

SLWS197B-MARCH 2007-REVISED JUNE 2009

# QUAD CHANNEL, 12-BIT, 125-MSPS ADC WITH SERIAL LVDS INTERFACE

### **FEATURES**

- Maximum Sample Rate: 125 MSPS
- 12-Bit Resolution with No Missing Codes
- 1.65-W Total Power
- Simultaneous Sample and Hold
- 70.3 dBFS SNR at Fin = 50 MHz
- 83 dBc SFDR at Fin = 50 MHz, 0 dB Gain
- 79 dBc SFDR at Fin = 170 MHz, 3.5 dB Gain
- 3.5 dB Coarse Gain and up to 6 dB Programmable Fine Gain for SFDR/SNR Trade-Off
- Serialized LVDS Outputs with Programmable Internal Termination Option
- Supports Sine, LVCMOS, LVPECL, LVDS Clock Inputs and Amplitude Down to 400 mV<sub>pp</sub> Differential
- Internal Reference with External Reference
   Support
- No External Decoupling Required for References
- 3.3-V Analog and Digital Supply
- 64 QFN Package (9 mm × 9 mm)
- Pin Compatible 14-Bit Family (ADS644X SLAS532)

## APPLICATIONS

- Base-Station IF Receivers
- Diversity Receivers
- Medical Imaging
- Test Equipment

# DESCRIPTION

The ADS6425 is a high performance 12-bit, 125-MSPS quad channel ADC. Serial LVDS data outputs reduce the number of interface lines, resulting in a compact 64-pin QFN package (9 mm  $\times$  9 mm) that allows for high system integration density. The device includes a 3.5 dB coarse gain option that can be used to improve SFDR performance with little degradation in SNR. In addition to the coarse gain, fine gain options also exist, programmable in 1dB steps up to 6dB.

The output interface is 2-wire, where each ADC's data is serialized and output over two LVDS pairs. This makes it possible to halve the serial data rate (compared to a 1-wire interface) and restrict it to less than 1Gbps easing receiver design. The ADS6425 also includes the traditional 1-wire interface that can be used at lower sampling frequencies.

An internal phase locked loop (PLL) multiplies the incoming ADC sampling clock to derive the bit clock. The bit clock is used to serialize the 12-bit data from each channel. In addition to the serial data streams, the frame and bit clocks are also transmitted as LVDS outputs. The LVDS output buffers have features such as programmable LVDS currents, current doubling modes, and internal termination options. These can be used to widen eye-openings and improve signal integrity, easing capture by the receiver.

The ADC channel outputs can be transmitted either as MSB or LSB first and 2s complement or straight binary.

The ADS6425 has internal references, but can also support an external reference mode. The device is specified over the industrial temperature range  $(-40^{\circ}C \text{ to } 85^{\circ}C)$ .



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

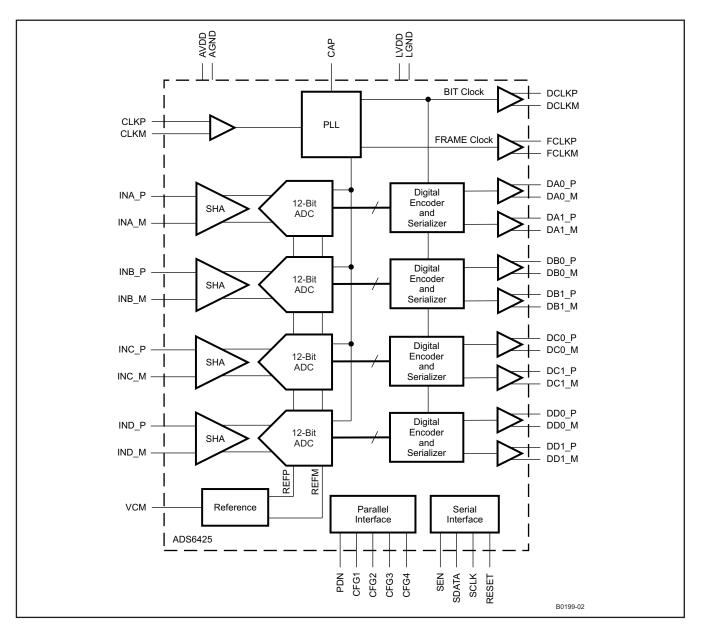


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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.



#### PACKAGE/ORDERING INFORMATION<sup>(1)</sup>

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
ADS6425	QFN-64 <sup>(2)</sup>	RGC	–40°C to 85°C	AZ6425	ADS6425IRGCT	250, Tape/reel
AD30425	QEIN-0417	NGC	-40 0 10 65 0	AZ0420	ADS6425IRGCR	2000, Tape/reel

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

(2) For thermal pad size on the package, see the mechanical drawings at the end of this data sheet.  $\theta_{JA} = 23.17 \text{ °C/W}$  (0 LFM air flow),  $\theta_{JC} = 22.1 \text{ °C/W}$  when used with 2 oz. copper trace and pad soldered directly to a JEDEC standard four layer 3 in. x 3 in. PCB.



## **ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>**

		VALUE	UNIT
AVDD	Supply voltage range	-0.3 to 3.9	V
LVDD	Supply voltage range	-0.3 to 3.9	V
	Voltage between AGND and DGND	-0.3 to 0.3	V
	Voltage between AVDD to LVDD	-0.3 to 3.3	V
	Voltage applied to external pin, VCM	-0.3 to 2.0	V
	Voltage applied to analog input pins	-0.3V to minimum ( 3.6, AVDD + 0.3V)	V
T <sub>A</sub>	Operating free-air temperature range	-40 to 85	°C
TJ	Operating junction temperature range	125	°C
T <sub>stg</sub>	Storage temperature range	-65 to 150	°C
	Lead temperature 1,6 mm (1/16") from the case for 10 seconds	220	°C

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## **RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
SUPPL	IES		-			
AVDD	Analog supply voltage		3.0	3.3	3.6	V
LVDD	LVDS Buffer supply voltage		3.0	3.3	3.6	V
ANALC	OG INPUTS		·			
	Differential input voltage range			2		V <sub>pp</sub>
	Input common-mode voltage			1.5 ±0.1		V
	Voltage applied on VCM in external reference mode				1.55	V
CLOC	( INPUT		L			
	Input clock sample rate		5		125	MSPS
		Sine wave, ac-coupled	0.4	1.5		
		LVPECL, ac-coupled		± 0.8		V
	Input clock amplitude differential (V <sub>CLKP</sub> – V <sub>CLKM</sub> )	LVDS, ac-coupled		± 0.35		V <sub>pp</sub>
		LVCMOS, ac-coupled		3.3		
	Input Clock duty cycle		35%	50%	65%	
DIGITA	L OUTPUTS		·			
0	Maximum external load capacitance from each output pin to	Without internal termination		5		_
C <sub>LOAD</sub>	DGND	With internal termination		10		pF
$R_{LOAD}$	Differential load resistance (external) between the LVDS output	ut pairs		100		Ω
T <sub>A</sub>	Operating free-air temperature		-40		85	°C



## **ELECTRICAL CHARACTERISTICS**

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, sampling rate = 125MSPS, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
RESOLU	TION			12		Bits
ANALOG	INPUT		L			
	Differential input voltage range			2.0		V <sub>pp</sub>
	Differential input capacitance			7		pF
	Analog input bandwidth			500		MHz
	Analog input common mode current (per input pin of each ADC)			155		μA
REFERE	NCE VOLTAGES					
VREFB	Internal reference bottom voltage			1.0		V
VREFT	Internal reference top voltage			2.0		V
VCM	Common mode output voltage			1.5		V
	VCM Output current capability			±4		mA
DC ACCI	URACY					
	No missing codes			Assured		
Eo	Offset error		-15	± 2	+15	mV
	Offset error temperature coefficient					
	Offset error temperature coefficient, channel-channel			0.05		mV/°C
	Internal reference error (VREFT-VREFB)		-15	± 5	15	mV
	Internal reference error temperature coefficient			0.25		mV/°C
E <sub>G</sub>	Gain error <sup>(1)</sup>	Does not include gain error caused due to internal reference error	-1	0.3	+1	% FS
	Gain error temperature coefficient					
	Gain error temperature coefficient, channel-channel			0.005		∆%/°C
DNL	Differential nonlinearity		-0.9	0.5	2.0	LSB
INL	Integral nonlinearity		-2.5	1.0	2.5	LSB
PSRR	DC Power supply rejection ratio			-0.5		mV/V
POWER	SUPPLY					
I <sub>CC</sub>	Total supply current			502		mA
I <sub>AVDD</sub>	Analog supply current			412		mA
I <sub>LVDD</sub>	LVDS supply current			90		mA
	Total power			1.65	1.8	W
	Power down	Input clock running		77	150	mW

(1) This is specified by design and characterization. It is not tested in production.



## **ELECTRICAL CHARACTERISTICS**

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, AVDD = LVDD = 3.3V, sampling rate = 125MSPS, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode (unless otherwise noted).

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
DYNAMIC	C AC CHARACTERISTICS						
		Fin = 10 MHz			70.9		
		Fin = 50 MHz		67.5	70.5		
		Fin = 100 MHz			69.9		
SNR	Signal to noise ratio	Fin = 170 MHz	0 dB Gain		68.5		dBFS
		FIN = 170 MHz	3.5 dB Coarse gain		68.1		
			0 dB Gain		67.4		
		Fin = 230 MHz	3.5 dB Coarse gain		67.1		
		Fin = 10 MHz			70.7		
		Fin = 50 MHz		67	70		
		Fin = 100 MHz			69.7		
SINAD	Signal to noise and distortion ratio		0 dB Gain		66.9		dBFS
		Fin = 170 MHz	3.5 dB Coarse gain		67.4		
			0 dB Gain		66		
		Fin = 230 MHz	3.5 dB Coarse gain		66.5		
	RMS Output noise	Inputs tied to com	mon-mode		0.407		LSB
	Spurious free dynamic range	Fin = 10 MHz			90		-
		Fin = 50 MHz		73	83		
		Fin = 100 MHz			87		
SFDR		Fin = 170 MHz	0 dB Gain		75		dBc
			3.5 dB Coarse gain		79		
			0 dB Gain		74		
		Fin = 230 MHz	3.5 dB Coarse gain		78		
		Fin = 10 MHz			93		
		Fin = 50 MHz		73	91		
		Fin = 100 MHz			90		
HD2	Second harmonic		0 dB Gain		85		dBc
		Fin = 170 MHz	3.5 dB Coarse gain		88		
			0 dB Gain		82		
		Fin = 230 MHz	3.5 dB Coarse gain		85		
		Fin = 10 MHz			90		
		Fin = 50 MHz		73	83		
		Fin = 100 MHz			87		
HD3	Third harmonic		0 dB Gain		75		dBc
		Fin = 170 MHz	3.5 dB Coarse gain		79		
			0 dB Gain		74		
		Fin = 230 MHz	3.5 dB Coarse gain		78		
		Fin = 10 MHz			95	95	
		Fin = 50 MHz			94		dBc
	Worst harmonic (other than HD2, HD3)	Fin = 100 MHz			91		
	(60)	Fin = 170 MHz			88		
		Fin = 230 MHz			86		



## **ELECTRICAL CHARACTERISTICS (continued)**

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, sampling rate = 125MSPS, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		Fin = 10 MHz		88		
		Fin = 50 MHz	70	81		
THD	Total harmonic distortion	Fin = 100 MHz		84		dBc
		Fin = 170 MHz		73		
		Fin = 230 MHz		72		
ENOB	Effective number of bits	Fin = 50 MHz	10.8	11.4		Bits
	Two tops internet detice distortion	F1= 46.09 MHz, F2 = 50.09 MHz	90			
IMD	Two-tone intermodulation distortion	F1= 185.09 MHz, F2 = 190.09 MHz		82		dBFS
	<b>0</b>	Near channel, Frequency of interfering signal = 10 MHz		92		dBFS
	Cross-talk	Far channel, Frequency of interfering signal = 10 MHz		105		uBF5

## **DIGITAL CHARACTERISTICS**

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1 AVDD = LVDD = 3.3V,  $I_0 = 3.5mA$ ,  $R_{LOAD} = 100\Omega^{(1)}$ .

