3-phase Inverter Motor Drive Inverter Hybrid IC

Overview

The STK621-061-E and STK621-061A-E are 3-phase inverter power hybrid IC containing power elements (IGBT and FRD), pre-driver, overcurrent and excessive temperature protection circuit.

Applications

• 3-phase inverter motor drive.

Features

- Integrates power elements (IGBT and FRD), pre-driver, and protective circuit.
- Protective circuits including overcurrent (bus line), excessive temperature and pre-drive low voltage protection are built in.
- Direct input of CMOS level control signals without an insulating circuit (photocoupler, etc) is possible.
- Single power supply drive is possible by using a bootstrap circuit with a built-in IC.
- Temperature monitor is possible by the thermistor inside the IC.
- Built-in simultaneous upper/lower ON prevention circuit to prevent arm shorting through simultaneous ON input for the upper and lower side transistors. (Dead time is required for preventing shorting due to switching delay.)
- SIP (The single in-line package) of the transfer full mold structure.

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Specifications

Absolute maximum ratings at $Tc = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VCC	+, Surge < 500V *1	450	V
Collector-emitter voltage	V _{CE}	+ - U (V, W) or U (V, W)	600	V
Output current	IO	+, -, U, V, W terminal current	±30	А
Output peak current	Іор	+, -, U, V, W terminal current PW=100µs	±45	А
Pre-driver supply voltage	V _D 1, 2, 3, 4	VB1 - U, VB2 - V, VB3 - W, V _{DD} - V _{SS} *2	20	V
Input signal voltage	VIN	HIN1, 2, 3, LIN1, 2, 3 terminal	0 to 7	V
FAULT terminal voltage	VFAULT	FAULT terminal	20	V
Maximum loss	Pd	IGBT, Per 1 channel	49	W
Junction temperature	Tj	IGBT, FRD junction temperature	150	°C
Storage temperature	Tstg		-40 to +125	°C
Operating temperature	TC	H-IC case temperature	-20 to +100	°C
Tightening torque	MT	A screw part at use M4 type screw *3	1.17	N∙m
Withstand voltage	Vis	50Hz sine wave AC 1 minute *4	2000	VRMS

In the case without the instruction, the voltage standard is - terminal = V_{SS} terminal voltage.

*1 Surge voltage developed by the switching operation due to the wiring inductance between the + and – terminals.

*2 VD1= between VB1-U, VD2=VB2-V, VD3=VB3-W, VB4=V_{DD}-V_{SS}, terminal voltage.

*3 Flatness of the heat-sink should be lower than 0.25mm.

*4 The test condition is AC 2500V, 1 second.

Electrical Characteristics at Tc=25°C, VD=15V

Parameters	Symbols	Conditions		min	typ	max	unit	Test circuit
Power output part								
Collector-to-emitter cut-off current	ICE	V _{CE} =600V				0.5	mA	Fig.1
Boot-strap diode reverse current	IR (BD)	VR (BD)=600V				0.5	mA	Fig.1
Collector-to-emitter saturation voltage	V _{CE} (SAT)	I _O =15A	Upper side		1.9	2.7	.,	51.0
			Lower side		2.1	2.9	V	Fig.2
Diode forward voltage	VF	I _O =-15A	Upper side		1.7	2.5		Fig.3
			Lower side		1.9	2.7	V	
Junction-to-substrate thermal resistance	on-to-substrate thermal resistance θj-c(T) IGBT			2.1				
	θj-c(D)	FWD			2.5		°C/W	
Control (Pre-driver) part								•
Pre-drive power supply consumption ID		VD1, 2, 3=15V			0.07	0.4		
electric current	VD4=15V				3.3	7	mA	Fig.4
Input ON voltage	VIH	Output ON				0.8	V	
Input OFF voltage	VIL	Output OFF		3.0			V	
Protection part								
Excessive temperature	TSD	The substra	te surface	100		120	°C	
Overcurrent protection electric current	ISD	PW=100μs		45		59	А	Fig.5
Pre-drive low voltage protection	UVLO			10		12	V	
FAULT terminal input electric current	IOSD	VFAULT =0	.1V		0.5		mA	
FAULT clearness delay time	FLTCLR	After each protection operation ending		18		80	ms	
Board temperature mounting resistance	Rt	Resistance between the FAULT and V _{SS} terminals		90		110	kΩ	
Switching time	tON	I _O =15A, Inc			0.8			
	tOFF				1.3		μs	Fig.6
Electric current output signal level	ISO	I _O =15A			0.141		V	

In the case without the instruction, the voltage standard is - terminal = V_{SS} terminal voltage.

Notes

1. Input ON voltage indicates a value to turn on output stage IGBT. Input OFF voltage indicates a value to turn off output stage IGBT.

At the time of output ON, set the input signal voltage 0V to $V_{\mbox{IH}}$ (max).