All LVDS specifications are characterized, but not tested at production.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DIGIT	AL INPUTS					
	High-level input voltage		2.4			V
	Low-level input voltage				0.8	V
	High-level input current			10		μA
	Low-level input current			10		μA
	Input capacitance			4		pF
DIGIT	AL OUTPUTS					
	High-level output voltage			1375		mV
	Low-level output voltage			1025		mV
V <sub>OD</sub>	Output differential voltage		250	350	450	mV
V <sub>OS</sub>	Output offset voltage	Common-mode voltage of OUTP and OUTM		1200		mV
	Output capacitance	Output capacitance inside the device, from either output to ground		2		pF

(1) I<sub>O</sub> refers to the LVDS buffer current setting, R<sub>LOAD</sub> is the external differential load resistance between the LVDS output pair



### TIMING SPECIFICATIONS<sup>(1)</sup>

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5 V<sub>PP</sub> clock amplitude, C<sub>L</sub> = 5 pF <sup>(2)</sup>, I<sub>O</sub> = 3.5 mA, R<sub>L</sub> = 100  $\Omega$  <sup>(3)</sup>, no internal termination, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
tj	Aperture jitter	Uncertainty in the sampling instant		250		fs rms
Interfac	ce: 2-wire, DDR bit clock, 12x serializ	zation <sup>(4)</sup>				
t <sub>su</sub>	Data setup time <sup>(5) (6)</sup>	Measured from zero crossing of data transitions to zero crossing of bit clock	0.4	0.6		ns
t <sub>h</sub>	Data hold time <sup>(5) (6)</sup>	Measured from zero crossing of bit clock to zero crossing of data transitions	0.5	0.7		ns
t <sub>su</sub>	Frame setup time	Measured from zero-cross of frame clock rising edge to zero-cross of bit clock rising edge	0.4	0.6		ns
t <sub>h</sub>	Frame hold time	Measured from zero-cross of bit clock falling edge to zero-cross of frame clock falling edge	0.5	0.7		ns
t <sub>pd_clk</sub>	Clock propagation delay <sup>(4)</sup>	Input clock rising edge cross-over to frame clock rising edge cross-over	3.6	4.4	5.2	ns
	Bit clock cycle-cycle jitter (6)			350		ps pp
	Frame clock cycle-cycle jitter (6)			75		ps pp
Below	specifications apply for 5 MSPS ≤ Fs	s ≤125 MSPS and all interface options.				
t <sub>A</sub>	Aperture delay	Delay from rising edge of input clock to the actual sampling instant	1	2	3	ns
	Aperture delay variation, channel-channel	Within the same device	-250		250	ps
	ADC Latency (7)	Time for a sample to propagate to the ADC output Figure 1		12		Clock cycles
		Time to valid data after coming out of global power down			100	μs
	Wake up time	Time to valid data after input clock is re-started			100	μs
		Time to valid data after coming out of channel standby			200	clock cycles
t <sub>RISE</sub>	Data rise time	Data rise time measured from -100 mV to +100 mV	50	100	200	ps
t <sub>FALL</sub>	Data fall time	Data fall time measured from +100 mV to -100 mV	50	100	200	ps
t <sub>RISE</sub>	Bit clock and frame clock rise time	Rise time measured from -100mV to +100mV	50	100	200	ps
t <sub>FALL</sub>	Bit clock and frame clock fall time	Fall time measured from +100mV to -100mV	50	100	200	ps
	LVDS Bit clock duty cycle		45%	50%	55%	
	LVDS Frame clock duty cycle		47%	50%	53%	

Timing parameters are ensured by design and characterization and not tested in production. (1)

(2)

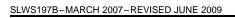
 $C_L$  is the external single-ended load capacitance between each output pin and ground.  $I_0$  refers to the LVDS buffer current setting;  $R_L$  is the external differential load resistance between the LVDS output pair. (3)

(4) Refer to Output Timings in application section for timings at lower sampling frequencies and other interface options.

Timing parameters are measured at the end of a 2 inch pcb trace (100-Ω characteristic impedance) terminated by RLand CL. (5)

(6) Setup and hold time specifications take into account the effect of jitter on the output data and clock.

Note that the total latency = ADC latency + internal serializer latency. The serializer latency depends on the interface option selected as (7) shown in Table 25



TEXAS INSTRUMENTS

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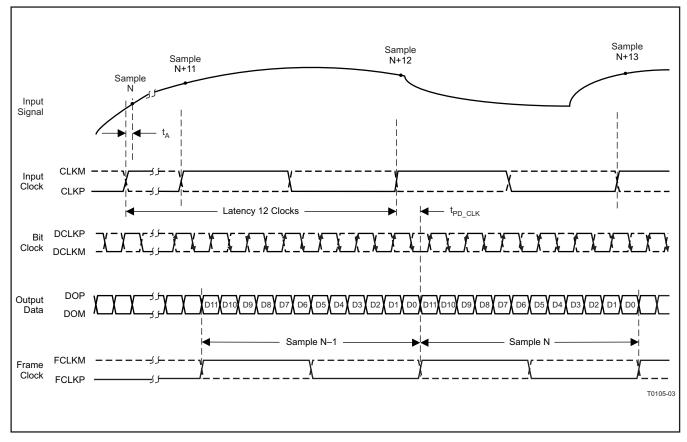


Figure 1. Latency

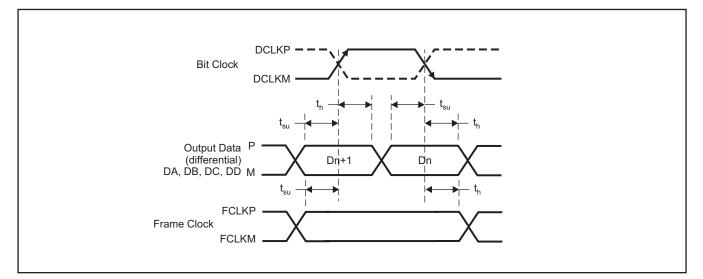


Figure 2. LVDS Timings



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#### **DEVICE PROGRAMMING MODES**

The ADS6425 offers flexibility with several programmable features that are easily configured.

The device can be configured independently using either parallel interface control or serial interface programming.

In addition, the device supports a third configuration mode, where both the parallel interface and the serial control registers are used. In this mode, the priority between the parallel and serial interfaces is determined by a priority table (Table 2). If this additional level of flexibility is not required, the user can select either the serial interface programming or the parallel interface control.

## USING PARALLEL INTERFACE CONTROL ONLY

To control the device using parallel interface, keep RESET tied to *high* (LVDD). Pins CFG1, CFG2, CFG3, CFG4, PDN, SEN, SCLK, and SDATA are used to directly control certain functions of the ADC. After power-up, the device will automatically get configured as per the parallel pin voltage settings (Table 3 to Table 6) and no reset is required. In this mode, SEN, SCLK, and SDATA function as parallel interface control pins.

Frequently used functions are controlled in this mode—output data interface and format, power down modes, coarse gain and internal/external reference. The parallel pins can be configured using a simple resistor string (with 10% tolerance resistors) as illustrated in Figure 3.

Table 1 briefly describes the modes controlled by the parallel pins.

PIN	CONTROL FUNCTIONS	
SEN	Coarse gain and internal/external reference.	
SCLK, SDATA	Sync, deskew patterns and global power down.	
PDN	Dedicated pin for global power down	
CFG1	1-Wire/2-wire and DDR/SDR bit clock	
CFG2	12x/14x Serialization and SDR bit clock capture edge	
CFG3	Reserved function. Tie CFG3 to Ground.	
CFG4	MSB/LSB First and data format.	

#### Table 1. Parallel Pin Definition

#### USING SERIAL INTERFACE PROGRAMMING ONLY

In this mode, SEN, SDATA, and SCLK function as serial interface pins and are used to access the internal registers of ADC. The registers must first be reset to their default values either by applying a pulse on RESET pin or by a *high* setting on the <RST> bit (in register ). After reset, the RESET pin must be kept **low**.

The Serial Interface section describes the register programming and register reset in more detail.

Since the parallel pins (CFG1-4 and PDN) are not used in this mode, they must be tied to ground. The register override bit <OVRD> - D10 in register 0x0D has to be set *high* to disable the control of parallel interface pins in this serial interface control ONLY mode.

#### USING BOTH THE SERIAL INTERFACE AND PARALLEL CONTROLS

For increased flexibility, a combination of serial interface registers and parallel pin controls (CFG1-4 and PDN) can also be used to configure the device.

The parallel interface control pins CFG1 to CFG4 and PDN are available. After power-up, the device will automatically get configured as per the parallel pin voltage settings (Table 3 to Table 9) and no reset is required. A simple resistor string can be used as illustrated in Figure 3.

SEN, SDATA, and SCLK function as serial interface pins and are used to access the internal registers of ADC. The registers must first be reset to their default values either by applying a pulse on RESET pin or by a *high* setting on the <RST> bit (in register ). After reset, the RESET pin must be kept **low**.

The Serial Interface section describes the register programming and register reset in more detail.

Since some functions are controlled using both the parallel pins and serial registers, the priority between the two is determined by a priority table (Table 2).

	Table 2. Priority Between Parallel Pins and Serial Registers				
PIN	FUNCTIONS SUPPORTED	PRIORITY			
CFG1 to CFG4	As described in Table 6 to Table 9	Register bits can control the modes ONLY if the <b><ovrd></ovrd></b> bit is <i>high</i> . If the <b><ovrd></ovrd></b> bit is LOW, then the control voltage on these parallel pins determines the function as per Tables			
PDN	Global Power Down	D0 bit in register 0x00 controls global power down ONLY if PDN pin is LOW. If PDN is <i>high</i> , device is in global power down mode.			
SEN	Serial Interface Enable	3.5 dB coarse gain setting is controlled by bit D5 in register 0x0D ONLY if the <ovrd> bit is <i>high</i>. Else, it is in default setting of 0 dB coarse gain.</ovrd>			
		Internal/External reference setting is determined by bit D5 in register 0x00.			
SCLK,	Serial Interface Clock and	Bits D5-D7 in register 0x0A control the SYNC and DESKEW output patterns.			
SDATA	Serial Interface Data	Power down is determined by bit D0 in 0x00 register.			

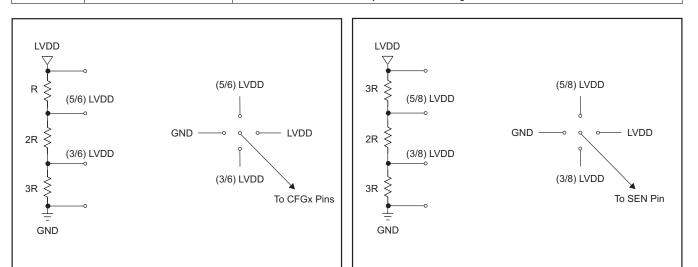


Figure 3. Simple Scheme to Configure Parallel Pins



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#### **DESCRIPTION OF PARALLEL PINS**

SCLK	SDATA	DESCRIPTION
LOW	LOW	NORMAL conversion.
LOW	HIGH	SYNC - ADC outputs sync pattern on all channels. This pattern can be used by the receiver to align the deserialized data to the frame boundary. See Capture Test Patterns for details.
HIGH	LOW	POWER DOWN –Global power down, all channels of the ADC are powered down, including internal references, PLL and output buffers.
HIGH	HIGH	DESKEW - ADC outputs deskew pattern on all channels. This pattern can be used by the receiver to ensure deserializer uses the right clock edge. See Capture Test Patterns for details.

#### Table 3. SCLK, SDATA Control Pins

#### Table 4. SEN Control Pin

SEN	DESCRIPTION	
0	External reference and 0 dB coarse gain (full-scale = 2V pp)	
(3/8)LVDD	External reference and 3.5 dB coarse gain (full-scale = 1.34V pp)	
(5/8)LVDD	Internal reference and 3.5 dB coarse gain (full-scale = 1.34V pp)	
LVDD	Internal reference and 0 dB coarse gain (full-scale = 2V pp)	

Independent of the programming mode used, after power-up the parallel pins PDN, CFG1 to CFG4 will automatically configure the device as per the voltage applied (Table 5 to Table 9).

#### Table 5. PDN Control Pin

PDN	DESCRIPTION
0	Normal operation
AVDD	Power down global

#### Table 6. CFG1 Control Pin

CFG1	DESCRIPTION
0 (default) +200mV	DDR Bit clock and 1-wire interface
(3/6)LVDD ±200mV	Not used
(5/6)LVDD ±200mV	SDR Bit clock and 2-wire interface
LVDD - 200mV	DDR Bit clock and 2-wire interface

#### Table 7. CFG2 Control Pin

CFG2	DESCRIPTION
0 (default) +200mV	12x Serialization and capture at falling edge of bit clock (only with SDR bit clock)
(3/6)LVDD ±200mV	14x Serialization and capture at falling edge of bit clock (only with SDR bit clock)
(5/6)LVDD ±200mV	14x Serialization and capture at rising edge of bit clock (only with SDR bit clock)
LVDD - 200mV	12x Serialization and capture at rising edge of bit clock (only with SDR bit clock)

## Table 8. CFG3 Control Pin

CFG3	RESERVED - TIE TO GROUND



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CFG4	DESCRIPTION
0 (default) +200mV	MSB First and 2s complement
(3/6)LVDD ±200mV	MSB First and Offset binary
(5/6)LVDD ±200mV	LSB First and Offset binary
LVDD - 200mV	LSB First and 2s complement

## SERIAL INTERFACE

The ADC has a serial interface formed by pins SEN (serial interface enable), SCLK (serial interface clock), SDATA (serial interface data) and RESET. Serial shift of bits into the device is enabled when SEN is low. Serial data SDATA is latched at every falling edge of SCLK when SEN is active (low). The serial data is loaded into the register at every 16th SCLK falling edge when SEN is low. In case the word length exceeds a multiple of 16 bits, the excess bits are ignored. Data can be loaded in multiple of 16-bit words within a single active SEN pulse. The interface can work with SCLK frequency from 20 MHz down to very low speeds (few hertz) and even with non-50% duty cycle SCLK.

The first 5-bits of the 16-bit word are the address of the register while the next 11 bits are the register data.

#### **Register Reset**

After power-up, the internal registers *must* be reset to their default values. This can be done in one of two ways:

- 1. Either by applying a high-going pulse on RESET (of width greater than 10ns) **OR**
- 2. By applying software reset. Using the serial interface, set the **<RST>** bit in register 0x00 to *high* this resets the registers to their default values and then self-resets the **<RST>** bit to LOW.

When RESET pin is not used, it must be tied to LOW.



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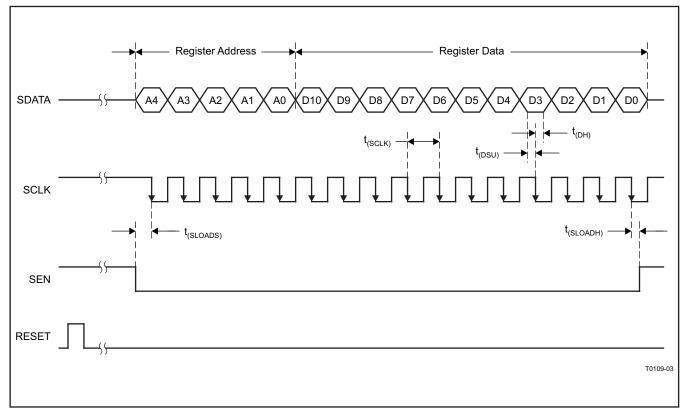


Figure 4. Serial Interface Timing



## SERIAL INTERFACE TIMING CHARACTERISTICS

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, unless otherwise noted.

	PARAMETER	MIN	TYP	MAX	UNIT
f <sub>SCLK</sub>	SCLK Frequency, f <sub>SCLK</sub> = 1/t <sub>SCLK</sub>	> dc		20	MHz
t <sub>SLOADS</sub>	SEN to SCLK Setup time		25		ns
t <sub>SLOADH</sub>	SCLK to SEN Hold time		25		ns
t <sub>DSU</sub>	SDATA Setup time		25		ns
t <sub>DH</sub>	SDATA Hold time		25		ns
	Time taken for register write to take effect after 16th SCLK falling edge		100		ns

## **RESET TIMING**

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, unless otherwise noted.

	PARMATER	CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>1</sub>	Power-on delay time	Delay from power-up of AVDD and LVDD to RESET pulse active	5			ms
t <sub>2</sub>	Reset pulse width	Pulse width of active RESET signal	10			ns
t <sub>3</sub>	Register write delay time	Delay from RESET disable to SEN active	25			ns
t <sub>PO</sub>	Power-up delay time	Delay from power-up of AVDD and LVDD to output stable		6.5		ms

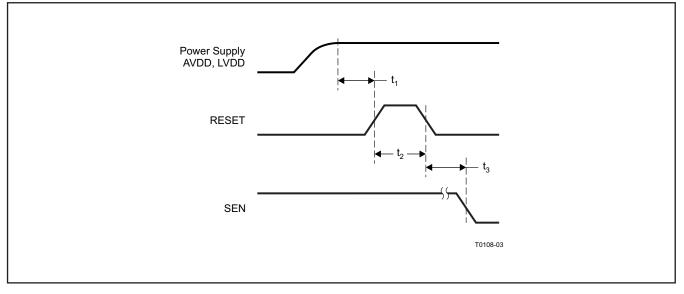


Figure 5. Reset Timing



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#### SERIAL REGISTER MAP

REGISTER ADDRESS					REGIST	TER FUNCTION	IS <sup>(1)(2)(3)</sup>				
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
00	< <b>RST&gt;</b> S/W RESET	0	0	0	0	< <b>REF&gt;</b> INTERNAL OR EXTERNAL	<pdn chd=""> POWER DOWN CH D</pdn>	<pdn chc=""> POWER DOWN CHC</pdn>	<pdn chb=""> POWER DOWN CH B</pdn>	<pdn cha=""> POWER DOWN CH A</pdn>	<pdn GLOBAL&gt; GLOBAL POWER DOWN</pdn 
04	0	0	0	0	0 CLKIN GAIN> INPUT CLOCK BUFFER GAIN CONTROL						0
0A	0	<pre><df> DATA FORMAT 2S COMP OR STRAIGHT BINARY</df></pre>	0		<patterns> EST PATTERN</patterns>	S	0	0	0	0	0
0B					CUSTOM P	<custom a=""> ATTERN (LOW</custom>					
0C	FINE GAIN	<fine gain=""> N CONTROL (10</fine>	dB to 6 dB)	0	0	0	0	0	0	0	<custom B&gt; CUSTOM PATTERN (MSB BIT)</custom 
0D	<ovrd> OVERRIDE BIT</ovrd>	0	0	BYTE-WISE OR BIT-WISE	MSB OR LSB FIRST	<coarse GAIN&gt; COURSE GAIN ENABLE</coarse 	FALLING OR RISING BIT CLOCK CAPTURE EDGE	0	12-BIT OR 14-BIT SERIALIZE	DDR OR SDR BIT CLOCK	1-WIRE OR 2-WIRE INTERFACE
10	LVDS	INTERNAL TER	<term clk=""> MINATION BIT</term>	AND WORD CI	LOCKS		<lvds LVDS CURRE</lvds 		·	<curr d<="" td=""><td></td></curr>	
11	WORD-WIS	E CONTROL	0	0	0	0	LV		<term data=""></term>	- DATA OUTPU	TS

#### Table 10. Summary of Functions Supported By Serial Interface

The unused bits in each register (shown by blank cells in above table) must be programmed as 0. Multiple functions in a register can be programmed in a single write operation. After a hardware or software reset, all register bits are cleared to 0. (1)

(2) (3)

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### **DESCRIPTION OF SERIAL REGISTERS**

## Table 11. Serial Register A<sup>(1)</sup>

REGISTER ADDRESS		BITS												
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0			
00	< <b>RST&gt;</b> S/W RESET	0	0	0	0	< <b>REF&gt;</b> INTERNAL OR EXTERNAL	<pdn chd=""> POWER DOWN CH D</pdn>	<pdn chc=""> POWER DOWN CHC</pdn>	<pdn chb=""> POWER DOWN CH B</pdn>	<pdn cha=""> POWER DOWN CH A</pdn>	< <b>PDN&gt;</b> GLOBAL POWER DOWN			

D0 - D4	Power down modes
D0	<pdn global=""></pdn>
0	Normal operation
1	Global power down, including all channels ADCs, internal references, internal PLL and output buffers
D1	<pdn cha=""></pdn>
0	CH A Powered up
1	CH A ADC Powered down
D2	<pdn chb=""></pdn>
0	CH B Powered up
1	CH B ADC Powered down
D3	<pdn chc=""></pdn>
0	CH C Powered up
1	CH C ADC Powered down
D4	<pdn chd=""></pdn>
0	CH D Powered up
1	CH D ADC Powered down
D5	<ref> Reference</ref>
0	Internal reference enabled
1	External reference enabled
D10	<rst></rst>
1	Software reset applied – resets all internal registers and self-clears to 0

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## Table 12. Serial Register B<sup>(1)</sup>

REGISTER ADDRESS		BITS										
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
04	0	0	0	0		CLKIN GAIN> INPUT CLOCK BUFFER GAIN CONTROL				0	0	

(1) After a hardware or software reset, all register bits are cleared to 0.

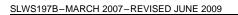
## D6 - D2 <CLKIN GAIN> Input clock buffer gain control

11000	Gain 0, minimum gain
00000	Gain 1, default gain after reset
01100	Gain 2
01010	Gain 3
01001	Gain 4
01000	Gain 5, maximum gain

# Table 13. Serial Register C<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
00	0	<b><df></df></b> DATA DORMAT 2S COMP OR STRAIGHT BINARY	0	-	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>		0	0	0	0	0

D7 - D5	<patterns> Capture test patterns</patterns>
000	Normal ADC operation
001	Output all zeros
010	Output all ones
011	Output toggle pattern
100	Unused
101	Output custom pattern (contents of CUSTOM pattern registers 0x0B and 0x0C)
110	Output DESKEW pattern (serial stream of 1010)
111	Output SYNC pattern
D9	<b>&gt;Data format selection</b>
0	2s Complement format
1	Straight binary format



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## Table 14. Serial Register D<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0B					CUSTOM P	<custom a=""> ATTERN (LOWE</custom>					

(1) After a hardware or software reset, all register bits are cleared to 0.

### D10 - D0 <CUSTOM A> Lower 11 bits of custom pattern <D10>...<D0>

#### Table 15. Serial Register E<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0C	FINE GAIN	<fine gain=""> I CONTROL (1 (</fine>		0	0	0	0	0	0	0	<custom B&gt; CUSTOM PATTERN (MSB BIT)</custom 

(1) After a hardware or software reset, all register bits are cleared to 0.

#### D4 - D0 <CUSTOM B> MSB bit of custom pattern <D11>

D10-D8	<fine gain=""> Fine gain control</fine>
000	0 dB Gain (full-scale range = $2.00 V_{PP}$ )
001	1 dB Gain (full-scale range = 1.78 V <sub>PP</sub> )
010	2 dB Gain (full-scale range = $1.59 V_{PP}$ )
011	3 dB Gain (full-scale range = $1.42 V_{PP}$ )
100	4 dB Gain (full-scale range = $1.26 V_{PP}$ )
101	5 dB Gain (full-scale range = $1.12 V_{PP}$ )
110	6 dB Gain (full-scale range = $1.00 V_{PP}$ )

## Table 16. Serial Register F<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0D	<ovrd> OVER-RIDE BITE</ovrd>	0	0	BYTE-WISE OR BIT-WISE	MSB OR LSB FIRST	<coarse GAIN&gt; COARSE GAIN ENABLE</coarse 	FALLING OR RISING BIT CLOCK CAPTURE EDGE	0	14-BIT OR 16-BIT SERIALIZE	DDR OR SDR BIT CLOCK	1-WIRE OR 2-WIRE INTERFACE

D0	Interface selection
0	1 Wire interface
1	2 Wire interface
D1	Bit clock selection (only in 2-wire interface)
0	DDR Bit clock
1	SDR Bit clock
D2	Serialization selection
0	12x Serialization
1	14x Serialization

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D4	Bit clock capture edge (only when SDR bit clock is selected, D1 = 1)
0	Capture data with falling edge of bit clock
1	Capture data with rising edge of bit clock
D5	<coarse gain=""> Coarse gain control</coarse>
0	0 dB coarse gain
1	3.5dB coarse gain (full-scale range = 1.34 $V_{PP}$ )
D6	MSB or LSB first selection
0	MSB First
1	LSB First
D7	Byte/bit wise outputs (only when 2-wire is selected)
0	Byte wise
1	Bit wise
D10	<b><ovrd></ovrd></b> Over-ride bit. All the functions in register 0x0D can also be controlled using the parallel control pins. By setting bit <ovrd> = 1, the contents of register 0x0D will over-ride the settings of the parallel pins.</ovrd>
0	Disable over-ride
1	Enable over-ride

# Table 17. Serial Register G<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
10	LVDS	INTERNAL TER	<term clk=""></term>		LOCKS			CURR> NT SETTINGS			OUBLE> ENT DOUBLE

D0	<curr double=""> LVDS current double for data outputs</curr>
0	Nominal LVDS current, as set by <d5d2></d5d2>
1	Double the nominal value
D1	<curr double=""> LVDS current double for bit and word clock outputs</curr>
0	Nominal LVDS current, as set by <d5d2></d5d2>
1	Double the nominal value
D3-D2	<lvds curr=""> LVDS current setting for data outputs</lvds>
00	3.5 mA
01	4 mA
10	2.5 mA
11	3 mA
D5-D4	<lvds curr=""> LVDS current setting for bit and word clock outputs</lvds>
00	3.5 mA
01	4 mA

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10	2.5 mA
11	3 mA
D10-D6	<term clk=""> LVDS internal termination for bit and word clock outputs</term>
00000	No internal termination
00001	166 Ω
00010	200 Ω
00100	250 Ω
01000	333 Ω
10000	500 Ω
	Any combination of above bits can also be programmed, resulting in a parallel combination of the selected values. For example, 00101 is the parallel combination of $166  250 = 100 \Omega$
00101	100 Ω

## Table 18. Serial Register H<sup>(1)</sup>

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
11	WORD-WIS	E CONTROL	0	0	0	0	LV		<term data=""></term>		ITS

D4-D0	<term data=""> LVDS internal termination for data outputs</term>
00000	No internal termination
00001	166 Ω
00010	200 Ω
00100	250 Ω
01000	333 Ω
10000	500 Ω
	Any combination of above bits can also be programmed, resulting in a parallel combination of the selected values. For example, 00101 is the parallel combination of 166  250 = 100 $\Omega$
00101	100 Ω
D10-D9	Only when 2-wire interface is selected
00	Byte-wise or bit-wise output, 1x frame clock
11	Word-wise output enabled, 0.5x frame clock
01,10	Do not use