- At the time of output OFF, set the input signal voltage V_{IL} (min) to 5V.
- 2. When the internal protection circuit operates, there is a FAULT signal ON (When the FAULT terminal is low level, FAULT signal is ON state: output form is open DRAIN) but the FAULT signal doesn't latch.

After protection operation ends, it returns automatically within about 18ms to 80ms and resumes operation beginning condition. So, after FAULT signal detection, set OFF (HIGH) to all input signals at once.

However, the operation of pre-drive power supply low voltage protection (UVLO: it has a hysteresis about 0.3V) is as follows.

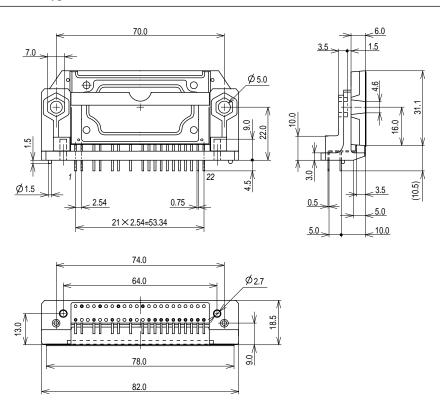
Lower side → It outputs FAULT signal with gate signal OFF. However, it is different from the protection operation of upper side, it is automatically resets about 18ms to 80ms later and resumes operation beginning condition when recovering to normal voltage. (The protection operation doesn't latch by the input signal.)

- 3. When assembling the hybrid IC on the heat sink with M4 type screw, tightening torque range is 0.79N•m to 1.17N•m. Flatness of the heat-sink should be lower than 0.25mm.
- 4. The pre-drive low voltage protection is the feature to protect a device when the pre-driver supply voltage declines with the operating malfunction. As for the pre-driver supply voltage decline in case of operation beginning, and so on, we request confirmation in the set.

[STK621-061-E]

Package Dimensions

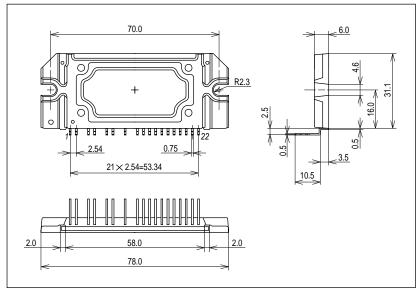
unit:mm (typ)



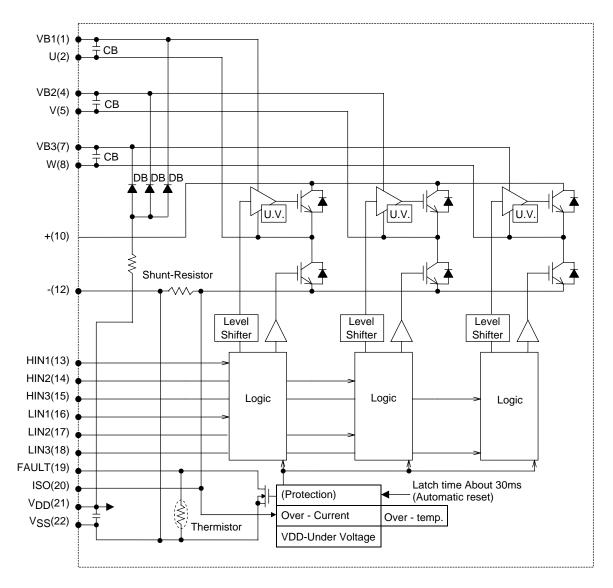
Package Dimensions

unit:mm (typ)

[STK621-061A-E]



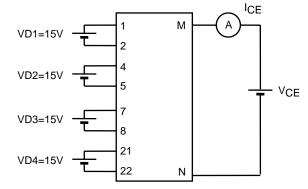
Internal Equivalent Circuit Diagram



Test Circuit

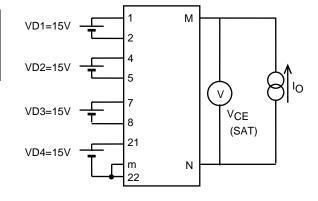
1: ICE

	U+	V+	W+	U-	V-	W-
М	10	10	10	2	5	8
N	2	5	8	12	12	12



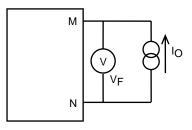
2: VCE (SAT)