## **PIN CONFIGURATION (2-WIRE INTERFACE)**

Image: constraint of the second state of the second sta
DA1_P       DA1_A       DA1_A       DD0_M         DA1_M       2       47       DD0_P         DA0_P       3       46       DD1_M         DA0_M       2       47       DD0_P         DA0_P       3       46       DD1_M         DA0_P       3       46       DD1_M         DA0_M       2       47       DD0_P         DA0_M       2       46       DD1_M         DA0_M       24       45       DD1_P         CAP       5       44       SCLK         RESET       6       43       SDATA         LVDD       7       42       SEN         AGND       28       ADS6425       40       AVDD         AVDD       9       40       39       AGND         INA_M       11       38       IND_M       38       IND_M         INA_P       112       37       36       AGND       AGND         AGND       13       36       AGND       35       INC_M         INB_M       14       35       34       INC_P
DA1_P       164       63       62       61       60       59       58       57       56       53       52       51       50       48<       DD0_P         DA1_M       22       47C       DD0_P       DD0_P       DD1_M       46C       DD1_M         DA0_P       3       46C       DD1_P       45C       DD1_P         DA0_M       4       55       44       5C       DD1_P         CAP       55       44       5C       DD1_P         CAP       55       44C       SCLK       SEN         RESET       6       43C       SDATA       42C       SEN         AGND       7       42C       SEN       41C       PDN         AGND       38       ADS6425       40C       AVDD         AGND       10       39C       AGND       39C       AGND         INA_M       11       38C       IND_M       39C       AGND         INA_P       112       37C       37C       IND_P       36C       AGND         INB_M       14       35C       INC_M       34C       INC_P
DA1_M       2       47C       DD0_P         DA0_P       3       46C       DD1_M         DA0_M       24       45C       DD1_P         CAP       25       44C       SCLK         RESET       26       43C       SDATA         LVDD       27       42C       SEN         AGND       29       4DS6425       41C       PDN         AVDD       29       40C       AVDD       AVDD         AGND       210       39C       AGND       MD_M         INA_M       211       38C       IND_M         INA_M       211       36C       AGND         INA_M       213       36C       AGND         INB_M       214       35C       INC_M         INB_P       215       34C       INC_P
DA0_M       2.4       45       DD1_P         CAP       2.5       44       SCLK         RESET       2.6       43       SDATA         LVDD       2.7       42       SEN         AGND       2.8       ADS6425       41       PDN         AVDD       2.9       40       AVDD       AGND         AGND       2.10       39       AGND       AGND         INA_M       2.11       38       IND_M         INA_P       2.12       37       IND_P         AGND       2.13       36       AGND         INB_M       2.14       35       INC_M         INB_P       2.15       34       INC_P
CAP       35       44 C       SCLK         RESET       36       43 C       SDATA         LVDD       7       42 C       SEN         AGND       38       ADS6425       41 C       PDN         AVDD       9       40 C       AVDD         AGND       10       39 C       AGND         INA_M       11       38 C       IND_M         INA_P       12       37 C       IND_P         AGND       13       36 C       AGND         INB_M       14       35 C       INC_M         INB_P       15       34 C       INC_P
RESET       0       43 (0)       SDATA         LVDD       0       7       42 (0)       SEN         AGND       0       8       ADS6425       41 (0)       PDN         AVDD       0       9       ADS6425       40 (0)       AVDD         AGND       0       10       39 (0)       AGND       39 (0)       AGND         INA_M       0       11       38 (0)       10       38 (0)       10       38 (0)       10         INA_M       0       12       37 (0)       10       36 (0)       10       10       40 (0)<
LVDD       D       7       42C       SEN         AGND       D       8       ADS6425       41C       PDN         AVDD       D       9       ADS6425       40C       AVDD         AGND       D       10       39C       AGND       IND_M         INA_M       D       11       38C       IND_M         INA_P       D       37C       IND_P         AGND       313       36C       AGND         INB_M       14       35C       INC_M         INB_P       15       34C       INC_P
AGND $\bigcirc 8$ ADS6425       41 <
AVDD       D9       ADS6425       40 C = AVDD         AGND       D10       39 C = AGND       39 C = AGND         INA_M       D11       38 C = IND_M       IND_P         INA_P       D12       37 C = IND_P       AGND         AGND       D13       36 C = AGND       IND_P         INB_M       D14       35 C = INC_M       INC_P         INB_P       D15       34 C = INC_P       INC_P
AVDD       D       40 < AVDD
INA_M       D 11       38 C       IND_M         INA_P       D 12       37 C       IND_P         AGND       D 13       36 C       AGND         INB_M       D 14       35 C       INC_M         INB_P       D 15       34 C       INC_P
INA_P       12       37 C       IND_P         AGND       13       36 C       AGND         INB_M       14       35 C       INC_M         INB_P       15       34 C       INC_P
AGND       C 13       36 C AGND         INB_M       C 14       35 C INC_M         INB_P       C 15       34 C INC_P
INB_M     INC_M       INB_P     15
INB_P _ 0 15 34 C _ INC_P
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
AVDD AVDD AVDD AVDD NC CFG4 AGND AGND AGND AVDD CFG3 CFG3 CFG3 CFG3 AGND AVDD AVDD
$\begin{array}{cccccccccccccccccccccccccccccccccccc$

## PIN ASSIGNMENTS (2-WIRE INTERFACE)

PINS		1/0	NO. OF	DECODIDITION			
NAME	AME NO.		PINS	DESCRIPTION			
SUPPLY AND GR	OUND PINS						
AVDD	9,17,19,27,32,40,		6	Analog power supply			
AGND	8,10,13,16,18,23,26, 31,33 36,39,		11	Analog ground			
LVDD	7,49,64		3	Digital power supply			
LGND	54,59		2	Digital ground			
INPUT PINS							
CLKP, CLKM	24,25	Ι	2	Differential input clock pair			
INA_P, INA_M	12,11	Ι	2	Differential input signal pair, channel A. If unused, the pins should be tied to VCM and not floated.			

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## PIN ASSIGNMENTS (2-WIRE INTERFACE) (continued)

PINS			NO. OF	DESODIDION					
NAME	NO.	- I/O	PINS	DESCRIPTION					
INB_P, INB_M	15,14	Ι	2	Differential input signal pair, channel B. If unused, the pins should be tied to VCM and not floated.					
INC_P, INC_M	34,35	I	2	Differential input signal pair, channel C. If unused, the pins should be tied to VCM and not floated.					
IND_P, IND_M	37,38	I	2	Differential input signal pair, channel D. If unused, the pins should be tied to VCM and not floated.					
CAP	5		1	Connect 2nF capacitor from pin to ground					
SCLK	44	I	1	This pin functions as serial interface clock input when RESET is low. When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SDATA). See Table 3 for description. This pin has an internal pull-down resistor.					
SDATA	43	I	1	This pin functions as serial interface data input when RESET is low. When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SCLK). See Table 3 for description. This pin has an internal pull-down resistor.					
SEN	42	I	1	This pin functions as serial interface enable input when RESET is low. When RESET is <i>high</i> , it controls coarse gain and internal/external reference modes. See Table 4 for description. This pin has an internal pull-up resistor.					
				Serial interface reset input.					
RESET	6	I	1	When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to the Serial Interface section. In parallel interface mode, tie RESET permanently <i>high</i> . (SCLK, SDATA and SEN function as parallel control pins in this mode).					
				The pin has an internal pull-down resistor to ground.					
PDN	41	Ι	1	Global power down control pin.					
CFG1	30	I	1	Parallel input pin. It controls 1-wire or 2-wire interface and DDR or SDR bit clock selection. See Table 6 for description. Tie to AVDD for 2-wire interface with DDR bit clock.					
CFG2	29	I	1	Parallel input pin. It controls 12x or 14x serialization and SDR bit clock capture edge. See Table 7 for description. For 12x serialization with DDR bit clock, tie to ground or AVDD.					
CFG3	28	1	1	RESERVED pin - Tie to ground.					
CFG4	21	I	1	Parallel input pin. It controls data format and MSB or LSB first modes. See Table 9 for description.					
VCM	22	I/O	1	Internal reference mode – common-mode voltage output External reference mode – reference input. The voltage forced on this pin sets the internal reference.					
OUTPUT PINS									
DA0_P,DA0_M	3,4	0	2	Channel A differential LVDS data output pair, wire 0					
DA1_P,DA1_M	1,2	0	2	Channel A differential LVDS data output pair, wire 1					
DB0_P,DB0_M	62,63	0	2	Channel B differential LVDS data output pair, wire 0					
DB1_P,DB1_M	60,61	0	2	Channel B differential LVDS data output pair, wire 1					
DC0_P,DC0_M	52,53	0	2	Channel C differential LVDS data output pair, wire 0					
DC1_P,DC1_M	50,51	0	2	Channel C differential LVDS data output pair, wire 1					
DD0_P,DD0_M	47,48	0	2	Channel D differential LVDS data output pair, wire 0					
DD1_P,DD1_M	45,46	0	2	Channel D differential LVDS data output pair, wire 1					
DCLKP,DCLKM	57,58	0	2	Differential bit clock output pair					
FCLKP,FCLKM	55,56	0	2	Differential frame clock output pair					
NC	20		1	Do Not Connect					



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## **PIN CONFIGURATION (1-WIRE INTERFACE)**

								C PA									
	LVDD	DA_M	DA_P	DB_M	DB_P	LGND	DCLKM	DCLKP	FCLKM	FCLKP	LGND	DC_M	DC_P	M_DD_M	DD_P	LVDD	
UNUSED	_⊃1 <sup>64</sup>	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49 48C	UNUSED
UNUSED	_⊃2															47	UNUSED
UNUSED	=⊃ 3															46〔]	UNUSED
UNUSED	□⊃4															45(]	UNUSED
CAP	[]5															44(]	SCLK
RESET	<u> </u>															43(]	SDATA
LVDD	207															42〔]	SEN
AGND	208							ADS	612	5						41	PDN
AVDD	E⊃9						,	403	042.	J						40〔]	AVDD
AGND	_⊃10															39(]	AGND
INA_M	_⊃ 11															38(]	IND_M
INA_P	<u>)</u> 12															37 🤇 🗌	IND_P
AGND	_ ⊃ 13															36 🤇 🗌	AGND
INB_M	_⊃14															35 🤇 🗌	INC_M
INB_P	<u>)</u> 15															34 🤇 🗌	INC_P
AGND	こつ 16 <sub>7</sub>		19	20	21		23	24	25 ( )	26	27	28	29	30	31	32 <sup>33</sup> ⊂−	AGND
	AVDD	AGND	AVDD	NC	CFG4	VCM	AGND	CLKP	CLKM	AGND	AVDD	CFG3	CFG2	CFG1	AGND	AVDD	I
																	P0056-03

## **PIN ASSIGNMENTS (1-WIRE INTERFACE)**

PINS			NO. OF	DECODIDATION			
NAME	NO.	I/O	PINS	DESCRIPTION			
SUPPLY AND GR	OUND PINS						
AVDD	9,17,19,27,32,40,		6	Analog power supply			
AGND	8,10,13,16,18,23,26, 31,33 36,39,		11	Analog ground			
LVDD	7,49,64		3	Digital power supply			
LGND	54,59		2	Digital ground			
INPUT PINS							
CLKP, CLKM	24,25	Ι	2	Differential input clock pair			
INA_P, INA_M	12,11	Ι	2	Differential input signal pair, channel A. If unused, the pins should be tied to VCM and not floated.			

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## PIN ASSIGNMENTS (1-WIRE INTERFACE) (continued)

P	INS								
NAME	NO.	I/O	NO. OF PINS	DESCRIPTION					
INB_P, INB_M	15,14	I	2	Differential input signal pair, channel B. If unused, the pins should be tied to VCM and not floated.					
INC_P, INC_M	34,35	I	2	Differential input signal pair, channel C. If unused, the pins should be tied to VCM and not floated.					
IND_P, IND_M	37,38	I	2	Differential input signal pair, channel D. If unused, the pins should be tied to VCM and not floated.					
CAP	5		1	Connect 2nF capacitance from pin to ground					
SCLK	44	I	1	This pin functions as serial interface clock input when RESET is <i>low.</i> When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SDATA). See <u>Table 3</u> for description. This pin has an internal pull-down resistor.					
SDATA	43	I	1	This pin functions as serial interface data input when RESET is <i>low</i> . When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SCLK). See Table 3 for description. This pin has an internal pull-down resistor.					
SEN	42	I	1	This pin functions as serial interface enable input when RESET is <i>low</i> . When RESET is <i>high</i> , it controls coarse gain and internal/external reference modes. See Table 4 for description. This pin has an internal pull-up resistor.					
				Serial interface reset input.					
RESET	6	I	1	When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to the Serial Interface section. In parallel interface mode, tie RESET permanently <i>high</i> . (SCLK, SDATA and SEN function as parallel control pins in this mode).					
				The pin has an internal pull-down resistor to ground.					
PDN	41	I	1	Global power down control pin.					
CFG1	30	I	1	Parallel input pin. It controls 1-wire or 2-wire interface and DDR or SDR bit clock selection. See Table 6 for description. Tie to ground for 1-wire interface with DDR bit clock.					
CFG2	29	I	1	Parallel input pin. It controls 12x or 14x serialization and SDR bit clock capture edge. See Table 7 for description. For 12x serialization with DDR bit clock, tie to ground or AVDD.					
CFG3	28	I	1	RESERVED pin - Tie to ground.					
CFG4	21	I	1	Parallel input pin. It controls data format and MSB or LSB first modes. See Table 9 for description.					
VCM	22	I/O	1	Internal reference mode – common-mode voltage output External reference mode – reference input. The voltage forced on this pin sets the internal reference.					
OUTPUT PINS									
DA_P,DA_M	62,63	0	2	Channel A differential LVDS data output pair					
DB_P,DB_M	60,61	0	2	Channel B differential LVDS data output pair					
DC_P,DC_M	52,53	0	2	Channel C differential LVDS data output pair					
DD_P,DD_M	50,51	0	2	Channel D differential LVDS data output pair					
DCLKP,DCLKM	57,58	0	2	Differential bit clock output pair					
FCLKP,FCLKM	55,56	0	2	Differential frame clock output pair					
UNUSED	1-4,45-48		8	These pins are unused in the 1-wire interface. Do not connect					
NC	20		1	Do not connect					



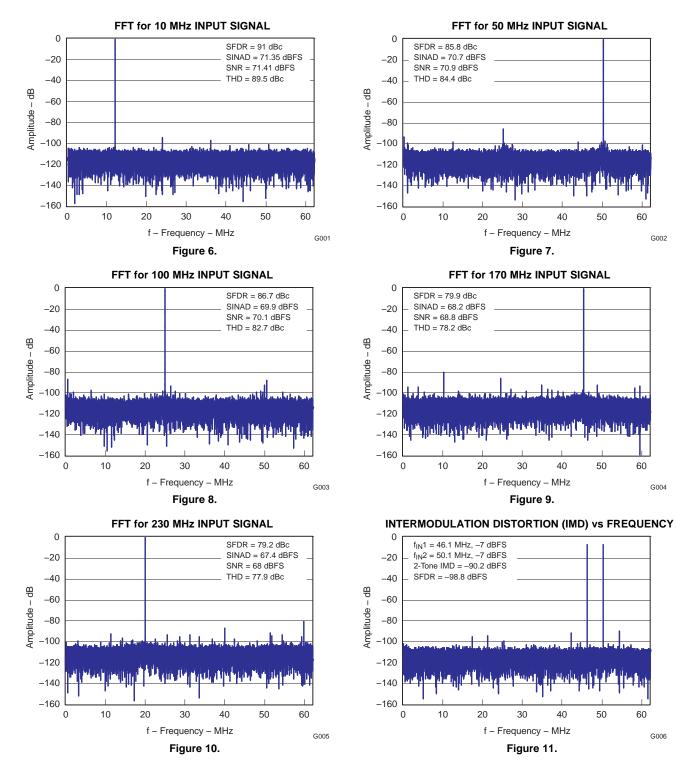


DS6425

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### **TYPICAL CHARACTERISTICS**

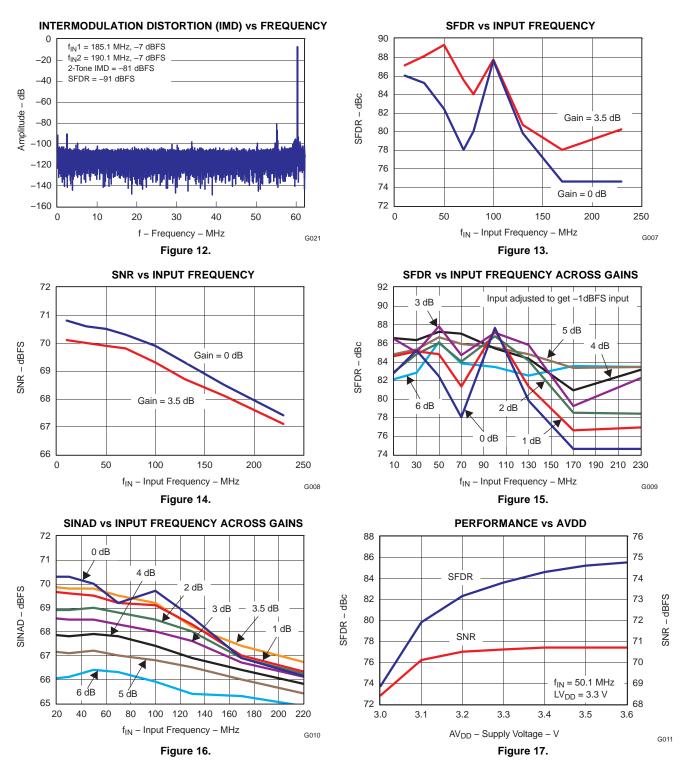
All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)



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**TYPICAL CHARACTERISTICS (continued)** 

All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)



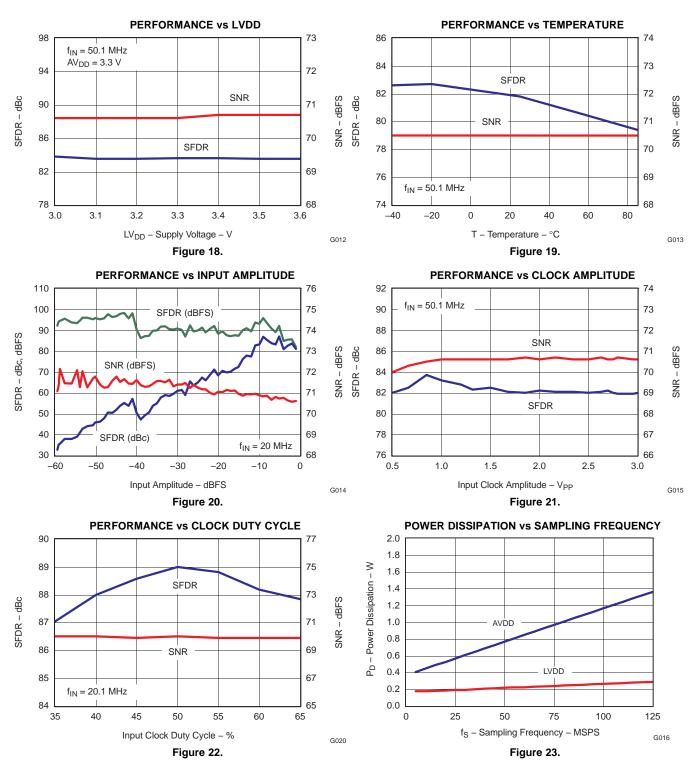
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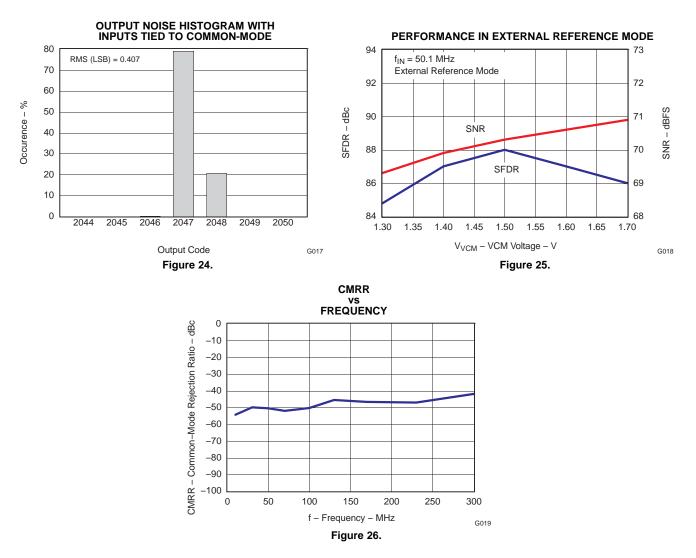
# **TYPICAL CHARACTERISTICS (continued)**

All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)



# **TYPICAL CHARACTERISTICS (continued)**

All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)





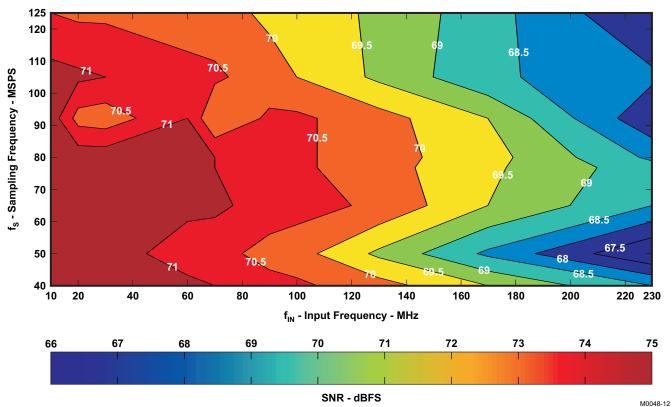
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## **TYPICAL CHARACTERISTICS (continued)**

All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)





## **TYPICAL CHARACTERISTICS (continued)**

All plots are at 25°C, AVDD = LVDD = 3.3 V, sampling frequency = 125 MSPS, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, 32K point FFT (unless otherwise noted)

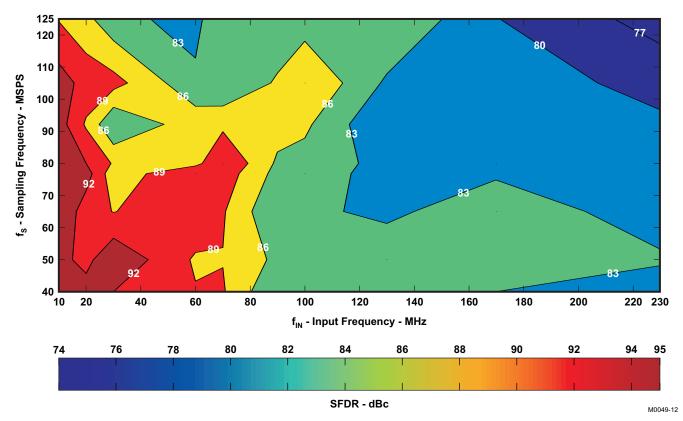


Figure 28. SFDR Contour

**FEXAS** 

INSTRUMENTS

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## **APPLICATION INFORMATION**

#### THEORY OF OPERATION

The ADS6425 is a quad channel, 12-bit, 125-MSPS, pipeline ADC, based on switched capacitor architecture in CMOS technology.

The conversion is initiated simultaneously by all the four channels at the rising edge of the external input clock. After the input signals are captured by the sample and hold circuit of each channel, the samples are sequentially converted by a series of low resolution stages. The stage outputs are combined in a digital correction logic block to form the final 12-bit word with a latency of 12 clock cycles. The 12-bit word of each channel is serialized and output as LVDS levels. In addition to the data streams, a bit clock and a frame clock are also output. The frame clock is aligned with the 12-bit word boundary.

#### ANALOG INPUT

The analog input consists of a switched-capacitor based differential sample and hold architecture, shown in Figure 29. This differential topology results in very good AC performance even for high input frequencies. The INP and INM pins have to be externally biased around a common-mode voltage of 1.5 V, available on VCM pin 13. For a full-scale differential input, each input pin INP, INM has to swing symmetrically between VCM + 0.5 V and VCM – 0.5 V, resulting in a 2-V<sub>pp</sub> differential input swing. The maximum swing is determined by the internal reference voltages REFP (2.0V nominal) and REFM (1.0 V, nominal). The sampling circuit has a 3 dB bandwidth that extends up to 500 MHz (Figure 30, shown by the transfer function from the analog input pins to the voltage across the sampling capacitors TF\_ADC).

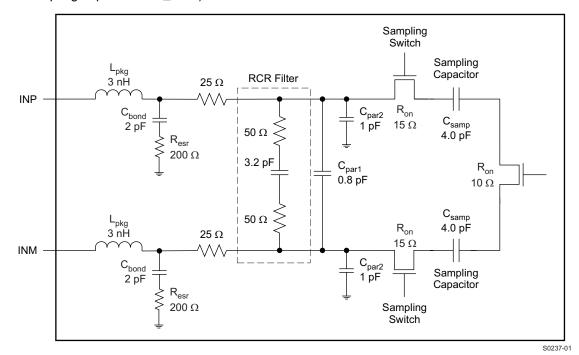


Figure 29. Input Sampling Circuit



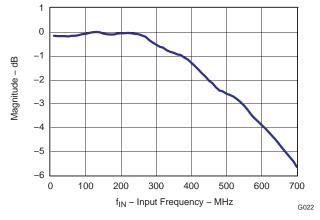


Figure 30. Analog Input Bandwidth (represented by magnitude of TF\_ADC, see Figure 31)

#### **Drive Circuit Requirements**

For optimum performance, the analog inputs must be driven differentially. This improves the common-mode noise immunity and even order harmonic rejection.

A 5- $\Omega$  resistor in series with each input pin is recommended to damp out ringing caused by the package parasitics. It is also necessary to present low impedance (< 50  $\Omega$ ) for the common mode switching currents. For example, this is achieved by using two resistors from each input terminated to the common mode voltage (VCM).

#### **Using RF-Transformer Based Drive Circuits**

Figure 31 shows a configuration using a single 1:1 turns ratio transformer (for example, WBC1-1) that can be used for low input frequencies up to 100MHz.

The single-ended signal is fed to the primary winding of the RF transformer. The transformer is terminated on the secondary side. Putting the termination on the secondary side helps to shield the kickbacks caused by the sampling circuit from the RF transformer's leakage inductances. The termination is accomplished by two resistors connected in series, with the center point connected to the 1.5 V common mode (VCM pin). The value of the termination resistors (connected to common mode) has to be low (< 100  $\Omega$ ) to provide a low-impedance path for the ADC common-mode switching current.

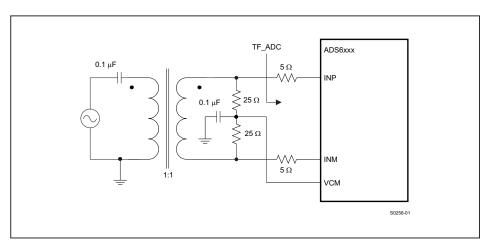


Figure 31. Single Transformer Drive Circuit

At high input frequencies, the mismatch in the transformer parasitic capacitance (between the windings) results



in degraded even-order harmonic performance. Connecting two identical RF transformers back-to-back helps minimize this mismatch, and good performance is obtained for high frequency input signals. Figure 32 shows an example using two transformers (Coilcraft WBC1-1). An additional termination resistor pair (enclosed within the shaded box in Figure 32) may be required between the two transformers to improve the balance between the P and M sides. The center point of this termination must be connected to ground.

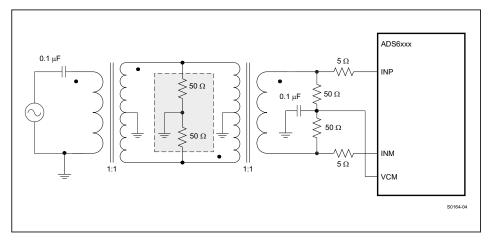


Figure 32. Two Transformer Drive Circuit

#### **INPUT COMMON MODE**

To ensure a low-noise common-mode reference, the VCM pin is filtered with a  $0.1-\mu$ F low-inductance capacitor connected to ground. The VCM pin is designed to directly drive the ADC inputs. The input stage of the ADC sinks a common-mode current in the order of 155  $\mu$ A at 125 MSPS (per input pin). Equation 1 describes the dependency of the common-mode current and the sampling frequency.

155 μAxFs 125 MSPS

(1)

This equation helps to design the output capability and impedance of the CM driving circuit accordingly.

#### REFERENCE

The ADS6425 has built-in internal references REFP and REFM, requiring no external components. Design schemes are used to linearize the converter load seen by the references; this and the on-chip integration of the requisite reference capacitors eliminates the need for external decoupling. The full-scale input range of the converter can be controlled in the external reference mode as explained below. The internal or external reference modes can be selected by programming the register bit **<REF>** (Table 11).