	U+	V+	W+	U-	V-	W-
М	10	10	10	2	5	8
Ν	2	5	8	12	12	12
m	13	14	15	16	17	18



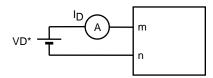
3: VF

	U+	V+	W+	U-	V-	W-
М	10	10	10	2	5	8
Ν	2	5	8	12	12	12

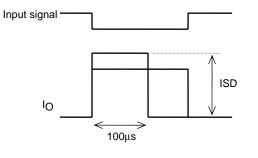


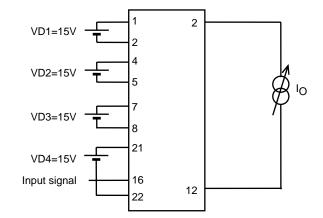
4: ID

	VD1	VD2	VD3	VD4
m	1	4	7	21
n	2	5	8	22

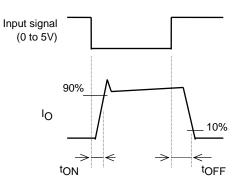


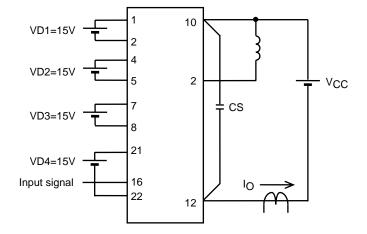
5: ISD



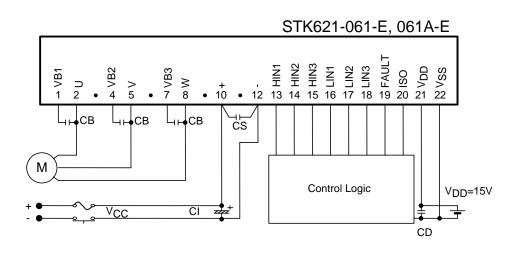


6: Switching time





Example of The Application Circuit



Parameters	Symbol	Conditions	min	typ	max	unit
Supply voltage	V _{CC}	+	0	280	400	V
Pre-driver supply voltage	VD1, 2, 3	VB1-U, VB2-V, VB3-W	12.5	15	17.5	
	VD4	V _{DD} -V _{SS} *1	13.5	15	16.5	V
ON input signal voltage	V _{IN} (ON)	HIN1, HIN2, HIN3, LIN1, LIN2, LIN3-V _{SS}	0		0.3	V
OFF input signal voltage	V _{IN} (OFF)	terminal	3.5		5	V
PWM frequency	fPWM		1		20	kHz
Dead time	DT	Upper/lower input signal downtime	2			μs
Tightening torque	МТ	'M4' type screw	0.79		1.17	N∙m

Recommended Operating Conditions

*1 Pre-driver power supply (VD4=15 \pm 1.5V) must have the capacity of I_O=20mA (DC), 0.5A (Peak).

Precautions

1. A control power supply can be driven with one power supply by attaching the capacitor CB (1 to max 47μ F) for a bootstrap. In this case, a bottom element is made to charge.

(When not using bootstrap circuit, each upper side pre-drive power supply needs an independent power supply. Externally set.)

In addition, please carry out capacity of the capacitor for a bootstrap (external) to $47\mu F (\pm 20\%)$. When $47\mu F (\pm 20\%)$ or more are connected, Please connect resistance (about 20Ω) also with 3-phase at series between each top power supply terminal (VB1, 2, and 3) and the capacitor for a bootstrap. Moreover, since top power supply voltage may be insufficient depending on the control method, Please carry out a check with the system.

- 2. Because the jump voltage which is accompanied by the vibration in case of switching operation occurs by the influence of the floating inductance of the wiring of the outer power supply which is connected with of the + terminal and the terminal, restrains and spares serge voltage being as the connection of the snubber circuit (Capacitor / CS / about 0.22 to 10 μ F) for the voltage absorption with the neighborhood as possible between + and the terminal, and so on, with making a wiring length (among the terminals each from CI) short and making a wiring inductance small.
- 3. ISO terminal (20pin) is for the electric current monitor. When the pull up with the resistance, use above $5.6k\Omega$ Be careful, because the over current protection does not operate when short-circuiting in the ISO terminal and the V_{SS} terminal.
- 4. Output form of the FAULT terminal is open DRAIN (it is operating as FAULT when becoming low). The STK621-061-E and STK621-061A-E has abuilt-in thermistor between the FAULT and V_{SS} terminals. It allows monitoring of the board temperature using the divided voltage developed with the pull-up resistance RP. Theresistance of the RP must be $10k\Omega$ or higher at a pull-up voltage of 5V and $39k\Omega$ or higher at pull-up voltage of 15V
- 5. Zener diode with 5V (5.0 to 5.4V) is connected with the inside of the signal input terminal. When inputting the voltage which exceeds 5V, connect resistor to between the side of the power and the signal input terminal, for the input current of the signal input terminal become equal to or less than 0.5mA. This resistor is effective with the noise absorption of the signal terminal, too.
- 6. The over current protection feature operates only when it is possible to do a circuit control normally. For the safety, put a fuse, and so on in the V_{CC} line.
- 7. Because the IC sometimes destroys and bursts when motor connection terminal (2pin, 5pin, 8pin) becomes open while the motor turns, especially, be careful of the connection (the soldering condition) of this terminal.
- If terminal and VSS terminal are short-circuited, since an over-current protection (ISD) value will become lower than the inside setting value of HIC, please do not connect externally. (– terminal and VSS terminal are connected inside HIC)

* This data shows the example of the application circuit, does not guarantee a design as the mass production set.

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