Instruments

Texas

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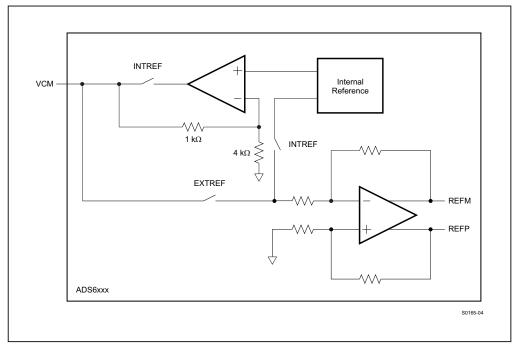


Figure 33. Reference Section

#### Internal Reference

When the device is in internal reference mode, the REFP and REFM voltages are generated internally. Common-mode voltage (1.5 V nominal) is output on VCM pin, which can be used to externally bias the analog input pins.

#### **External Reference**

When the device is in external reference mode, the VCM acts as a reference input pin. The voltage forced on the VCM pin is buffered and gained by 1.33 internally, generating the REFP and REFM voltages. The differential input voltage corresponding to full-scale is given by Equation 2.

Full-scale differential input  $pp = (Voltage forced on VCM) \times 1.33$ 

(2)

In this mode, the range of voltage applied on VCM pin should be 1.45 to 1.55V. The 1.5-V common-mode voltage to bias the input pins has to be generated externally.

#### COARSE GAIN AND PROGRAMMABLE FINE GAIN

The ADS6425 includes gain settings that can be used to get improved SFDR performance (compared to 0 dB gain mode). The gain settings are 3.5 dB coarse gain and programmable fine gain from 0 dB to 6 dB. For each gain setting, the analog input full-scale range scales proportionally, as shown in Table 19.

The coarse gain is a fixed setting of 3.5 dB and is designed to improve SFDR with little degradation in SNR (as seen in Figure 13 and Figure 14). The fine gain is programmable in 1 dB steps from 0 to 6 dB. With the fine gain also, SFDR improvement is achieved, but at the expense of SNR (there will be about 1dB SNR degradation for every 1dB of fine gain).

So, the fine gain can be used to trade-off between SFDR and SNR. The coarse gain makes it possible to get best SFDR but without losing SNR significantly. At high input frequencies, the gains are especially useful as the SFDR improvement is significant with marginal degradation in SINAD.

The gains can be programmed using the register bits **<COARSE GAIN>** (Table 16) and **<FINE GAIN>** (Table 15). Note that the default gain after reset is 0 dB.

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	Table 19. I uli-Scale Kaliye Across Gallis										
GAIN, dB	TYPE	FULL-SCALE, V <sub>pp</sub>									
0	Default (after reset)	2									
3.5	Coarse setting (fixed)	1.34									
1		1.78									
2		1.59									
3	Fine setting	1.42									
4	(programmable)	1.26									
5		1.12									
6		1.00									

Table 19. Full-Scale Range Across Gains

## **CLOCK INPUT**

The ADS6425 clock inputs can be driven differentially (SINE, LVPECL or LVDS) or single-ended (LVCMOS), with little or no difference in performance between them. The common-mode voltage of the clock inputs is set to VCM using internal 5-k $\Omega$  resistors as shown in Figure 34. This allows using transformer-coupled drive circuits for sine wave clock or ac-coupling for LVPECL, LVDS clock sources (see Figure 35 and Figure 37).

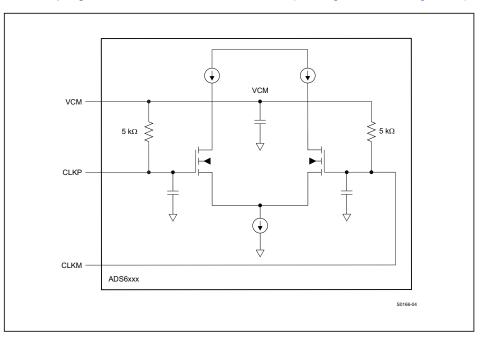


Figure 34. Internal Clock Buffer

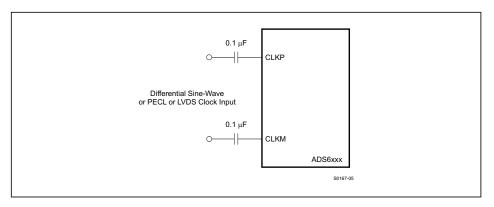


Figure 35. Differential Clock Driving Circuit

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Figure 36 shows a typical scheme using PECL clock drive from a CDCM7005 clock driver. SNR performance with this scheme is comparable with that of a low jitter sine wave clock source.

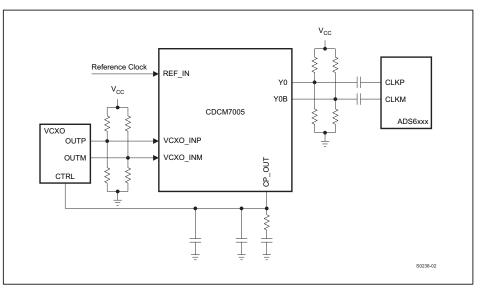


Figure 36. PECL Clock Drive Using CDCM7005

Single-ended CMOS clock can be ac-coupled to the CLKP input, with CLKM (pin) connected to ground with a 0.1- $\mu$ F capacitor, as shown in Figure 37.

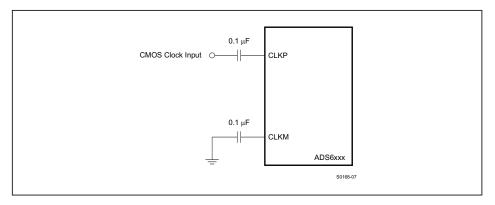


Figure 37. Single-Ended Clock Driving Circuit

For best performance, the clock inputs have to be driven differentially, reducing susceptibility to common-mode noise. For high input frequency sampling, it is recommended to use a clock source with very low jitter. Bandpass filtering of the clock source can help reduce the effect of jitter. There is no change in performance with a non-50% duty cycle clock input.

## CLOCK BUFFER GAIN

When using a sinusoidal clock input, the noise contributed by clock jitter improves as the clock amplitude is increased. Hence, it is recommended to use large clock amplitude. As shown by Figure 21, use clock amplitude greater than 1V pp to avoid performance degradation.

In addition, the clock buffer has programmable gain to amplify the input clock to support very low clock amplitude. The gain can be set by programming the register bits **<CLKIN GAIN>** (Table 12) and increases monotonically from Gain 0 to Gain 5 settings. Table 20 shows the minimum clock amplitude supported for each gain setting.



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Table 20. W	Table 20. Minimum Clock Amplitude Across Gains						
CLOCK BUFFER GAIN	MINIMUM CLOCK AMPLITUDE SUPPORTED, mV (pp differential)						
Gain 0 (minimum gain)	800						
Gain 1 (default gain)	400						
Gain 2	300						
Gain 3	200						
Gain 4	150						
Gain 5 (highest gain)	100						

## Table 20 Minimum Clock Amplitude Across Gains

### POWER DOWN MODES

The ADS6425 has three power down modes – global power down, channel standby and input clock stop.

#### **Global Power Down**

This is a global power down mode in which almost the entire chip is powered down, including the four ADCs, internal references, PLL and LVDS buffers. As a result, the total power dissipation falls to about 77 mW typical (with input clock running). This mode can be initiated by setting the register bit **<PDN GLOBAL>** (Table 11). The output data and clock buffers are in high impedance state.

The wake-up time from this mode to data becoming valid in normal mode is 100  $\mu$ s.

#### **Channel Standby**

In this mode, only the ADC of each channel is powered down and this helps to get very fast wake-up times. Each of the four ADCs can be powered down independently using the register bits **<PDN CH>** (Table 11). The analog power dissipation varies from 1115 mW (only one channel in standby) to 245 mW (all four channels in standby). The output LVDS buffers remain powered up.

The wake-up time from this mode to data becoming valid in normal mode is 200 clock cycles.

### **Input Clock Stop**

The converter enters this mode:

- If the input clock frequency falls below 1 MSPS or
- If the input clock amplitude is less than 400 mV (pp, differential with default clock buffer gain setting) at any sampling frequency.

All ADCs and LVDS buffers are powered down and the power dissipation is about 235 mW. The wake-up time from this mode to data becoming valid in normal mode is 100 µs.

POWER DOWN MODE	AVDD POWER (mW)	LVDD POWER (mW)	WAKE UP TIME	
In power-up	1360	297	-	
Global power down	65	12	100 μs	
1 Channel in standby	1115	297	200 Clocks	
2 Channels in standby	825	297	200 Clocks	
3 Channels in standby	532	297	200 Clocks	
4 Channels in standby	245	297	200 Clocks	
Input clock stop	200	35	100 μs	

Table 21	Power	Down	Modes	Summary
----------	-------	------	-------	---------

### POWER SUPPLY SEQUENCING

During power-up, the AVDD and LVDD supplies can come up in any sequence. The two supplies are separated inside the device. Externally, they can be driven from separate supplies or from a single supply.

## TEXAS INSTRUMENTS

### DIGITAL OUTPUT INTERFACE

The ADS6425 offers several flexible output options making it easy to interface to an ASIC or an FPGA. These options can be easily programmed using either parallel pins and/or the serial interface.

The output interface options are:

- 1-wire, 1× frame clock, 12× and 14× serialization with DDR bit clock
- 2-wire, 1x frame clock, 12x serialization, with DDR and SDR bit clock, byte wise/bit wise/word wise
- 2-wire, 1× word clock, 14× serialization, with SDR bit clock, byte wise/bit wise/word wise
- 2-wire, (0.5 x) frame clock, 14× serialization, with DDR bit clock, byte wise/bit wise/word wise.

The maximum sampling frequency, bit clock frequency and output data rate will vary depending on the interface options selected (refer to Table 12).

Table 22. Maximum Recommended Sampling Frequency for Different Output
---

INTERFACE OPTIONS		MAXIMUM RECOMMENDED SAMPLING FREQUENCY, MSPS	BIT CLOCK FREQUENCY, MHZ	FRAME CLOCK FREQUENCY, MHZ	SERIAL DATA RATE, Mbps	
1 \\/iro	1-Wire DDR Bit clock	12× Serialization	65	390	65	780
I-WIIE		14× Serialization	65	455	65	910
2-Wire	DDR Bit	12× Serialization	125	375	125	750
2-wile	clock	14× Serialization	125	437.5	62.5	875
2-Wire	SDR Bit	12× Serialization	65	390	65	390
2-00116	clock	14× Serialization	65	455	65	455

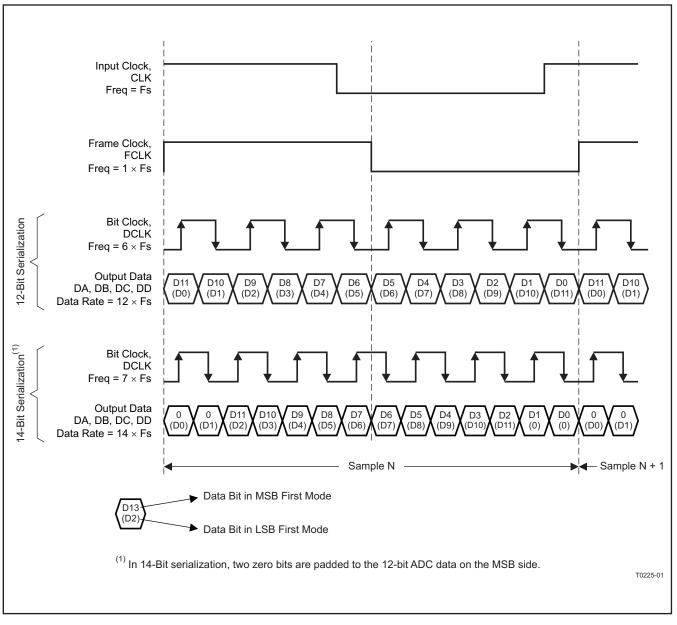
Each interface option is described in detail below.

### 1-WIRE INTERFACE - 12× AND 14× SERIALIZATION WITH DDR BIT CLOCK

Here the device outputs the data of each ADC serially on a single LVDS pair (1-wire). The data is available at the rising and falling edges of the bit clock (DDR bit clock). The ADC outputs a new word at the rising edge of every frame clock, starting with the MSB. Optionally, it can also be programmed to output the LSB first. The data rate is 12 × Sample frequency (12× serialization) and 14× Sample frequency (14× serialization).



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### Figure 38. 1-Wire Interface

### 2-WIRE INTERFACE - 12× SERIALIZATION WITH DDR/SDR BIT CLOCK

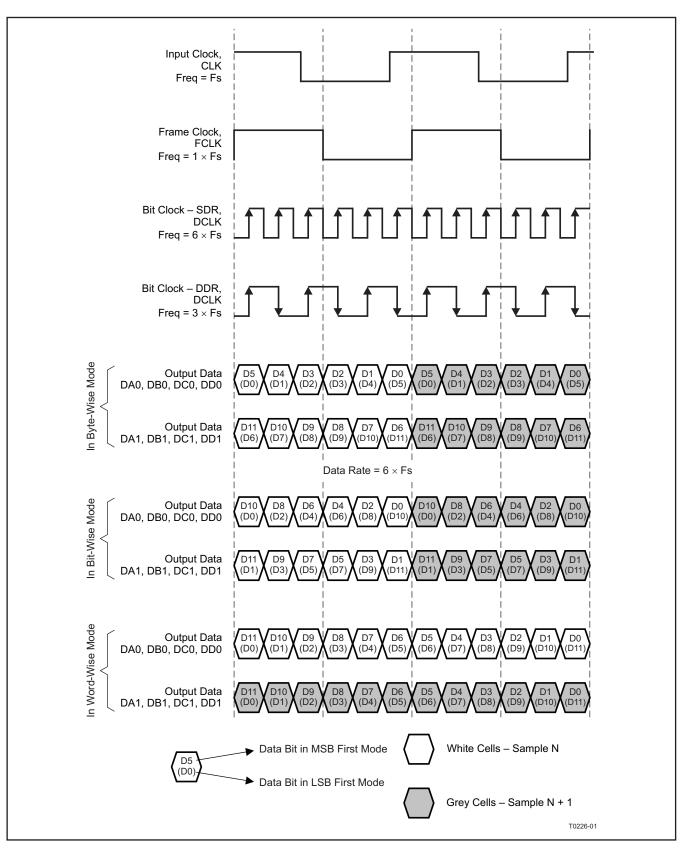
The 2-wire interface is recommended for sampling frequencies above 65 MSPS. The device outputs the data of each ADC serially on two LVDS pairs (2-wire). The data rate is 6 × Sample frequency since 6 bits are sent on each wire every clock cycle. The data is available along with DDR bit clock or optionally with SDR bit clock. Each ADC sample is sent over the 2 wires as byte-wise or bit-wise or word-wise.

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A. In the byte-wise and bit-wise modes, the frame clock frequency is 1 x Fs. In the word-wise mode, the frame clock frequency is 0.5 x Fs.



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#### Figure 39. 2-Wire Interface 12× Serialization

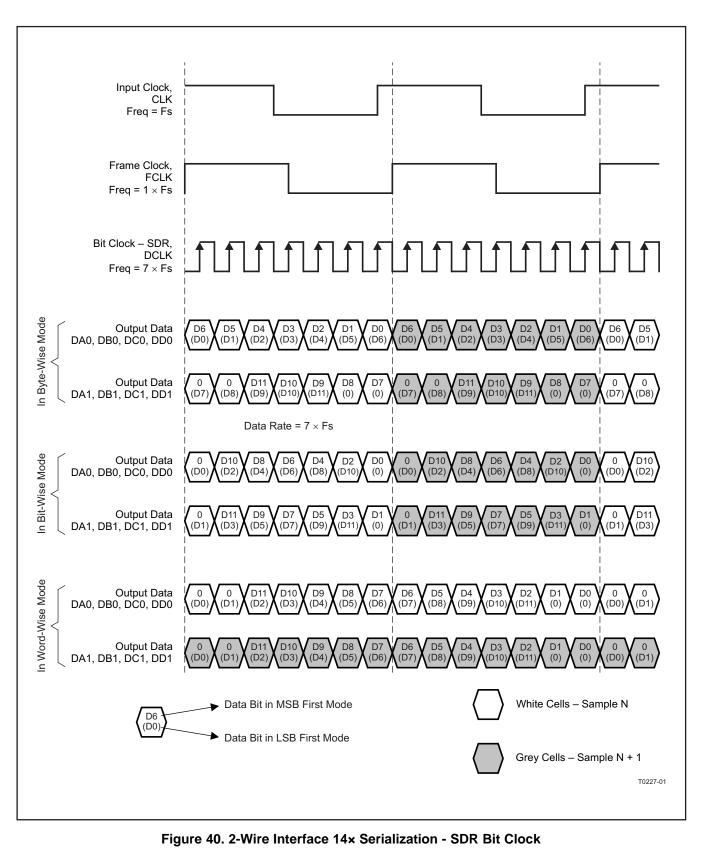
#### 2-WIRE INTERFACE - 14× SERIALIZATION

In 14x serialization, two zero bits are padded to the 12-bit ADC data on the MSB side and the combined 14-bit data is serialized and output over two LVDS pairs. A frame clock at 1x sample frequency is also available with an SDR bit clock. With DDR bit clock option, the frame clock frequency is 0.5x sample frequency. The output data rate will be 7 x Sample frequency as 7 data bits are output every clock cycle on each wire. Each ADC sample is sent over the 2 wires as byte-wise or bit-wise or word-wise.

Using the 14x serialization makes it possible to upgrade to a 14-bit ADC in the 64xx family in the future seamlessly, without requiring any modification to the receiver capture logic design.

## ADS6425

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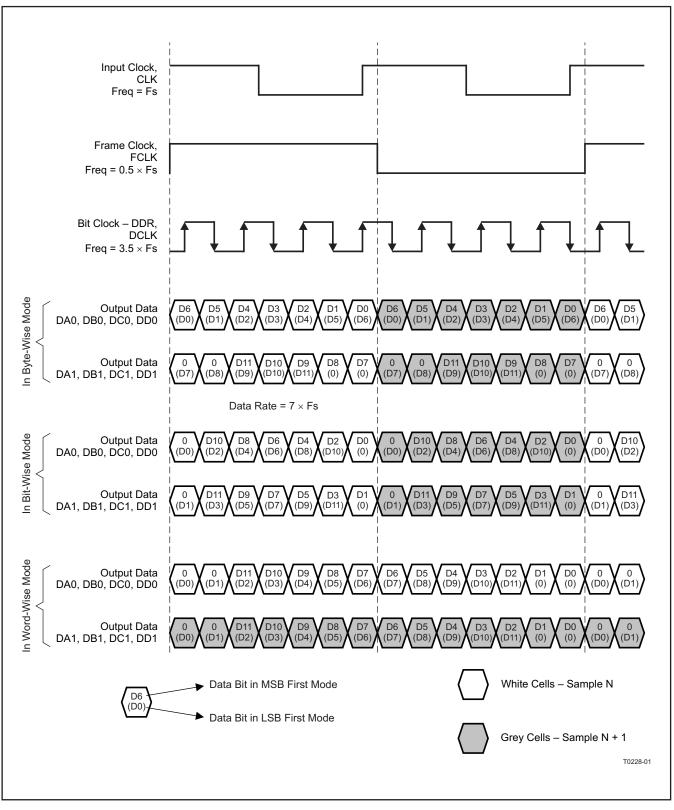


Figure 41. 2-Wire Interface 14× Serialization - DDR Bit Clock



### OUTPUT BIT ORDER

In the 2-wire interface, three types of bit order are supported - byte-wise, bit-wise and word-wise.

**Byte-wise:** Each 12-bit sample is split across the 2 wires. Wires DA0, DB0, DC0 and DD0 carry the 6 LSB bits D5-D0 and wires DA1, DB1, DC1 and DD1 carry the 6 MSB bits.

**Bit-wise:** Each 12-bit sample is split across the 2 wires. Wires DA0, DB0, DC0 and DD0 carry the 6 even bits (D0,D2,D4..) and wires DA1, DB1, DC1 and DD1 carry the 6 odd bits (D1,D3,D5...).

**Word-wise:** In this case, all 12-bits of a sample are sent over a single wire. Successive samples are sent over the 2 wires. For example sample N is sent on wires DA0, DB0, DC0 and DD0, while sample N+1 is sent over wires DA1, DB1, DC1 and DD1. The frame clock frequency is 0.5x sampling frequency, with the rising edge aligned with the start of each word.

### MSB/LSB FIRST

By default after reset, the 12-bit ADC data is output serially with the MSB first (D11,D10,...D1,D0). The data can be output LSB first also by programming the register bit **<MSB\_LSB\_First>**. In the 2-wire mode, the bit order in each wire is flipped in the LSB first mode.

### **OUTPUT DATA FORMATS**

Two output data formats are supported – 2s complement (default after reset) and offset binary. They can be selected using the serial interface register bit **<DF>**. In the event of an input voltage overdrive, the digital outputs go to the appropriate full-scale level. For a positive overdrive, the output code is 0xFFF in offset binary output format, and 0x7FF in 2s complement output format. For a negative input overdrive, the output code is 0x000 in offset binary output format and 0x800 in 2s complement output format.

### LVDS CURRENT CONTROL

The default LVDS buffer current is 3.5 mA. With an external 100- $\Omega$  termination resistance, this develops ±350-mV logic levels at the receiver. The LVDS buffer currents can also be programmed to 2.5 mA, 3.0 mA and 4.5 mA using the register bits **<LVDS CURR>**. In addition, there exists a current double mode, where the LVDS nominal current is doubled (register bits **<CURR DOUBLE>**, Table 17).

### LVDS INTERNAL TERMINATION

An internal termination option is available (using the serial interface), by which the LVDS buffers are differentially terminated inside the device. Five termination resistances are available – 166, 200, 250, 333, and 500  $\Omega$  (nominal with ±20% variation). Any combination of these terminations can be programmed; the effective termination will be the parallel combination of the selected resistances. The terminations can be programmed separately for the clock and data buffers (bits **<TERM CLK>** and **<TERM DATA>**, Table 18).

The internal termination helps to absorb any reflections from the receiver end, improving the signal integrity. This makes it possible to drive up to 10 pF of load capacitance, compared to only 5 pF without the internal termination. Figure 42 and Figure 43 show the eye diagram with 5 pF and 10 pF load capacitors (connected from each output pin to ground).

With  $100-\Omega$  internal and  $100-\Omega$  external termination, the voltage swing at the receiver end will be halved (compared to no internal termination). The voltage swing can be restored by using the LVDS current double mode (bits **<CURR DOUBLE>**, Table 17).

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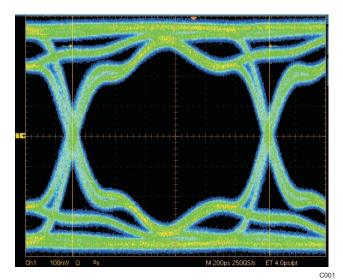


Figure 42. LVDS Data Eye Diagram with 5-pF Load Capacitance (No Internal Termination)

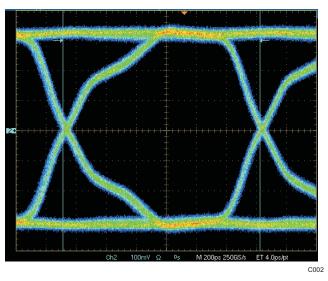


Figure 43. LVDS Data Eye Diagram with 10-pF Load Capacitance (100 Ω Internal Termination)

### **CAPTURE TEST PATTERNS**

The ADS6425 outputs the bit clock (DCLK), positioned nearly at the center of the data transitions. It is recommended to route the bit clock, frame clock and output data lines with minimum relative skew on the PCB. This ensures sufficient setup/hold times for a reliable capture by the receiver.

The DESKEW is a 1010... or 0101... pattern output on the serial data lines that can be used to verify if the receiver capture clock edge is positioned correctly. This may be useful in case there is some skew between DCLK and serial data inside the receiver. Once deserialized, it is required to ensure that the parallel data is aligned to the frame boundary. The SYNC test pattern can be used for this. For example, in the 1-wire interface, the SYNC pattern is 6 '1's followed by 6 '0's (from MSB to LSB). This information can be used by the receiver logic to shift the deserialized data till it matches the SYNC pattern.

In addition to DESKEW and SYNC, the ADS6425 includes other test patterns to verify correctness of the capture by the receiver such as all zeros, all ones and toggle. These patterns are output on all four channel data lines simultaneously. Some patterns like custom and sync are affected by the type of interface selected, serialization and bit order.

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### Table 23. Test Patterns

PATTERN	DESCRIPTION
All zeros	Outputs logic low.
All ones	Outputs logic high.
Toggle	Outputs toggle pattern - <d11-d0> alternates between 101010101010 and 010101010101 every clock cycle.</d11-d0>
Custom	Outputs a 12-bit custom pattern. The 12-bit custom pattern can be specified into two serial interface registers. In the 2-wire interface, each code is sent over the 2 wires depending on the serialization and bit order.
Sync	Outputs a sync pattern.
Deskew	Outputs deskew pattern. Either <d11-d0> = 101010101010 OR <d11-d0> = 010101010101 every clock cycle.</d11-d0></d11-d0>

#### Table 24. SYNC Pattern

INTERFACE OPTION	SERIALIZATION	SYNC PATTERN ON EACH WIRE
1-Wire	12 X	MSB-111111000000-LSB
I-WIIE	14 X	MSB-1111110000000-LSB
2-Wire	12 X	MSB-111000-LSB
2-wire	14 X	MSB-1111000-LSB



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### **OUTPUT TIMINGS AT LOWER SAMPLING FREQUENCIES**

Setup, hold and other timing parameters are specified across sampling frequencies and for each type of output interface in the tables below.

Table 26 to Table 29: Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, AVDD = LVDD = 3.3 V,  $C_L = 5 \text{ pF}$ ,  $I_O = 3.5 \text{ mA}$ ,  $R_L = 100 \Omega$ , no internal termination, unless otherwise noted.

Timing parameters are ensured by design and characterization and not tested in production.

Ts = 1/Sampling frequency = 1/Fs

#### Table 25. Clock Propagation Delay and Serializer Latency for Different Interface Options

INTERFACE	SERIALIZATION	CLOCK PROPAGATION DELAY, tpd_cik	SERIALIZER LATENCY <sup>(1)</sup> clock cycles	
1-Wire with DDR bit clock	12X	$t_{pd\_clk} = 0.5xT_s + t_{delay}$	0	
I-WITE WITH DDR DIL CIOCK	14X	$t_{pd\_clk} = 0.428 x T_s + t_{delay}$	0	
2-Wire with DDR bit clock	107	$t_{pd\_clk} = t_{delay}$	1	
2-Wire with SDR bit clock	12X	$t_{pd\_clk} = 0.5xT_s + t_{delay}$	0	
2-Wire with DDR bit clock		t _ 0.957vT + t	$\frac{2}{(\text{when } t_{\text{pd}\_\text{clk}} \ge T_s)}$	
2-Wire with DDR bit clock	14X	$t_{pd\_clk} = 0.857 x T_s + t_{delay}$	1 (when t <sub>pd_clk</sub> < T <sub>s</sub> )	
2-Wire with SDR bit clock		$t_{pd\_clk} = 0.428 x T_s + t_{delay}$	0	

(1) Note that the total latency = ADC latency + serializer latency. The ADC latency is 12 clocks.

SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns		DATA HOLD TIME, t <sub>h</sub> ns			t <sub>delay</sub> ns			
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX
	65	0.4	0.6		0.5	0.7		F <sub>s</sub> ≥40 MSPS		
12×	40	0.8	1.0		0.9	1.1		3	4	5
12×	20	1.6	2.0		1.8	2.2		F <sub>s</sub> < 40 MSPS		
	10	3.5	4.0		3.5	4.2		3	4.5	6
	65	0.3	0.5		0.4	0.6			F <sub>s</sub> ≥ 40 MSPS	
4.4.	40	0.65	0.85		0.7	0.9		3	4	5
14×	20	1.3	1.65		1.6	1.9			F <sub>s</sub> < 40 MSPS	·
	10	3.2	3.5		3.2	3.6		3	4.5	6

#### Table 26. Timings for 1-Wire Interface

#### Table 27. Timings for 2-Wire Interface, DDR Bit Clock

				0						
SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns		DATA HOLD TIME, t <sub>h</sub> ns			t <sub>delay</sub> ns			
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX
	105	0.55	0.75		0.6	0.8		F <sub>s</sub> ≥45 MSPS		
	92	0.65	0.85		0.7	0.9			4.4	5.4
12×	80	0.8	1.0		0.8	1.05		3.4	4.4	5.4
	65	0.9	1.2		1.0	1.3		F <sub>s</sub> < 45 MSPS		
	40	1.7	2.0		1.1	2.1		3.7	5.2	6.7
	105	0.45	0.65		0.5	0.7			F <sub>s</sub> ≥ 45 MSPS	
	92	0.55	0.75		0.6	0.8		0		_
14×	80	0.65	0.85		0.7	0.9		3	4	5
	65	0.8	1.1		0.8	1.1		F <sub>s</sub> < 45 MSPS		
	40	1.4	1.7		1.5	1.9		3	4.5	6



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SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns		DATA HOLD TIME, t <sub>h</sub> ns			t <sub>delay</sub> ns			
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX
	65	1.0	1.2		1.1	1.3		F <sub>s</sub> ≥40 MSPS		
12×	40	1.8	2.0		1.9	2.1		3.4	4.4	5.4
	20	3.9	4.1		3.8	4.1		F <sub>s</sub> < 40 MSPS		
	10	8.2	8.4		7.8	8.2		3.7	5.2	6.7
	65	0.8	1.0		1.0	1.2		F <sub>s</sub> ≥ 40 MSPS		
4.4.	40	1.5	1.7		1.6	1.8		3.4	4.4	5.4
14×	20	3.4	3.6		3.3	3.5		F <sub>s</sub> < 40 MSPS		1
	10	6.9	7.2		6.6	6.9		3.7	5.2	6.7

### Table 28. Timings for 2-Wire Interface, SDR Bit Clock

## Table 29. Output Jitter (applies to all interface options)

SAMPLING FREQUENCY	BIT CLC	OCK JITTER, CYCLE ps, peak-peak	-CYCLE	FRAME CLOCK JITTER, CYCLE-CYCLE ps, peak-peak			
WISF 5	MIN	TYP	MAX	MIN	ТҮР	MAX	
≥ 65		350			75		



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### **DEFINITION OF SPECIFICATIONS**

**Analog Bandwidth** – The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

**Aperture Delay** – The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

Aperture Uncertainty (Jitter) – The sample-to-sample variation in aperture delay.

**Clock Pulse Width/Duty Cycle** – The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.

**Maximum Conversion Rate** – The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

Minimum Conversion Rate – The minimum sampling rate at which the ADC functions.

**Differential Nonlinearity (DNL)** – An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

**Integral Nonlinearity (INL)** – The INL is the deviation of the ADC's transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.

**Gain Error** – The gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range.

**Offset Error** – The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV.

**Temperature Drift** – The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from  $T_{MIN}$  to  $T_{MAX}$ . It is calculated by dividing the maximum deviation of the parameter across the  $T_{MIN}$  to  $T_{MAX}$  range by the difference  $T_{MAX}$ – $T_{MIN}$ .

**Signal-to-Noise Ratio** – SNR is the ratio of the power of the fundamental (PS) to the noise floor power (PN), excluding the power at DC and the first nine harmonics.

$$SNR = 10Log10 \frac{P_S}{P_N}$$

(3)

(4)

(6)

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

**Signal-to-Noise and Distortion (SINAD)** – SINAD is the ratio of the power of the fundamental ( $P_S$ ) to the power of all the other spectral components including noise ( $P_N$ ) and distortion ( $P_D$ ), but excluding dc.

$$SINAD = 10Log10 \frac{P_S}{PN + PD}$$

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

Effective Number of Bits (ENOB) – The ENOB is a measure of a converter's performance as compared to the theoretical limit based on quantization noise.

$$\mathsf{ENOB} = \frac{\mathsf{SINAD} - 1.76}{6.02} \tag{5}$$

**Total Harmonic Distortion (THD)** – THD is the ratio of the power of the fundamental ( $P_s$ ) to the power of the first nine harmonics (PD).

$$THD = 10Log10 \frac{P_{S}}{PD}$$

THD is typically given in units of dBc (dB to carrier).



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**Spurious-Free Dynamic Range (SFDR)** – The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).

**Two-Tone Intermodulation Distortion** – IMD3 is the ratio of the power of the fundamental (at frequencies f1 and f2) to the power of the worst spectral component at either frequency 2f1–f2 or 2f2–f1. IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

**DC Power Supply Rejection Ratio (DC PSRR)** – The DC PSSR is the ratio of the change in offset error to a change in analog supply voltage. The DC PSRR is typically given in units of mV/V.

**AC Power Supply Rejection Ratio (AC PSRR)** – AC PSRR is the measure of rejection of variations in the supply voltage by the ADC. If  $\Delta$ Vsup is the change in supply voltage and  $\Delta$ Vout is the resultant change of the ADC output code (referred to the input), then

$$PSRR = 20Log10 \frac{\Delta Vout}{\Delta Vsup}, \text{ expressed in dBc}$$

(7)

**Voltage Overload Recovery** – The number of clock cycles taken to recover to less than 1% error for a 6 dB overload on the analog inputs. A 6 dBFS sine wave input at Nyquist frequency is used as the test stimulus.

**Common Mode Rejection Ratio (CMRR)** – CMRR is the measure of rejection of variations in the analog input common-mode by the ADC. If  $\Delta$ Vcm\_in is the change in the common-mode voltage of the input pins and  $\Delta$ Vout is the resultant change of the ADC output code (referred to the input), then

$$CMRR = 20Log10 \frac{\Delta Vout}{\Delta V cm_in}$$
, expressed in dBc

(8)

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<ul> <li>Added Frame setup time to timing specifications</li></ul>	7
Added Frame hold time to timing specifications	7
Changed Figure 2	8
Added (with 10% tolerance resistors) to USING PARALLEL INTERFACE CONTROL ONLY section	
Changed Figure 3	10
Added voltage values to Table 6	11
<ul> <li>Added voltage values to Table 7</li> <li>Added voltage values to Table 9</li> </ul>	11
Added voltage values to Table 9	12
Added note to Table 10	15
Added 32K point FFT to typical characteristics conditions	25
Added 32K point FFT to typical characteristics conditions	
Added 32K point FFT to typical characteristics conditions	27
Added 32K point FFT to typical characteristics conditions	28
Added 32K point FFT to typical characteristics conditions	29
Added 32K point FFT to typical characteristics conditions	30
Changed Gain 4 to Gain 5 in CLOCK BUFFER GAIN section	
Added Gain 5 to Table 20.	37



6-Feb-2020

## PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
ADS6425IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6425	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE MATERIALS INFORMATION

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### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal	
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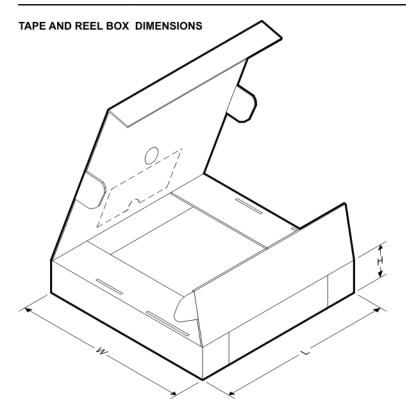
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS6425IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2

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# PACKAGE MATERIALS INFORMATION

15-Sep-2018



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS6425IRGCT	VQFN	RGC	64	250	213.0	191.0	55.0

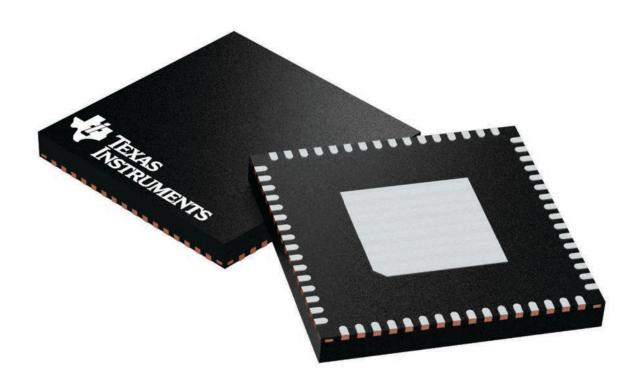
# **RGC 64**

9 x 9, 0.5 mm pitch

# **GENERIC PACKAGE VIEW**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

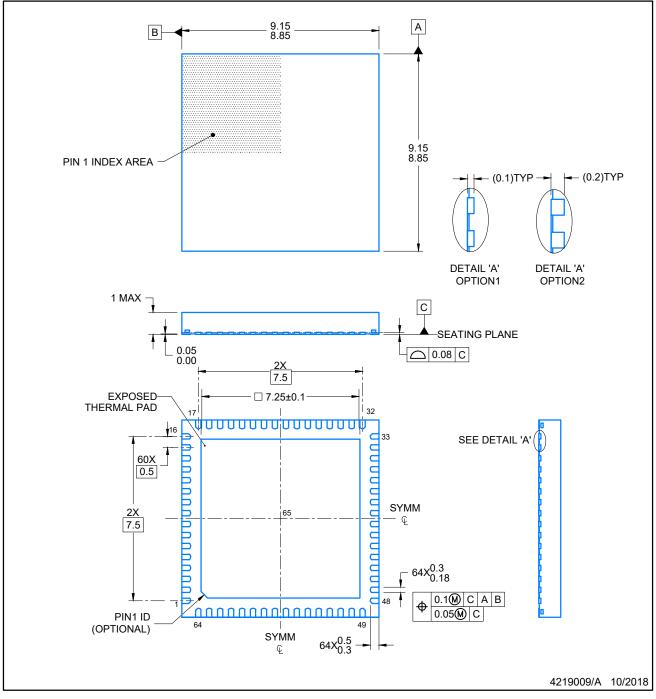


# **RGC0064A**

## **PACKAGE OUTLINE**

## VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

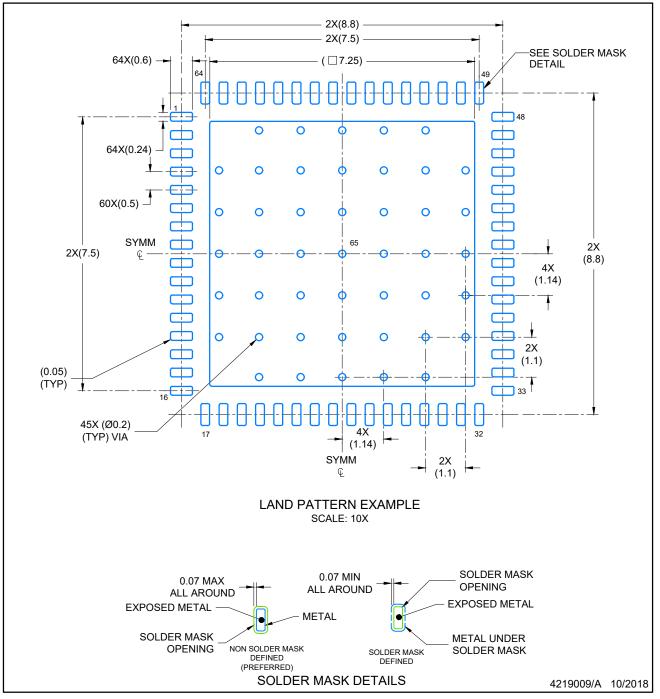


# **RGC0064A**

# **EXAMPLE BOARD LAYOUT**

## VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

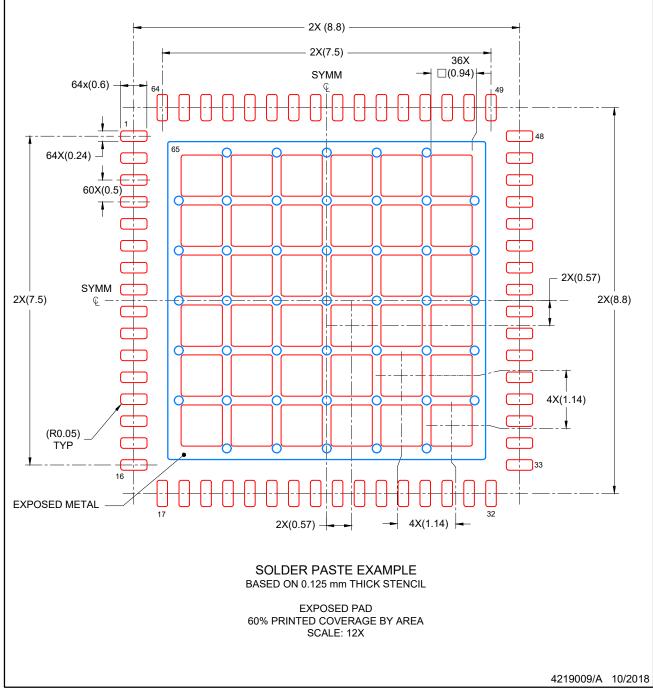


# **RGC0064A**

# **EXAMPLE STENCIL DESIGN**

## VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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